

# SAT-BASED BOUNDED MODEL CHECKING

Formal Models SS16



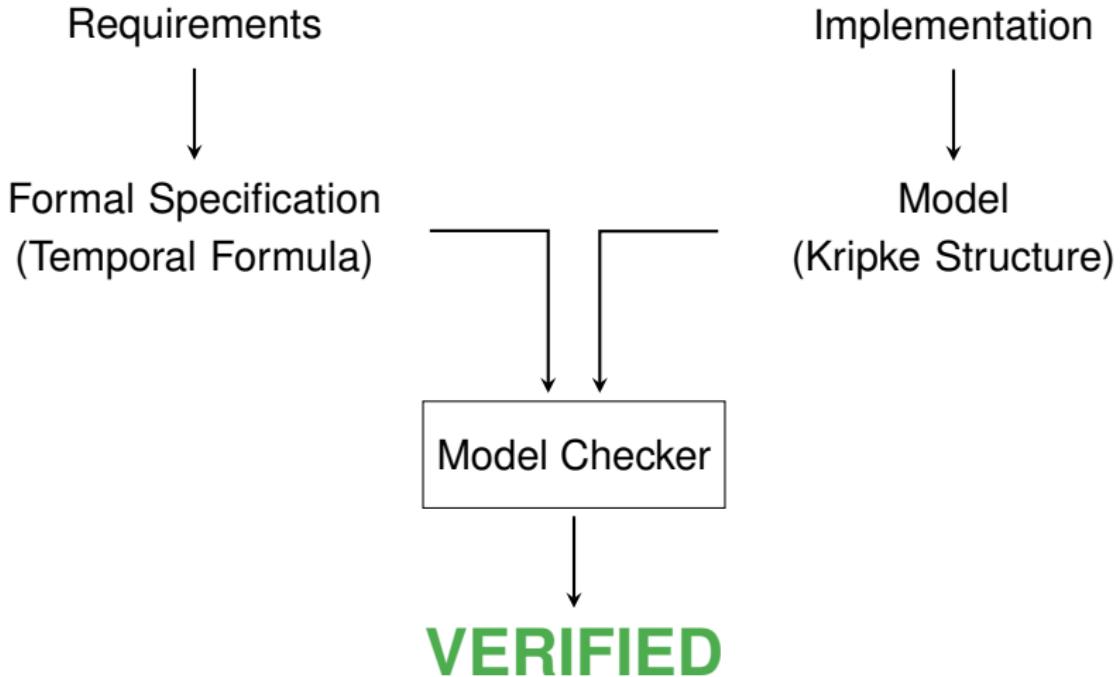
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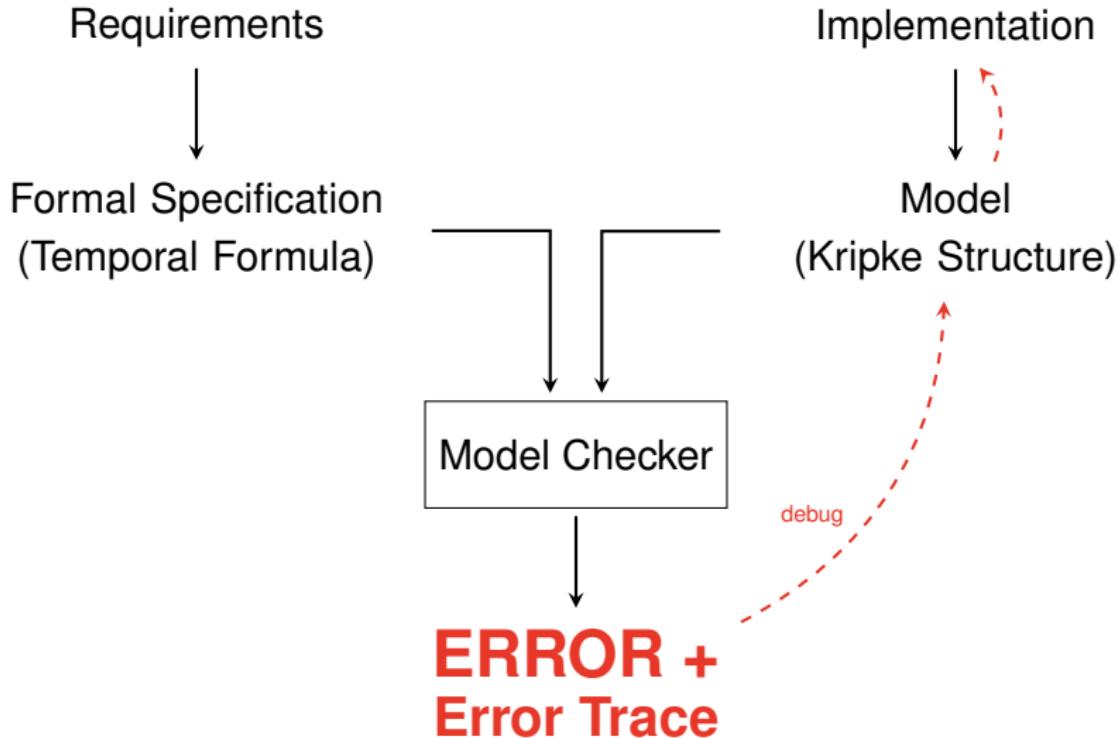


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# Model Checking



# Model Checking



# Types of Model Checking

**General question:** Given a system  $K$  and a property  $p$ , does  $p$  hold for  $K$  (i.e., for all initial states of  $K$ ) ?

- Explicit state model checking
  - enumeration of the state space
  - state explosion problem
- Symbolic model checking
  - representation of model checking problem as logical formula (e.g., in propositional logic (SAT) or QBF)

# Some Properties

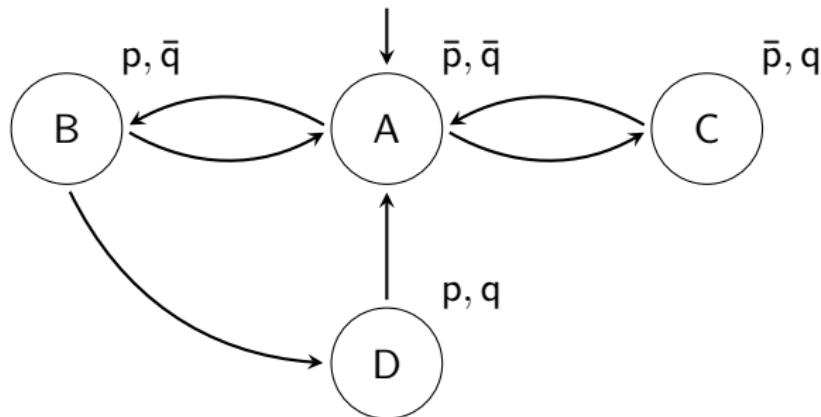
- **Reachability:** property  $p$  holds in one reachable state
- **Invariant:** property  $p$  holds in all reachable states
- **Safety:** some bad property  $p$  never holds  
“something bad will never happen”
- **Liveness:** something good will eventually happen
- **Fairness:** under certain conditions, some property holds repeatedly

# Example: Mutual Exclusion

Given two processes P and Q which share a resource R.

- If R is accessed by P, then property p is true.
- If R is accessed by Q, then property q is true.

The behavior of P and Q is modeled by this Kripke structure:



# Limboole

- SAT-solver for formulas in non-CNF
- available at <http://fmv.jku.at/limboole/>
- input format in BNF:

$\langle expr \rangle ::= \langle iff \rangle$

$\langle iff \rangle ::= \langle implies \rangle \mid \langle implies \rangle " \leftrightarrow " \langle implies \rangle$

$\langle implies \rangle ::= \langle or \rangle \mid \langle or \rangle " \rightarrow " \langle or \rangle \mid \langle or \rangle " \leftarrow " \langle or \rangle$

$\langle or \rangle ::= \langle and \rangle \mid \langle and \rangle " \mid " \langle and \rangle$

$\langle and \rangle ::= \langle not \rangle \mid \langle not \rangle " \& " \langle not \rangle$

$\langle not \rangle ::= \langle basic \rangle \mid " ! " \langle not \rangle$

$\langle basic \rangle ::= \langle var \rangle \mid "(" \langle expr \rangle ")"$

where 'var' is a string over letters, digits, and

- - - . [ ] \$ @

# Symbolic Encoding of Kripke Structures

Given Kripke structure  $K = (S, I, T, L)$  over  $\mathcal{A} = \{a_1, \dots, a_n\}$ .

1. Introduce sets  $\mathcal{A}' = \{a'_1, \dots, a'_n\}$  and  $\mathcal{A}'' = \{a''_1, \dots, a''_n\}$  for the **definition of one transition step  $\mathcal{T}$  over  $\mathcal{A}'$  and  $\mathcal{A}''$** .
2. Associate each state  $s \in S$  with two conjunctions of literals  $current(s)$  and  $next(s)$ :<sup>1</sup>
  - $current(s) := (l_1 \wedge \dots \wedge l_n)$   
such that  $l_i = a'_i$  if  $a_i \in L(s)$  else  $l_i = \bar{a}'_i$ ;
  - $next(s) := (k_1 \wedge \dots \wedge k_n)$   
such that  $k_i = a''_i$  if  $a_i \in L(s)$  else  $k_i = \bar{a}''_i$ .
3. Define prop. formula  $\mathcal{T}$  over  $\mathcal{A}', \mathcal{A}''$  such that  $\forall s_i, s_j \in S$   
 $(\mathcal{T} \wedge current(s_i) \wedge next(s_j))$  is satisfiable iff  $(s_i, s_j) \in T$ .

---

<sup>1</sup>note: the mapping “state to conjunction” has to be bijective

# Naive Encoding of Kripke Structures in SAT

Let  $K = (S, I, T, L)$  be a Kripke structure over  $\mathcal{A}$ .

$\mathcal{T} := \top$

**while**  $S \neq \emptyset$  **do**

    select  $s \in S$

$S := S \setminus \{s\}$

$N := \perp$

**for all**  $(s, t) \in T$  **do**

$N := N \vee \text{next}(t)$

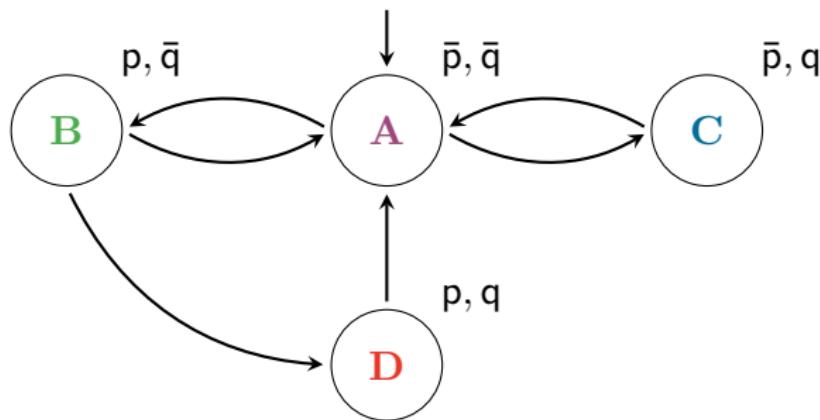
**end for**

$\mathcal{T} := \mathcal{T} \wedge (\text{current}(s) \rightarrow N)$

**end while**

**return**  $\mathcal{T}$

# Naive Encoding of Kripke Structures in SAT



$$\begin{aligned}\mathcal{T} := \top && \wedge \\ (\bar{p} \wedge \bar{q}) \rightarrow (\perp \vee (\bar{p}' \wedge q') \vee (p' \wedge \bar{q}')) && \wedge \\ (p \wedge \bar{q}) \rightarrow (\perp \vee (\bar{p}' \wedge \bar{q}') \vee (p' \wedge q')) && \wedge \\ (\bar{p} \wedge q) \rightarrow (\perp \vee (\bar{p}' \wedge \bar{q}')) && \wedge \\ (p \wedge q) \rightarrow (\perp \vee (\bar{p}' \wedge \bar{q}'))\end{aligned}$$

# Naive Encoding of Kripke Structures in SAT

Encoding in Limboole syntax:

```
((!p & !q) -> (!p-next & q-next) | (p-next & !q-next)) &
((p & !q) -> (!p-next & !q-next) | (p-next & q-next)) &
((!p & q) -> (!p-next & !q-next)) &
((p & q) -> (!p-next & !q-next))
```

```
> limboole limboole/mutual.boole -s
% SATISFIABLE formula (satisfying assignment follows)
```

```
p = 0
q = 0
p-next = 0
q-next = 1
```

# Symbolic Encoding of Kripke Structures

Alternative encoding of transition function:

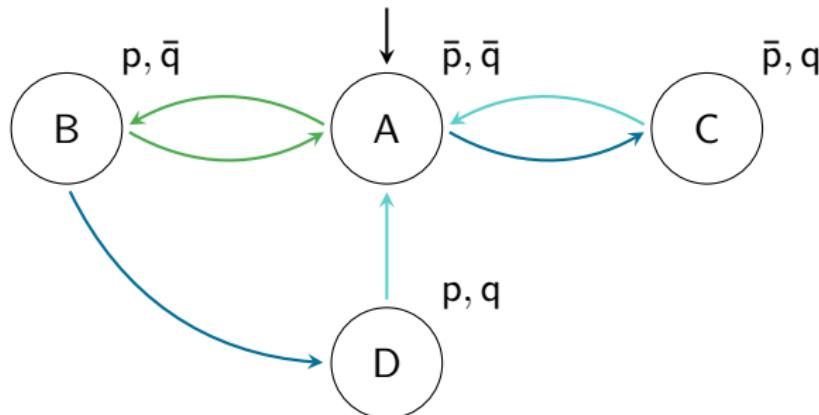
**Successor states**  $p', q'$ :

$$(p' \leftrightarrow (\bar{p} \wedge \bar{q}) \wedge q' \leftrightarrow 0)$$

$\vee$

$$(p' \leftrightarrow (p \wedge \bar{q}) \wedge q' \leftrightarrow \bar{q})$$

$p$	$q$	$p'$	$q'$	or	$p'$	$q'$
0	0	1	0		0	1
0	1	0	0		0	0
1	0	0	0		1	1
1	1	0	0		0	0



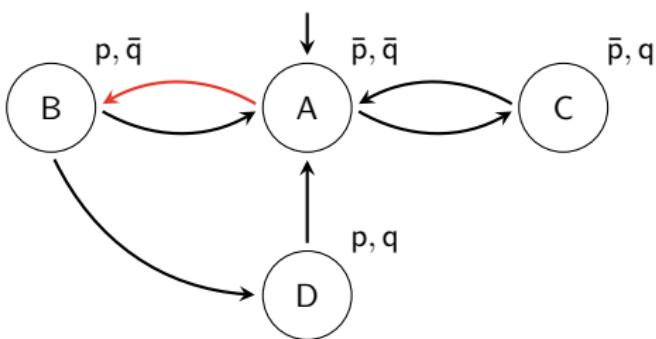
# Example: One Step

Encoding in Limboole syntax:

```
((p-next <-> (!p & !q)) & (!q-next)) |  
(p-next <-> (p & !q)) & (q-next <-> !q)))
```

```
> limboole -s mutual2.boole  
% SATISFIABLE formula (satisfying assignment follows)
```

```
p = 0  
q = 0  
p-next = 1  
q-next = 0
```



# Multiple Transition Steps

- $\mathcal{T}$  over  $\mathcal{A}'$  and  $\mathcal{A}''$  defines one transition step
  - we also write  $\mathcal{T}(s_0, s_1)$  indicating that we can go from state a  $s_0$  to a state  $s_1$
- $\mathcal{T}$  over  $\mathcal{A}''$  and  $\mathcal{A}'''$  defines one transition step
  - we also write  $\mathcal{T}(s_1, s_2)$  indicating that we can go from state a  $s_1$  to a state  $s_2$
- $\mathcal{T}(s_0, s_1) \wedge \mathcal{T}(s_1, s_2)$  defines two transition steps from a state  $s_0$  to a state  $s_1$
- Example (previous slides):
$$(((p' \leftrightarrow (\bar{p} \wedge \bar{q})) \wedge (q' \leftrightarrow 0)) \vee ((p' \leftrightarrow (p \wedge \bar{q})) \wedge (q' \leftrightarrow \bar{q}))) \quad \wedge \\ (((p'' \leftrightarrow (\bar{p}' \wedge \bar{q}')) \wedge (q'' \leftrightarrow 0)) \vee ((p'' \leftrightarrow (p' \wedge \bar{q}')) \wedge (q'' \leftrightarrow \bar{q}')))$$

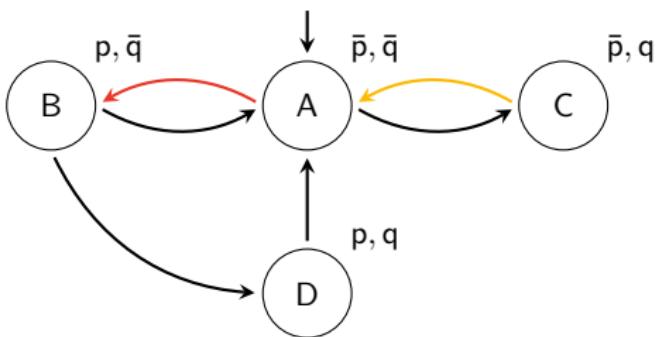
# Example: Two Steps

Encoding in Limboole syntax:

```
((((p-next <-> (!p & !q)) & (!q-next)) |  
((p-next <-> (p & !q)) & (q-next <-> !q)))) &  
(((p-next2 <-> (!p-next & !q-next)) & (!q-next2)) |  
((p-next2 <-> (p-next & !q-next)) & (q-next2 <-> !q-next))))
```

```
> limboole -s mutual2-twoSteps.boole  
% SATISFIABLE formula (satisfying assignment follows)
```

```
p = 0  
q = 1  
p-next = 0  
q-next = 0  
p-next2 = 1  
q-next2 = 0
```



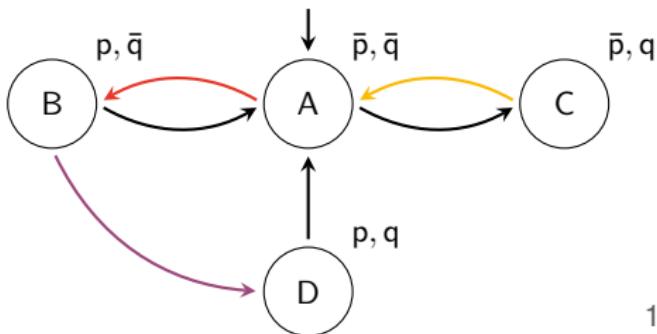
# Example: Three Steps

Encoding in Limboole syntax:

```
((((p-next <-> (!p & !q)) & (!q-next)) |  
((p-next <-> (p & !q)) & (q-next <-> !q)))) &  
(((p-next2 <-> (!p-next & !q-next)) & (!q-next2)) |  
((p-next2 <-> (p-next & !q-next)) & (q-next2 <-> !q-next)))) &  
(((p-next3 <-> (!p-next2 & !q-next2)) & (!q-next3)) |  
((p-next3 <-> (p-next2 & !q-next2)) & (q-next3 <-> !q-next2))))
```

```
limboole -s mutual2-threeSteps.boole  
% SATISFIABLE formula (satisfying assignment follows)
```

```
p = 0  
q = 1  
p-next = 0  
q-next = 0  
p-next2 = 1  
q-next2 = 0  
p-next3 = 1  
q-next3 = 1
```



# Bounded Model Checking (Safety)

- Given a Kripke structure  $K$ . Is there a path of length  $k$  to a **bad state**  $s$ , i.e., a certain property  $p$  is violated in  $s$ ?
- In other words: there is a path where  $\text{G}p$  does not hold in  $K$
- Observation: if  $\text{G}p$  does not hold in  $K$ , there is a **finite counter-example**.
- Idea: consider paths of fixed length  $k$ 
  - encode problem to propositional formula  $\phi$
  - pass problem to SAT solver
  - $\phi$  is true  $\Leftrightarrow$  model of  $\phi$  is counter-example
  - if  $\phi$  is false, then increase  $k$

# Bounded Model Checking (Safety)

A bounded model checking (BMC) problem for Kripke structure  $K$  and safety property  $Gp$  is encoded by

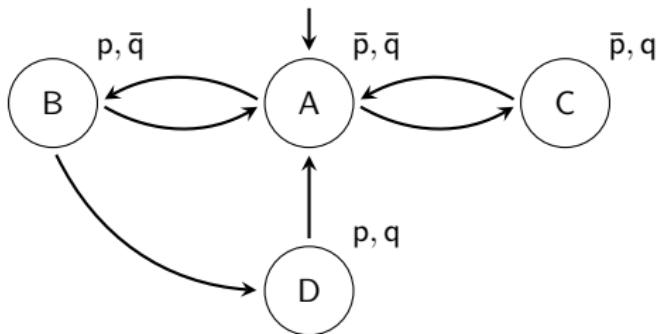
$$I(s_0) \wedge \mathcal{T}(s_0, s_1) \wedge \mathcal{T}(s_1, s_2) \wedge \dots \wedge \mathcal{T}(s_{k-1}, s_k) \wedge B(s_k)$$

where

- $I(s_0)$  is true  $\Leftrightarrow s_0$  is an initial state
- $\mathcal{T}$  is the transition function of  $K$
- $B(s_k)$  is true  $\Leftrightarrow s_k$  is a bad state, i.e.,  $\neg p$  holds in  $s_k$

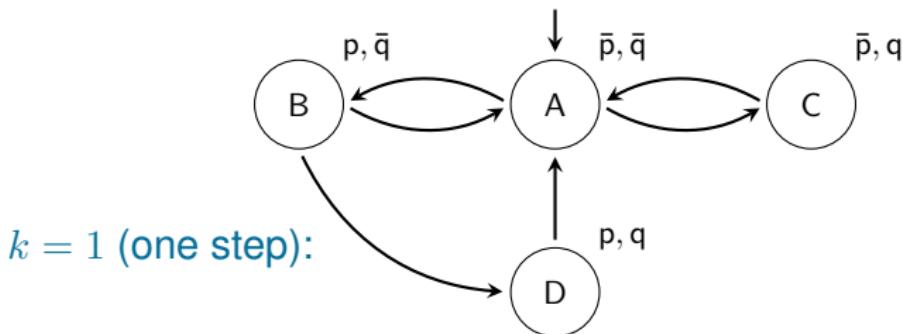
# BMC Example

We want to know if  $G(\bar{p} \vee \bar{q})$  holds for Kripke structure  $K$ :



# BMC Example

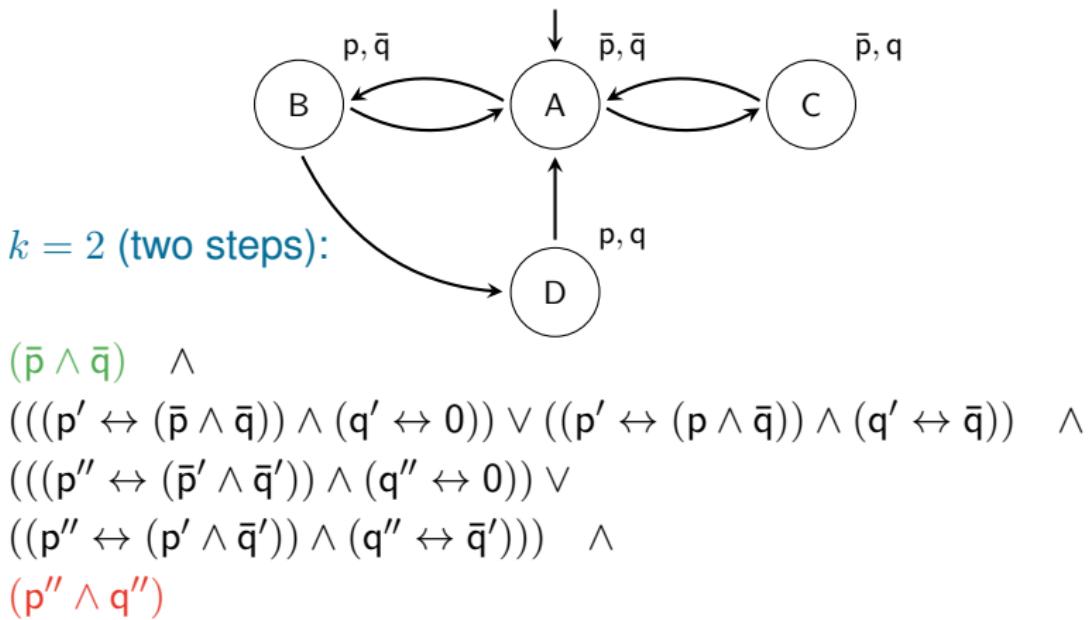
We want to know if  $G(\bar{p} \vee \bar{q})$  holds for Kripke structure  $K$ :



$$((\bar{p} \wedge \bar{q}) \wedge ((p' \leftrightarrow (\bar{p} \wedge \bar{q})) \wedge (q' \leftrightarrow 0)) \vee ((p' \leftrightarrow (p \wedge \bar{q})) \wedge (q' \leftrightarrow \bar{q}))) \wedge (p' \wedge q')$$

# BMC Example

We want to know if  $G(\bar{p} \vee \bar{q})$  holds for Kripke structure  $K$ :



# Bounded Model Checking (Safety) in QBF

A bounded model checking (BMC) problem for Kripke structure  $K$  and reachability property  $p$  is encoded by

$$\exists s_0, s_1, \dots, s_k \forall x, x'. \quad (I(s_0) \quad \wedge \quad B(s_k) \quad \wedge \\ (\bigvee_{i=0}^{k-1} (x \leftrightarrow s_i \wedge x' \leftrightarrow s_{i+1}) \rightarrow \mathcal{T}(x, x')))$$

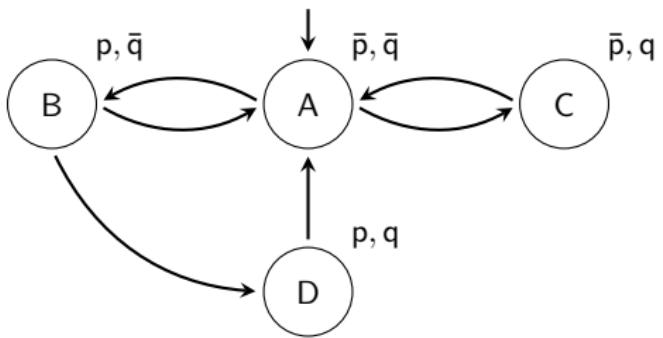
where

- $I(s_0)$  is true  $\Leftrightarrow s_0$  is an initial state
- $\mathcal{T}$  is the transition function of  $K$
- $B(s_k)$  is true  $\Leftrightarrow s_k$  is a bad state, i.e.,  $p$  holds in  $s_k$

**Advantage: only one copy of transition function!**

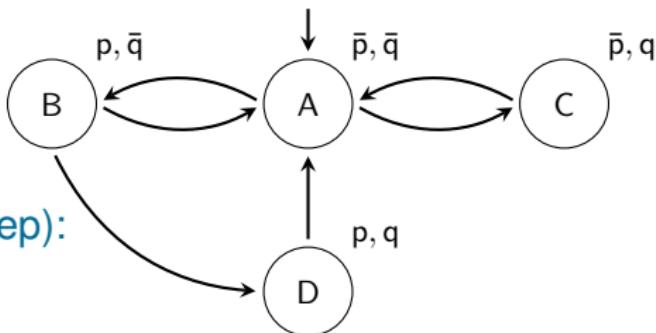
# BMC Example in QBF

We want to know if  $G(\bar{p} \vee \bar{q})$  holds for Kripke structure  $K$ :



# BMC Example in QBF

We want to know if  $G(\bar{p} \vee \bar{q})$  holds for Kripke structure  $K$ :



$k = 1$  (one step):

$\exists p, q, p', q' \forall x, y, x', y'.$

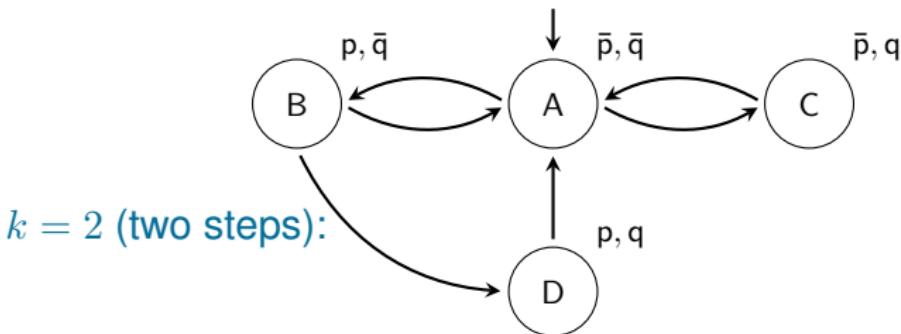
$(\bar{p} \wedge \bar{q}) \quad \wedge \quad (p' \wedge q') \quad \wedge$

$((((x \leftrightarrow p) \wedge (y \leftrightarrow q)) \wedge ((x' \leftrightarrow p') \wedge (y' \leftrightarrow q'))) \rightarrow$

$((x' \leftrightarrow (\bar{x} \wedge \bar{y})) \wedge (y' \leftrightarrow 0)) \vee ((x' \leftrightarrow (x \wedge \bar{y})) \wedge (y' \leftrightarrow \bar{y})))$

# BMC Example in QBF

We want to know if  $G(\bar{p} \vee \bar{q})$  holds for Kripke structure  $K$ :



$$\exists p, q, p', q', p'', q'' \forall x, y, x', y'.$$

$$(\bar{p} \wedge \bar{q}) \quad \wedge \quad (p'' \wedge q'') \quad \wedge$$

$$(((x \leftrightarrow p) \wedge (y \leftrightarrow q) \wedge (x' \leftrightarrow p') \wedge (y' \leftrightarrow q')) \quad \vee$$

$$(((x \leftrightarrow p') \wedge (y \leftrightarrow q') \wedge (x' \leftrightarrow p'') \wedge (y' \leftrightarrow q''))) \rightarrow$$

$$((x' \leftrightarrow (\bar{x} \wedge \bar{y})) \wedge (y' \leftrightarrow 0)) \vee ((x' \leftrightarrow (x \wedge \bar{y})) \wedge (y' \leftrightarrow \bar{y})))$$

# Transformation to PCNF

We assume QBF in prenex normal form, i.e., we have a quantifier prefix  $\Pi$  and propositional formula  $\phi$ .

1. for subformula  $\psi$  of  $\phi'$  introduce new variable  $x_\psi$
2. replace  $\psi$  by  $x_\psi$
3. add definition  $\psi \leftrightarrow x_\psi$  as clauses
4. collect all constraints in a big conjunction
5. add existential quantifier with new variables at the end of the prefix

The transformation is **satisfiability equivalent**:  
the result is satisfiable iff the original formula is satisfiable

# Normalform Transformation: Definitions

## Negation

$$\begin{aligned}x \leftrightarrow \bar{y} &\Leftrightarrow (x \rightarrow \bar{y}) \wedge (\bar{y} \rightarrow x) \\&\Leftrightarrow (\bar{x} \vee \bar{y}) \wedge (y \vee x)\end{aligned}$$

# Normalform Transformation: Definitions

## Disjunction

$$\begin{aligned}x \leftrightarrow (y \vee z) &\Leftrightarrow (y \rightarrow x) \wedge (z \rightarrow x) \wedge (x \rightarrow (y \vee z)) \\&\Leftrightarrow (\bar{y} \vee x) \wedge (\bar{z} \vee x) \wedge (\bar{x} \vee y \vee z)\end{aligned}$$

# Normalform Transformation: Definitions

## Conjunction

$$\begin{aligned}x \leftrightarrow (y \wedge z) &\Leftrightarrow (x \rightarrow y) \wedge (x \rightarrow z) \wedge ((y \wedge z) \rightarrow x) \\&\Leftrightarrow (\bar{x} \vee y) \wedge (\bar{x} \vee z) \wedge (\overline{(y \wedge z)} \vee x) \\&\Leftrightarrow (\bar{x} \vee y) \wedge (\bar{x} \vee z) \wedge (\bar{y} \vee \bar{z} \vee x)\end{aligned}$$

# Normalform Transformation: Definitions

## Equivalence

$$\begin{aligned}x \leftrightarrow (y \leftrightarrow z) &\Leftrightarrow (x \rightarrow (y \leftrightarrow z)) \wedge ((y \leftrightarrow z) \rightarrow x) \\&\Leftrightarrow (x \rightarrow ((y \rightarrow z) \wedge (z \rightarrow y))) \wedge ((y \leftrightarrow z) \rightarrow x) \\&\Leftrightarrow (x \rightarrow (y \rightarrow z)) \wedge (x \rightarrow (z \rightarrow y)) \wedge ((y \leftrightarrow z) \rightarrow x) \\&\Leftrightarrow (\bar{x} \vee \bar{y} \vee z) \wedge (\bar{x} \vee \bar{z} \vee y) \wedge ((y \leftrightarrow z) \rightarrow x) \\&\Leftrightarrow (\bar{x} \vee \bar{y} \vee z) \wedge (\bar{x} \vee \bar{z} \vee y) \wedge (((y \wedge z) \vee (\bar{y} \wedge \bar{z})) \rightarrow x) \\&\Leftrightarrow (\bar{x} \vee \bar{y} \vee z) \wedge (\bar{x} \vee \bar{z} \vee y) \wedge ((y \wedge z) \rightarrow x) \wedge ((\bar{y} \wedge \bar{z}) \rightarrow x) \\&\Leftrightarrow (\bar{x} \vee \bar{y} \vee z) \wedge (\bar{x} \vee \bar{z} \vee y) \wedge (\bar{y} \vee \bar{z} \vee x) \wedge (y \vee z \vee x)\end{aligned}$$

# Transformation to PCNF: Example

$$\begin{aligned} & \exists p, q, p', q' \forall x, y, x', y'. \\ & (\bar{p} \wedge \bar{q}) \quad \wedge \quad (p' \wedge q') \quad \wedge \\ & (((x \leftrightarrow p) \wedge (y \leftrightarrow q) \wedge (x' \leftrightarrow p') \wedge (y' \leftrightarrow q')) \rightarrow \\ & ((x' \leftrightarrow (\bar{x} \wedge \bar{y})) \wedge (y' \leftrightarrow 0)) \vee ((x' \leftrightarrow (x \wedge \bar{y})) \wedge (y' \leftrightarrow \bar{y}))) \end{aligned}$$

# Transformation to PCNF: Example

$\exists p, q, p', q' \forall x, y, x', y'.$

$(\bar{p} \wedge \bar{q}) \quad \wedge \quad (p' \wedge q')$   $\wedge$

$((x \leftrightarrow p) \wedge (y \leftrightarrow q) \wedge (x' \leftrightarrow p') \wedge (y' \leftrightarrow q')) \rightarrow$

$((x' \leftrightarrow (\bar{x} \wedge \bar{y})) \wedge (y' \leftrightarrow 0)) \vee ((x' \leftrightarrow (x \wedge \bar{y})) \wedge (y' \leftrightarrow \bar{y}))$

$\exists p, q, p', q' \forall x, y, x', y' \exists a, b, c, d, e, f, g, h, i, j, k.$

...

$(\bar{x} \vee \bar{a} \vee p) \wedge (\bar{x} \vee \bar{p} \vee a) \wedge (\bar{a} \vee \bar{p} \vee x) \wedge (a \vee p \vee x) \quad \wedge$

$(\bar{y} \vee \bar{b} \vee q) \wedge (\bar{y} \vee \bar{q} \vee b) \wedge (\bar{b} \vee \bar{q} \vee y) \wedge (b \vee q \vee y) \quad \wedge$

$(\bar{x}' \vee \bar{c} \vee p') \wedge (\bar{x}' \vee \bar{p}' \vee c) \wedge (\bar{c} \vee \bar{p}' \vee x') \wedge (c \vee p' \vee x') \quad \wedge$

$(\bar{y}' \vee \bar{d} \vee q') \wedge (\bar{y}' \vee \bar{q}' \vee d) \wedge (\bar{d} \vee \bar{q}' \vee y') \wedge (d \vee q' \vee y') \quad \wedge$

...

# Transformation to PCNF: Example

$$\begin{aligned} & \exists p, q, p', q' \forall x, y, x', y'. \\ & (\bar{p} \wedge \bar{q}) \quad \wedge \quad (p' \wedge q') \quad \wedge \\ & (((x \leftrightarrow p) \wedge (y \leftrightarrow q) \wedge (x' \leftrightarrow p') \wedge (y' \leftrightarrow q')) \rightarrow \\ & ((x' \leftrightarrow (\bar{x} \wedge \bar{y})) \wedge (y' \leftrightarrow 0)) \vee ((x' \leftrightarrow (x \wedge \bar{y})) \wedge (y' \leftrightarrow \bar{y}))) \end{aligned}$$

$$\exists p, q, p', q' \forall x, y, x', y' \exists a, b, c, d, e, f, g, h, i, j, k.$$

...

$$\begin{aligned} & (\bar{e} \vee \bar{x}) \wedge (\bar{e} \vee \bar{y}) \wedge (e \vee x \vee y) \quad \wedge \\ & (\bar{f} \vee x) \wedge (\bar{f} \vee \bar{y}) \wedge (f \vee \bar{x} \vee y) \quad \wedge \end{aligned}$$

...

# Transformation to PCNF: Example

$\exists p, q, p', q' \forall x, y, x', y' .$

$(\bar{p} \wedge \bar{q}) \quad \wedge \quad (p' \wedge q') \quad \wedge$

$((x \leftrightarrow p) \wedge (y \leftrightarrow q) \wedge (x' \leftrightarrow p') \wedge (y' \leftrightarrow q')) \rightarrow$

$((x' \leftrightarrow (\bar{x} \wedge \bar{y})) \wedge (y' \leftrightarrow 0)) \vee ((x' \leftrightarrow (x \wedge \bar{y})) \wedge (y' \leftrightarrow \bar{y})))$

$\exists p, q, p', q' \forall x, y, x', y' \exists a, b, c, d, e, f, g, h, i, j, k.$

...

$(\bar{x}' \vee \bar{g} \vee e) \wedge (\bar{x}' \vee \bar{e} \vee g) \wedge (\bar{g} \vee \bar{e} \vee x') \wedge (g \vee e \vee x') \quad \wedge$

$(\bar{f} \vee \bar{h} \vee x') \wedge (\bar{f} \vee \bar{x}' \vee h) \wedge (\bar{h} \vee \bar{x}' \vee f) \wedge (h \vee x' \vee f) \quad \wedge$

$(\bar{y}' \vee \bar{i} \vee \bar{y}) \wedge (\bar{y}' \vee \bar{y} \vee i) \wedge (\bar{i} \vee y \vee y') \wedge (i \vee \bar{y} \vee y') \quad \wedge$

...

# Transformation to PCNF: Example

$\exists p, q, p', q' \forall x, y, x', y'.$

$(\bar{p} \wedge \bar{q}) \quad \wedge \quad (p' \wedge q')$   $\wedge$

$((x \leftrightarrow p) \wedge (y \leftrightarrow q) \wedge (x' \leftrightarrow p') \wedge (y' \leftrightarrow q')) \rightarrow$

$((x' \leftrightarrow (\bar{x} \wedge \bar{y})) \wedge (y' \leftrightarrow 0)) \vee ((x' \leftrightarrow (x \wedge \bar{y})) \wedge (y' \leftrightarrow \bar{y}))$

$\exists p, q, p', q' \forall x, y, x', y' \exists a, b, c, d, e, f, g, h, i, j, k.$

...

$(\bar{j} \vee \bar{g}) \wedge (\bar{j} \vee y') \wedge (j \vee g \vee \bar{y}') \quad \wedge$

$(\bar{k} \vee h) \wedge (\bar{k} \vee i) \wedge (k \vee \bar{i} \vee \bar{h}) \quad \wedge$

...

# Transformation to PCNF: Example

$$\begin{aligned} & \exists p, q, p', q' \forall x, y, x', y'. \\ & (\bar{p} \wedge \bar{q}) \quad \wedge \quad (p' \wedge q') \quad \wedge \\ & (((x \leftrightarrow p) \wedge (y \leftrightarrow q) \wedge (x' \leftrightarrow p') \wedge (y' \leftrightarrow q')) \rightarrow \\ & ((x' \leftrightarrow (\bar{x} \wedge \bar{y})) \wedge (y' \leftrightarrow 0)) \vee ((x' \leftrightarrow (x \wedge \bar{y})) \wedge (y' \leftrightarrow \bar{y}))) \end{aligned}$$

$$\exists p, q, p', q' \forall x, y, x', y' \exists a, b, c, d, e, f, g, h, i, j, k.$$

...

$$\begin{aligned} & (\bar{p} \wedge \bar{q}) \wedge (p' \wedge q') \quad \wedge \\ & (\bar{a} \vee \bar{b} \vee \bar{c} \vee \bar{d} \vee j \vee k) \end{aligned}$$

# QBF Solving

- Most QBF solvers support only QDIMACS format
  - like DIMACS but with quantifier prefix
- QBF solvers return true/false
  - assignments for variables in outermost quantifier block
  - functions for solving strategies
- Community platform: [www.qbflib.org](http://www.qbflib.org)
- Examples for state-of-the-art solvers:
  - DepQBF
  - RAReQS

# Bounded Model Checking (Fairness)

- Given a Kripke structure  $K$ . Is there a path such that a property  $\neg p$  holds forever?
- In other words: there is a path such that  $\text{F}p$  does not hold in  $K$
- Observation 1: if  $\text{F}p$  does not hold in  $K$ , there is an **infinite counter-example**.
- Observation 2: if the counter-example is infinite, then it has to be because of a cycle.

# Bounded Model Checking (Fairness)

A bounded model checking (BMC) problem for Kripke structure  $K$  and fairness property  $\text{Fp}$  is encoded by

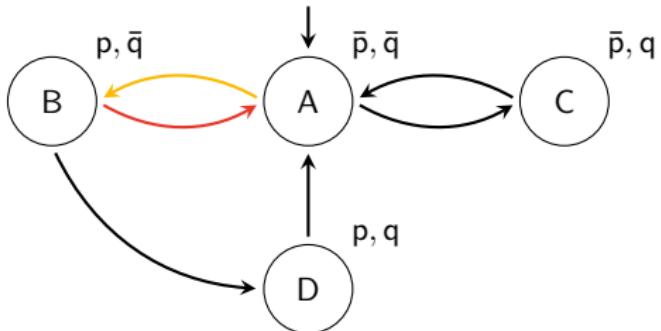
$$I(s_0) \wedge \bigwedge_{l=0}^{k-1} \mathcal{T}(s_l, s_{l+1}) \wedge \bigvee_{i=0}^k \mathcal{T}(s_k, s_i) \wedge \bigwedge_{j=0}^k F(s_j)$$

where

- $I(s_0)$  is true  $\Leftrightarrow s_0$  is an initial state
- $\mathcal{T}$  is the transition function of  $K$
- $F(s_k)$  is true  $\Leftrightarrow \neg p$  holds in  $s_k$

# BMC Fairness

We want to know if  $Fq$  holds for Kripke structure  $K$ :



Initial State:

$$(\bar{p} \wedge \bar{q}) \quad \wedge$$

One Step:

$$(((p' \leftrightarrow (\bar{p} \wedge \bar{q})) \wedge (q' \leftrightarrow 0)) \vee ((p' \leftrightarrow (p \wedge \bar{q})) \wedge (q' \leftrightarrow \bar{q}))) \quad \wedge$$

Cycle Check:

$$((((p \leftrightarrow (\bar{p}' \wedge \bar{q}')) \wedge (q \leftrightarrow 0)) \vee ((p \leftrightarrow (p' \wedge \bar{q}')) \wedge (q \leftrightarrow \bar{q}'))) \quad \vee \\ (((p' \leftrightarrow (\bar{p}' \wedge \bar{q}')) \wedge (q' \leftrightarrow 0)) \vee ((p' \leftrightarrow (p' \wedge \bar{q}')) \wedge (q' \leftrightarrow \bar{q}')))) \quad \wedge$$

Property Check:

$$\bar{q} \wedge \bar{q}'$$

# BMC Summary

- BMC is incomplete ...
  - if all checked formulas are unsat, no insight
  - how to choose  $k$ ? when to stop increasing  $k$ ?
- ... very efficient (e.g., debugging)
- many tuning techniques
  - exploit similarities between two transition steps  
(structure sharing)
  - simplification of formula by rewritings )

# How to choose $k$ for Safety?

Given Kripke structure  $K$ , the **diameter** is the smallest number  $d$  such that for every path  $s_0, \dots, s_{d+1}$  there exists a path  $t_0, \dots, t_l$  such that  $l \leq d$  and  $t_0 = s_0$  and  $t_l = s_{d+1}$ .

- If a state  $s$  is reachable from state  $t$ , then there is a path of length  $d$  of less where  $d$  is the diameter.
- The diameter is the maximum length between two states.
- Computing the diameter is difficult (solve a QBF).

# How to choose $k$ for Fairness?

Given Kripke structure  $K$ , the **recurrence diameter** is the smallest number  $d$  such that for every path  $s_0, \dots, s_{d+1}$ , there exists  $j \leq d$  with  $s_{d+1} = s_j$ .

- The recurrence diameter is the maximum length of a non-looping path.
- Can be formulated as validity checking problem.