LOGIC | SATISFIABILITY MODULO THEORIES

SMT DETAILS

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Propositional Skeleton

Example (arbitrary LRA formula)

$$x \neq y \land (2 * x \leq z \quad \lor \quad \neg (x - y \geq z \land z \leq y))$$

eliminate \neq by disjunction

$$(\underbrace{x < y}_{a} \lor \underbrace{x > y}_{b}) \land (\underbrace{2 * x \leq z}_{c} \lor \neg(\underbrace{x - y \geq z}_{d} \land \underbrace{z \leq y}_{e}))$$

which is abstracted to a propositional formula called "propositional skeleton"

$$(a \lor b) \land (c \lor \neg (d \land e))$$
 with $\alpha(x < y) = a, \quad \alpha(x > y) = b, \dots$

SAT solver enumerates solutions, e.g., a = b = c = d = e = 1

check solution literals with theory solver, e.g., Fourier-Motzkin

spurious solutions (disproven by theory solver) added as "lemma", e.g., $\neg(a \land b \land c \land d \land e)$ or just $\neg(a \land b)$ after minimization

continue until SAT solver says unsatisfiable or theory solver satisfiable

Lemmas-on-Demand

```
this is an extremely "lazy" version of DPLL (T) / CDCL(T)
LemmasOnDemand(\phi)
     \psi = PropositionalSkeleton(\phi)
      let \alpha be the abstraction function, mapping theory literals to prop. literals
     while \psi has satisfiable assignment \sigma
            let l_1, \ldots, l_n be all the theory literals with \sigma(\alpha(l_i)) = 1
            check conjunction L = l_1 \wedge \cdots \wedge l_n with theory solver
            if theory solver returns satisfying assignment ρ return satisfiable
            determine "small" sub-set \{k_1, \ldots, k_m\} \subset \{l_1, \ldots, l_n\} where
               K = k_1 \wedge \cdots \wedge k_m remains unsatisfiable (by theory solver)
            add lemma \neg K to \psi, actually replace \psi by \psi \wedge \alpha(\neg K)
      return unsatisfiable
```

note that these lemmas $\neg K$ are all clauses

Minimal Unsatisfiable Set (MUS)

motivation: the lemmas we add in "lemmas-on-demand" should be small

$$\overbrace{(a \vee \neg b) \wedge (a \vee b) \wedge \underbrace{(\neg a \vee \neg c) \wedge (\neg a \vee c)}_{\text{MUS}} \wedge (a \vee \neg c) \wedge (a \vee c)}$$

- \blacksquare given an unsatisfiable set of "constraints" S (set of literals, or clauses)
- \blacksquare an MUS M is a sub-set $M \subseteq S$ such that
 - \square *M* is still unsatisfiable
 - \square any $M' \subset M$ (with $M' \neq M$) is satisfiable
- so an MUS is a "minimal" inconsistent subset
 - $\ \square$ all constraints in the MUS are *necessary* for M to be inconsistent
 - $\ \square$ so one minimal way to explain inconsistency of S
- note that "being inconsistent" is a monotone property
 - \Box if $A \subseteq B$ is a set of constraints
 - \square if A is unsatisfiable then B is unsatisfiable
 - essential for algorithms to compute an MUS

Iterative Destructive Algorithm for MUS Computation

destructive = remove constraints from an over-approximation of an MUS

```
\begin{split} & M = S \\ & D = S \\ & \text{while } D \neq \emptyset \\ & \text{pick constraint } C \in D \\ & \text{if } M \backslash \{C\} \text{ unsatisfiable remove } C \text{ from } M \\ & \text{remove } C \text{ from } D \end{split}
```

needs exactly |S| satisfiability checks

any-time algorithm: preliminary result M remains inconsistent can stop any time

QuickXplain Variant of MUS Computation

quickly "zoom in" on one MUS (particularly if there is a small one)

```
QuickMUSRecursive(D)
     if M \setminus D is satisfiable
          if |D| > 1
               let D = L \cup R with |L|, |R| > 0 \ldots \ge \lfloor \frac{|D|}{2} \rfloor
                QuickMUSRecursive(L)
                QuickMUSRecursive(R)
     else remove D from M
QuickMUS(S)
     global variable M = S
     QuickMUSRecursive(S)
     return M
```

needs at most $2 \cdot |S|$ and at least |M| satisfiability checks

Theory of Arrays

- \blacksquare functions "read" and "write": read(a, i), write(a, i, v)
- axioms

$$\begin{aligned} \forall a,i,j\colon i=j \to \mathsf{read}(a,i) = \mathsf{read}(a,j) & \textit{array congruence} \\ \forall a,v,i,j\colon i=j \to \mathsf{read}(\mathsf{write}(a,i,v),j) = v & \textit{read over write 1} \\ \forall a,v,i,j\colon i\neq j \to \mathsf{read}(\mathsf{write}(a,i,v),j) = \mathsf{read}(a,j) & \textit{read over write 2} \end{aligned}$$

- used to model memory (HW and SW)
- eagerly reduce arrays to uninterpreted functions by eliminating "write"

$$read(write(a, i, v), j)$$
 replaced by $(i = j ? v : read(a, j))$

- more sophisticated non-eager algorithms are usually faster
 - □ such as for instance the "lemmas-on-demand" algorithm in Boolector

Simple Array Example

$$i \neq j \ \land \ u = \mathsf{read}(\mathsf{write}(a,i,v),j) \ \land \ v = \mathsf{read}(a,j) \ \land \ u \neq v$$

eliminate "write"

$$i \neq j \ \land \ u = (i = j \ ? \ v : \mathsf{read}(a, j)) \ \land \ v = \mathsf{read}(a, j) \ \land \ u \neq v$$

simplify conditional by assuming " $i \neq j$ "

$$i \neq j \ \land \ u = \mathsf{read}(a,j) \ \land \ v = \mathsf{read}(a,j) \ \land \ u \neq v$$

applying congruence for both "read"

$$i \neq j \land u = \operatorname{read}(a, j) = \operatorname{read}(a, j) = v \land u \neq v$$

which is clearly unsatisfiable

More Complex Array Example for Checking Aliasing

```
original
                              optimized
   assert (i != k);
                             int t = a[k];
   a[i] = a[k];
                 a[i] = t;
   a[i] = a[k]:
                            a[i] = t;
   i \neq k
                t = \mathsf{read}(a, k)
   b_1 = \mathsf{write}(a, i, t) c_1 = \mathsf{write}(a, i, t)
   b_2 = \mathsf{write}(b_1, j, s) c_2 = \mathsf{write}(c_1, j, t)
   s = \operatorname{read}(b_1, k)
original ≠ optimized
                             iff
                                                  b_2 \neq c_2
       b_2 \neq c_2 iff \exists l with read(b_2, l) \neq read(c_2, l)
```

thus $original \neq optimized$ iff

```
\begin{split} i &\neq k \\ t &= \mathsf{read}(a,k) \\ b_1 &= \mathsf{write}(a,i,t) \\ b_2 &= \mathsf{write}(b_1,j,s) \\ c_1 &= \mathsf{write}(a,i,t) \\ c_2 &= \mathsf{write}(c_1,j,t) \\ s &= \mathsf{read}(b_1,k) \\ \mathsf{read}(b_2,l) &\neq \mathsf{read}(c_2,l) \end{split}
```

thus original ≠ optimized iff

```
\begin{split} i &\neq k \\ t &= \mathsf{read}(a,k) \\ b_1 &= \mathsf{write}(a,i,t) \\ b_2 &= \mathsf{write}(b_1,j,s) \\ c_1 &= \mathsf{write}(a,i,t) \\ c_2 &= \mathsf{write}(c_1,j,t) \\ s &= \mathsf{read}(b_1,k) \\ u &= \mathsf{read}(b_2,l) \\ v &= \mathsf{read}(c_2,l) \\ u &\neq v \end{split}
```

satisfiable

after eliminating c_2

```
\begin{split} i \neq k \\ t &= \mathsf{read}(a,k) \\ b_1 &= \mathsf{write}(a,i,t) \\ b_2 &= \mathsf{write}(b_1,j,s) \\ c_1 &= \mathsf{write}(a,i,t) \\ c_2 &= \mathsf{write}(c_1,j,t) \\ s &= \mathsf{read}(b_1,k) \\ u &= \mathsf{read}(b_2,l) \\ v &= (l=j~?~t: \mathsf{read}(c_1,l)) \\ u \neq v \end{split}
```

after eliminating c_2 , c_1

```
\begin{split} i \neq k \\ t &= \mathsf{read}(a,k) \\ b_1 &= \mathsf{write}(a,i,t) \\ b_2 &= \mathsf{write}(b_1,j,s) \\ c_1 &= \mathsf{write}(a,i,t) \\ c_2 &= \mathsf{write}(c_1,j,t) \\ s &= \mathsf{read}(b_1,k) \\ u &= \mathsf{read}(b_2,l) \\ v &= (l=j~?~t:(l=i~?~t:\mathsf{read}(a,l))) \\ u \neq v \end{split}
```

after eliminating c_2 , c_1 , b_2

```
\begin{split} i \neq k \\ t &= \mathsf{read}(a,k) \\ b_1 &= \mathsf{write}(a,i,t) \\ b_2 &= \mathsf{write}(b_1,j,s) \\ c_1 &= \mathsf{write}(a,i,t) \\ c_2 &= \mathsf{write}(c_1,j,t) \\ s &= \mathsf{read}(b_1,k) \\ u &= (l=j~?~s: \mathsf{read}(b_1,l)) \\ v &= (l=j~?~t: (l=i~?~t: \mathsf{read}(a,l))) \\ u \neq v \end{split}
```

after eliminating c_2 , c_1 , b_2 , b_1

```
\begin{split} i \neq k \\ t &= \mathsf{read}(a,k) \\ b_1 &= \mathsf{write}(a,i,t) \\ b_2 &= \mathsf{write}(b_1,j,s) \\ c_1 &= \mathsf{write}(a,i,t) \\ c_2 &= \mathsf{write}(c_1,j,t) \\ s &= (k=i\ ?\ t: \mathsf{read}(a,k)) \\ u &= (l=j\ ?\ s: (l=i\ ?\ t: \mathsf{read}(a,l))) \\ v &= (l=j\ ?\ t: (l=i\ ?\ t: \mathsf{read}(a,l))) \\ u \neq v \end{split}
```

result after "write" elimination

```
\begin{split} & i \neq k \\ & t = \mathsf{read}(a,k) \\ & s = (k = i \ ? \ t : \mathsf{read}(a,k)) \\ & u = (l = j \ ? \ s : (l = i \ ? \ t : \mathsf{read}(a,l))) \\ & v = (l = j \ ? \ t : (l = i \ ? \ t : \mathsf{read}(a,l))) \\ & u \neq v \end{split}
```

after eliminating conditionals (if-then-else)

```
i \neq k
t = read(a, k)
k = i \rightarrow s = t
k \neq i \rightarrow s = \operatorname{read}(a, k)
l = i \rightarrow u = s
l \neq i \land l = i \rightarrow u = t
l \neq i \land l \neq i \rightarrow u = \text{read}(a, l)
l = i \rightarrow v = t
l \neq i \land l = i \rightarrow v = t
l \neq i \land l \neq i \rightarrow v = \text{read}(a, l)
u \neq v
```

now treat "read" as uninterpreted function (say f) check with lemmas-on-demand and congruence closure

Ackermann's Reduction

formula in theory of uninterpreted functions with equality and disequality:

1. flatten terms by introducing new variables as before ☐ remove nested function applications equalities and disequalities have at least one variable on left or right side 2. instantiate congruence axiom in all possible ways: \square replace all function applications f(u) by new variable f^u \square replace all function applications f(u,v) by new variable $f^{u,v}$ etc. 3. If formula contains f^u and f^v add $u = v \rightarrow f^u = f^v$ as lemma etc. 4. use decision procedure for theory of equality and disequality \square if the resulting formula after the first two steps contains n variables then only need to consider domains with n elements \square or bit-vectors of length $\lceil \log_2 n \rceil$ bits allows eager encoding into SAT

[&]quot;eagerly" generates all instantiations of the congruence axioms as lemmas

Example of Ackermann's Reduction

we start with an already flattened formula

$$x = f(y) \land y = f(x) \land x \neq y$$

after second step

$$x = f^y \land y = f^x \land x \neq y$$

after adding lemmas in third step

$$x = f^y \land y = f^x \land x \neq y \land (x = y \rightarrow f^x = f^y)$$

resulting formula has 4 variables thus needs bit-vectors of length 2

Example of Ackermann's Reduction to Bit-Vectors

```
$ cat ack.smt2
(set-logic QF BV)
(declare-fun x () ( BitVec 2))
(declare-fun v () ( BitVec 2))
(declare-fun fx () ( BitVec 2))
(declare-fun fy () ( BitVec 2))
(assert (and (= x fy) (= y fx) (distinct x y) (=> (= x y) (= fx fy))))
(check-sat)
(exit)
$ boolector ack.smt2 -m -d
sat
χO
y 3
fx 3
fy 0
```

Theory of Bit-Vectors

	allows "bit-precise" reasoning
	 □ caputures semantics of low-level languages like assembler, C, C++, □ Java / C# also use two-complement representations for int □ modelling of hardware / circuits on the word-level (RTL) □ important for security applications and precise test case generation
•	many operations
	 logical operations, bit-wise operations (and, or) equalities, inequalities, disequalities shift, concatenation, slicing addition, multiplication, division, modulo,
	main approach is reduction to SAT through bit-blasting
	 reduction of bit-vector operations similar to circuit synthesis Ackermann's Reduction only needs equality and disequality

Bit-Blasting Bit-Vector Equality

for each bit-vector equality u = v with u and v bit-vectors of width w

introduce new propositional variables for individual bits

$$u_1,\ldots,u_w$$
 v_1,\ldots,v_w

replace u=v by new propositional variable $e_{u=v}$

add the propositional constraint

$$e_{u=v} \leftrightarrow \bigwedge_{i=1}^{w} (u_i \leftrightarrow v_i)$$

disequality $u \neq v$ is replaced by $\neg e_{u=v}$

resulting formula satisfiable iff original formula satisfiable

Bit-Blasting Ackermann Example

$$x = f^y \land y = f^x \land x \neq y \land (x = y \to f^x = f^y)$$

now replacing the bit-vector equalities and the disequality by new e variables

$$e_{x=f^y} \wedge e_{y=f^x} \wedge \neg e_{x=y} \wedge (e_{x=y} \rightarrow e_{f^x=f^y})$$

and adding the equality constraints

$$\begin{array}{lll} e_{x=f^y} & \leftrightarrow & (x_1 \leftrightarrow f_1^y) \wedge (x_2 \leftrightarrow f_2^y) \\ e_{y=f^x} & \leftrightarrow & (y_1 \leftrightarrow f_1^x) \wedge (y_2 \leftrightarrow f_2^x) \\ e_{x=y} & \leftrightarrow & (x_1 \leftrightarrow y_1) \wedge (x_2 \leftrightarrow y_2) \\ e_{f^x=f^y} & \leftrightarrow & (f_1^x \leftrightarrow f_1^y) \wedge (f_2^x \leftrightarrow f_2^y) \end{array}$$

gives an "equi-satisfiable" formula which can be checked by SAT solver

Bit-Blasting Ackermann Example in Limboole Syntax

\$ cat ackbitblasted.limboole exfy & eyfx & !exy & (exy -> efxfy) & (exfy <-> (x1 <-> fy1) & (x2 <-> fy2)) &(eyfx <-> (y1 <-> fx1) & (y2 <-> fx2)) &(exy <-> (x1 <-> y1) & (x2 <-> y2)) &(efxfy <-> (fx1 <-> fy1) & (fx2 <-> fy2))\$ limboole ackbitblasted.limboole -s | grep -v SAT | sort efxfv = 0exfy = 1exy = 0eyfx = 1fx1 = 0fx2 = 1fv1 = 1fy2 = 1x1 = 1 $x^2 = 1$ v1 = 0

y2 = 1