

SAT-BASED BOUNDED MODEL CHECKING

Formal Models SS19



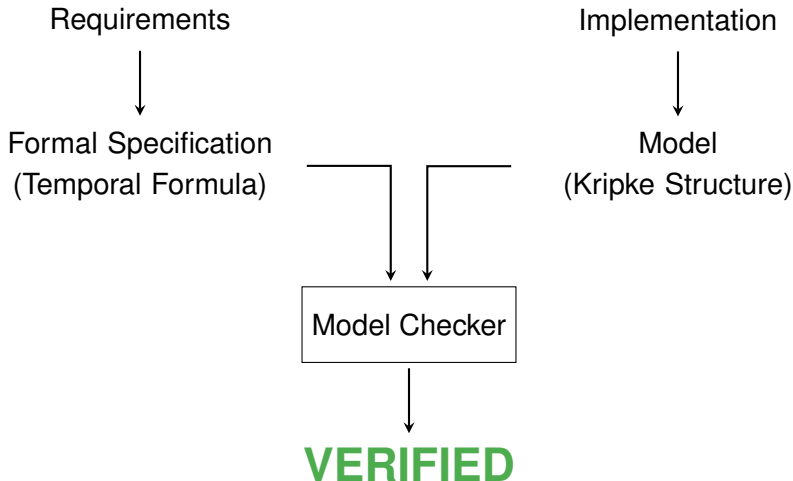
Martina Seidl

Institute for Formal Models and Verification

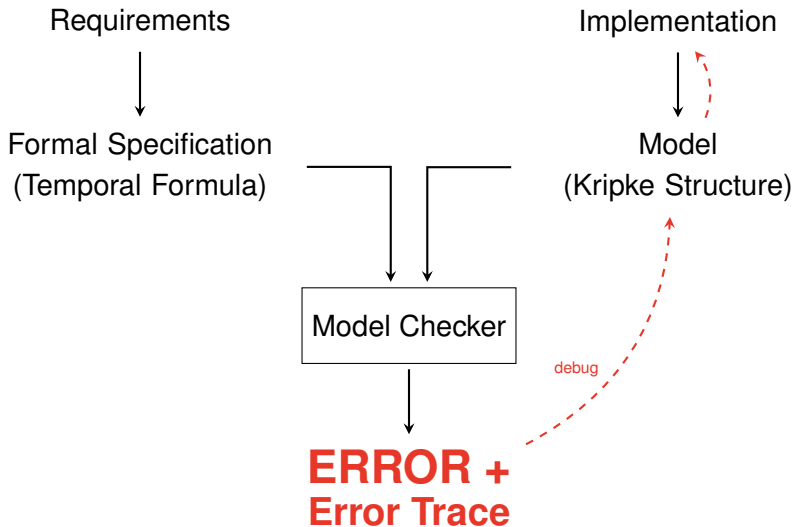


JOHANNES KEPLER
UNIVERSITY LINZ

Model Checking



Model Checking



Types of Model Checking

General question: Given a system K and a property p , does p hold for K (i.e., for all initial states of K) ?

- Explicit state model checking

- enumeration of the state space
- state explosion problem

- Symbolic model checking

- representation of model checking problem as logical formula (e.g., in propositional logic (SAT) or QBF)

Some Properties

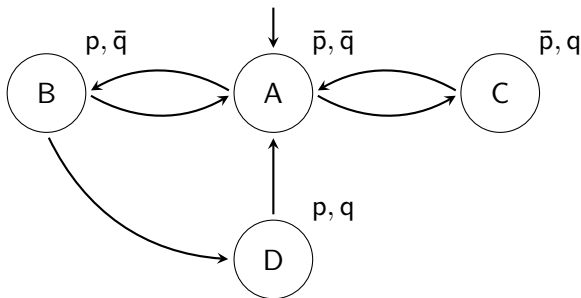
- **Reachability:** property p holds in one reachable state
- **Invariant:** property p holds in all reachable states
- **Safety:** some bad property p never holds
“something bad will never happen”
- **Liveness:** something good will eventually happen
- **Fairness:** under certain conditions, some property holds repeatedly

Example: Mutual Exclusion

Given two processes P and Q which share a resource R.

- If R is accessed by P, then property p is true.
- If R is accessed by Q, then property q is true.

The behavior of P and Q is modeled by this Kripke structure:



Limboole

- SAT-solver for formulas in non-CNF
- available at <http://fmv.jku.at/limboole/>
- input format in BNF:

$$\langle expr \rangle ::= \langle iff \rangle$$
$$\langle iff \rangle ::= \langle implies \rangle \mid \langle implies \rangle \text{ “<->” } \langle implies \rangle$$
$$\langle implies \rangle ::= \langle or \rangle \mid \langle or \rangle \text{ “->” } \langle or \rangle \mid \langle or \rangle \text{ “<-” } \langle or \rangle$$
$$\langle or \rangle ::= \langle and \rangle \mid \langle and \rangle \text{ “|” } \langle and \rangle$$
$$\langle and \rangle ::= \langle not \rangle \mid \langle not \rangle \text{ “&” } \langle not \rangle$$
$$\langle not \rangle ::= \langle basic \rangle \mid \text{ “!” } \langle not \rangle$$
$$\langle basic \rangle ::= \langle var \rangle \mid \text{ “(” } \langle expr \rangle \text{ “)”}$$

where 'var' is a string over letters, digits, and

- _ . [] \$ @

Symbolic Encoding of Kripke Structures

Given Kripke structure $K = (S, I, T, L)$ over $\mathcal{A} = \{a_1, \dots, a_n\}$.

1. Introduce sets $\mathcal{A}' = \{a'_1, \dots, a'_n\}$ and $\mathcal{A}'' = \{a''_1, \dots, a''_n\}$ for the **definition of one transition step \mathcal{T} over \mathcal{A}' and \mathcal{A}''** .
2. Associate each state $s \in S$ with two conjunctions of literals $current(s)$ and $next(s)$:¹
 - $current(s) := (l_1 \wedge \dots \wedge l_n)$
such that $l_i = a'_i$ if $a_i \in L(s)$ else $l_i = \bar{a}'_i$;
 - $next(s) := (k_1 \wedge \dots \wedge k_n)$
such that $k_i = a''_i$ if $a_i \in L(s)$ else $k_i = \bar{a}''_i$.
3. Define prop. formula \mathcal{T} over $\mathcal{A}', \mathcal{A}''$ such that $\forall s_i, s_j \in S$
 $(\mathcal{T} \wedge current(s_i) \wedge next(s_j))$ **is satisfiable iff** $(s_i, s_j) \in T$.

¹note: the mapping “state to conjunction” has to be bijective

Naive Encoding of Kripke Structures in SAT

Let $K = (S, I, T, L)$ be a Kripke structure over \mathcal{A} .

$\mathcal{T} := \top$

while $S \neq \emptyset$ **do**

 select $s \in S$

$S := S \setminus \{s\}$

$N := \perp$

for all $(s, t) \in T$ **do**

$N := N \vee next(t)$

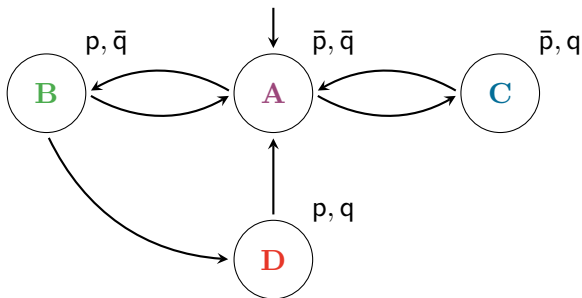
end for

$\mathcal{T} := \mathcal{T} \wedge (current(s) \rightarrow N)$

end while

return \mathcal{T}

Naive Encoding of Kripke Structures in SAT



$$\begin{aligned} \mathcal{T} &:= \top && \wedge \\ (\bar{p} \wedge \bar{q}) &\rightarrow (\perp \vee (\bar{p}' \wedge q') \vee (p' \wedge \bar{q}')) && \wedge \\ (p \wedge \bar{q}) &\rightarrow (\perp \vee (\bar{p}' \wedge \bar{q}') \vee (p' \wedge q')) && \wedge \\ (\bar{p} \wedge q) &\rightarrow (\perp \vee (\bar{p}' \wedge \bar{q}')) && \wedge \\ (p \wedge q) &\rightarrow (\perp \vee (\bar{p}' \wedge \bar{q}')) \end{aligned}$$

Naive Encoding of Kripke Structures in SAT

Encoding in Limboole syntax:

```
((!p & !q) -> (!p-next & q-next) | (p-next & !q-next)) &  
((p & !q) -> (!p-next & !q-next) | (p-next & q-next)) &  
((!p & q) -> (!p-next & !q-next)) &  
((p & q) -> (!p-next & !q-next))
```

```
> limboole limboole/mutual.boole -s  
% SATISFIABLE formula (satisfying assignment follows)
```

```
p = 0  
q = 0  
p-next = 0  
q-next = 1
```

Symbolic Encoding of Kripke Structures

Alternative encoding of transition function:

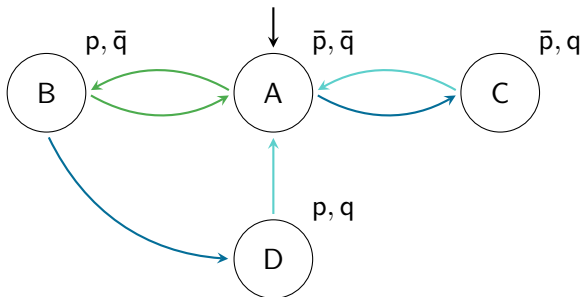
Successor states p', q' :

| p | q | p' | q' | or | p' | q' |
|-----|-----|------|------|----|------|------|
| 0 | 0 | 1 | 0 | | 0 | 1 |
| 0 | 1 | 0 | 0 | | 0 | 0 |
| 1 | 0 | 0 | 0 | | 1 | 1 |
| 1 | 1 | 0 | 0 | | 0 | 0 |

$$(p' \leftrightarrow (\bar{p} \wedge \bar{q}) \wedge q' \leftrightarrow 0)$$

\vee

$$(p' \leftrightarrow (p \wedge \bar{q}) \wedge q' \leftrightarrow \bar{q})$$



Example: One Step

Encoding in Limboole syntax:

```
((p-next <-> (!p & !q)) & (!q-next)) |  
((p-next <-> (p & !q)) & (q-next <-> !q))
```

```
> limboole -s mutual2.boole
```

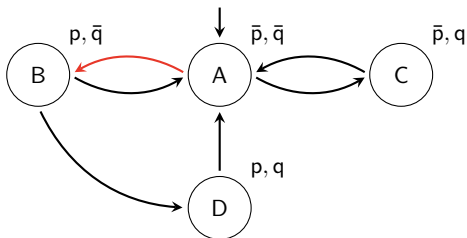
```
% SATISFIABLE formula (satisfying assignment follows)
```

```
p = 0
```

```
q = 0
```

```
p-next = 1
```

```
q-next = 0
```



Multiple Transition Steps

- \mathcal{T} over \mathcal{A}' and \mathcal{A}'' defines one transition step
 - we also write $\mathcal{T}(s_0, s_1)$ indicating that we can go from state s_0 to a state s_1
- \mathcal{T} over \mathcal{A}'' and \mathcal{A}''' defines one transition step
 - we also write $\mathcal{T}(s_1, s_2)$ indicating that we can go from state a s_1 to a state s_2
- $\mathcal{T}(s_0, s_1) \wedge \mathcal{T}(s_1, s_2)$ defines two transition steps from a state s_0 to a state s_1
- Example (previous slides):
$$(((p' \leftrightarrow (\bar{p} \wedge \bar{q})) \wedge (q' \leftrightarrow 0)) \vee ((p' \leftrightarrow (p \wedge \bar{q})) \wedge (q' \leftrightarrow \bar{q}))) \wedge$$
$$(((p'' \leftrightarrow (\bar{p}' \wedge \bar{q}')) \wedge (q'' \leftrightarrow 0)) \vee ((p'' \leftrightarrow (p' \wedge \bar{q}')) \wedge (q'' \leftrightarrow \bar{q}'))))$$

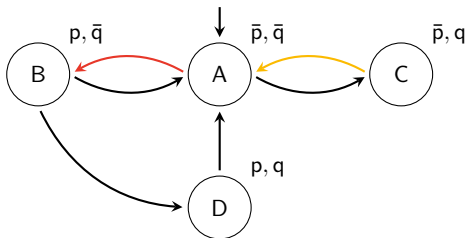
Example: Two Steps

Encoding in Limboole syntax:

```
((((p-next <-> (!p & !q)) & (!q-next)) |  
((p-next <-> (p & !q)) & (q-next <-> !q)))) &  
(((p-next2 <-> (!p-next & !q-next)) & (!q-next2)) |  
((p-next2 <-> (p-next & !q-next)) & (q-next2 <-> !q-next))))
```

```
> limboole -s mutual2-twoSteps.boole  
% SATISFIABLE formula (satisfying assignment follows)
```

```
p = 0  
q = 1  
p-next = 0  
q-next = 0  
p-next2 = 1  
q-next2 = 0
```



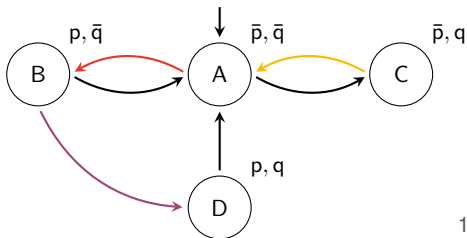
Example: Three Steps

Encoding in Limboole syntax:

```
((((p-next <-> (!p & !q)) & (!q-next)) |  
(p-next <-> (p & !q)) & (q-next <-> !q)))) &  
(((p-next2 <-> (!p-next & !q-next)) & (!q-next2)) |  
(p-next2 <-> (p-next & !q-next)) & (q-next2 <-> !q-next)))) &  
(((p-next3 <-> (!p-next2 & !q-next2)) & (!q-next3)) |  
(p-next3 <-> (p-next2 & !q-next2)) & (q-next3 <-> !q-next2))))
```

```
limboole -s mutual2-threeSteps.boole  
% SATISFIABLE formula (satisfying assignment follows)
```

```
p = 0  
q = 1  
p-next = 0  
q-next = 0  
p-next2 = 1  
q-next2 = 0  
p-next3 = 1  
q-next3 = 1
```



Bounded Model Checking (Safety)

- Given a Kripke structure K . Is there a path of length k to a **bad state** s , i.e., a certain property p is violated in s ?
- In other words: there is a path where Gp does not hold in K
- Observation: if Gp does not hold in K , there is a **finite counter-example**.
- Idea: consider paths of fixed length k
 - encode problem to propositional formula ϕ
 - pass problem to SAT solver
 - ϕ is true \Leftrightarrow model of ϕ is counter-example
 - if ϕ is false, then increase k

Bounded Model Checking (Safety)

A bounded model checking (BMC) problem for Kripke structure K and safety property Gp is encoded by

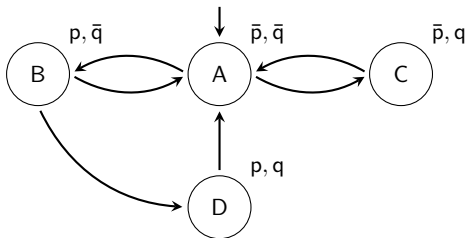
$$I(s_0) \wedge \mathcal{T}(s_0, s_1) \wedge \mathcal{T}(s_1, s_2) \wedge \dots \wedge \mathcal{T}(s_{k-1}, s_k) \wedge B(s_k)$$

where

- $I(s_0)$ is true $\Leftrightarrow s_0$ is an initial state
- \mathcal{T} is the transition function of K
- $B(s_k)$ is true $\Leftrightarrow s_k$ is a bad state, i.e., $\neg p$ holds in s_k

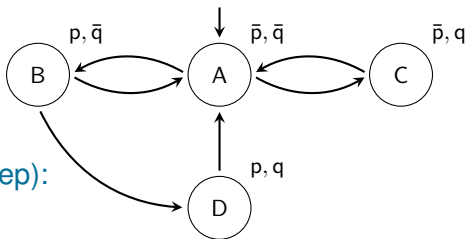
BMC Example

We want to know if $G(\bar{p} \vee \bar{q})$ holds for Kripke structure K :



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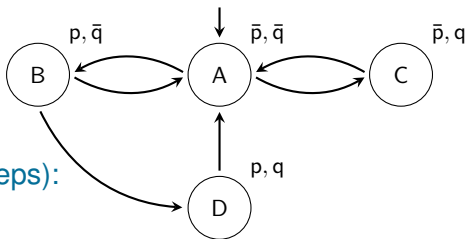


$k = 1$ (one step):

$$(\bar{p} \wedge \bar{q}) \wedge ((p' \leftrightarrow (\bar{p} \wedge \bar{q})) \wedge (q' \leftrightarrow 0)) \vee ((p' \leftrightarrow (p \wedge \bar{q})) \wedge (q' \leftrightarrow \bar{q})) \wedge (p' \wedge q')$$

BMC Example

We want to know if $G(\bar{p} \vee \bar{q})$ holds for Kripke structure K :



$k = 2$ (two steps):

$$\begin{aligned} & (\bar{p} \wedge \bar{q}) \wedge \\ & (((p' \leftrightarrow (\bar{p} \wedge \bar{q})) \wedge (q' \leftrightarrow 0)) \vee ((p' \leftrightarrow (p \wedge \bar{q})) \wedge (q' \leftrightarrow \bar{q}))) \wedge \\ & (((p'' \leftrightarrow (\bar{p}' \wedge \bar{q}')) \wedge (q'' \leftrightarrow 0)) \vee \\ & ((p'' \leftrightarrow (p' \wedge \bar{q}')) \wedge (q'' \leftrightarrow \bar{q}')))) \wedge \\ & (p'' \wedge q'') \end{aligned}$$

Compact BMC Encoding with QBF

A bounded model checking (BMC) problem for Kripke structure K and property Gp is encoded by

$$\exists s_0, s_1, \dots, s_k \forall x, x'. \quad (I(s_0) \wedge B(s_k) \wedge (\bigvee_{i=0}^{k-1} (x \leftrightarrow s_i \wedge x' \leftrightarrow s_{i+1}) \rightarrow \mathcal{T}(x, x'))))$$

where

- $I(s_0)$ is true $\Leftrightarrow s_0$ is an initial state
- \mathcal{T} is the transition relation of K
- $B(s_k)$ is true $\Leftrightarrow s_k$ is a bad state, i.e., p holds in s_k

Advantage: only one copy of transition relation!

Quantified Boolean Formulas (QBF)

- Extension of propositional logic
 - explicit quantifiers (\forall , \exists) over the Boolean variables
- Canonical PSPACE-complete problem
 - more succinct encoding than SAT (NP-complete)
- Many application domains: synthesis, AI, verification, ...

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closed QBF in prenex form

$$\exists x \exists y \forall u \exists z. (u \rightarrow z) \wedge (y \vee u \vee \neg z) \wedge (x \vee \neg u \vee \neg z) \wedge (x \leftrightarrow \neg y)$$

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prefix

matrix

QBF Syntax

■ QBFs in Prenex CNF (PCNF):

$$\exists x \exists y \forall u \exists z. \underbrace{(\underbrace{\downarrow \text{ literals}}_{\neg u \vee z}) \wedge (\underbrace{\text{clause}}_{y \vee u \vee \neg z}) \wedge (x \vee \neg u \vee \neg z)}_{\text{CNF}}$$

QBF Syntax

■ QBFs in Prenex CNF (PCNF):

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■ QBFs in Prenex DNF (PDNF):

$$\forall x \forall y \exists u \forall z. \underbrace{(u \wedge \neg z) \vee (\neg y \wedge \neg u \wedge z) \vee (\neg x \wedge u \wedge z)}_{\text{DNF}}$$

QBF Syntax

■ QBFs in Prenex CNF (PCNF):

$$\exists x \exists y \forall u \exists z. \underbrace{(\overset{\text{literals}}{\downarrow} \neg u \vee \overset{\downarrow}{z}) \wedge (\overset{\text{clause}}{\text{y} \vee u \vee \neg z}) \wedge (x \vee \neg u \vee \neg z)}_{\text{CNF}}$$

■ QBFs in Prenex DNF (PDFNF):

$$\forall x \forall y \exists u \forall z. \underbrace{(u \wedge \neg z) \vee (\neg y \wedge \neg u \wedge z) \vee (\neg x \wedge u \wedge z)}_{\text{cube}}$$

Note: $x, y < u < z$ ^{DNF}

QBF Semantics

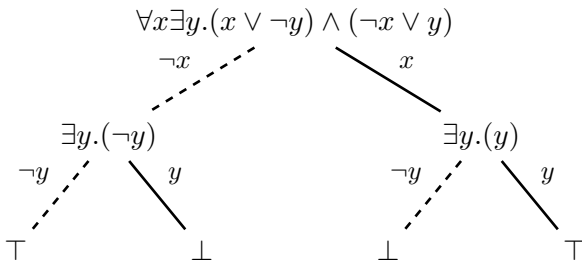
- $\forall x Q.\varphi$ true $\Leftrightarrow Q.\varphi[x]$ **and** $Q.\varphi[\neg x]$ true

QBF Semantics

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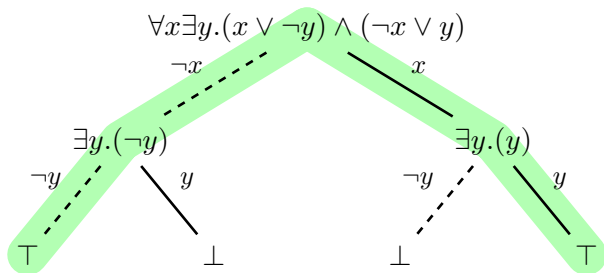
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- Example:



QBF Semantics

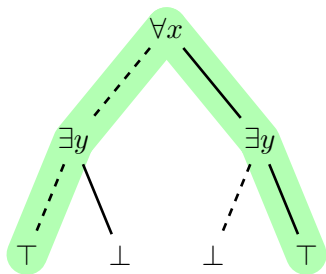
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- Example:



QBF Models

Tree model of **true** formula:

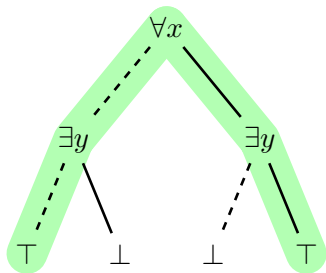
$$\forall x \exists y. (x \vee \bar{y}) \wedge (\bar{x} \vee y)$$



QBF Models

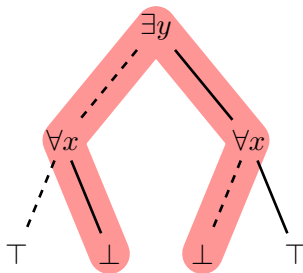
Tree model of **true** formula:

$$\forall x \exists y. (x \vee \bar{y}) \wedge (\bar{x} \vee y)$$



Tree refutation of **false** formula:

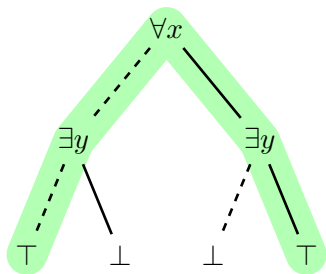
$$\exists y \forall x. (x \vee \bar{y}) \wedge (\bar{x} \vee y)$$



QBF Models

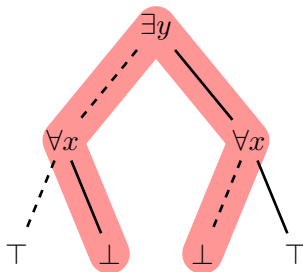
Tree model of **true** formula:

$$\forall x \exists y. (x \vee \bar{y}) \wedge (\bar{x} \vee y)$$



Tree refutation of **false** formula:

$$\exists y \forall x. (x \vee \bar{y}) \wedge (\bar{x} \vee y)$$



Skolem-functions of

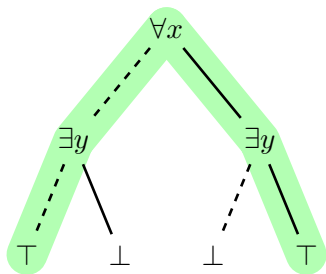
\exists -variables:

$$f_y(x) = x$$

QBF Models

Tree model of **true** formula:

$$\forall x \exists y. (x \vee \bar{y}) \wedge (\bar{x} \vee y)$$



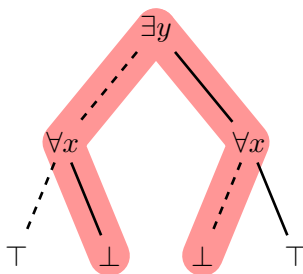
Skolem-functions of

\exists -variables:

$$f_y(x) = x$$

Tree refutation of **false** formula:

$$\exists y \forall x. (x \vee \bar{y}) \wedge (\bar{x} \vee y)$$



Herbrand-functions of

\forall -variables:

$$f_x(y) = \bar{y}$$

```

1 Boolean splitCNF (Prefix  $P$ , matrix  $\psi$ )
2
3 if ( $\psi == \emptyset$ ): return true;
4 if ( $\emptyset \in \psi$ ): return false;
5
6  $P = QXP'$ ,  $x \in X$ ,  $X' = X \setminus \{x\}$ ;
7
8 if ( $Q == \forall$ )
9     return (splitCNF( $QX'P'$ ,  $\psi'$ ) &&
10            splitCNF( $QX'P'$ ,  $\psi''$ ));
11 else
12     return (splitCNF( $QX'P'$ ,  $\psi'$ ) ||
13            splitCNF( $QX'P'$ ,  $\psi''$ ));
14 where
15  $\psi'$ : take clauses of  $\psi$ , delete clauses with  $x$ , delete  $\neg x$ 
16  $\psi''$ : take clauses of  $\psi$ , delete clauses with  $\neg x$ , delete  $x$ 

```

BMC Summary

- BMC is incomplete ...
 - if all checked formulas are unsat, no insight
 - how to choose k ? when to stop increasing k ?

- ... very efficient (e.g., debugging)

- many tuning techniques
 - exploit similarities between two transition steps (structure sharing)
 - simplification of formula by rewritings)