



Software Model Checking via Large-Block Encoding

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Motivations

- ◆ **SMT: very promising technology for verification**
 - ◆ SMT solvers: efficient, powerful, scalable
 - ◆ Several SMT-based verification techniques recently proposed
- ◆ **Software Model Checking: effective technique for software verification** (e.g. SLAM, BLAST, verification of device drivers)
 - ◆ **Popular approach:** lazy abstraction with analysis of an abstract reachability tree (ART)
- ◆ Current ART-based approaches do not take **full advantage** of SMT solvers
 - ◆ **Explicit exploration** of the ART, **SMT only** used (mostly) **for conjunctions** of constraints



Contribution

- ◆ **Large-Block Encoding:** (simple) generalization of traditional ART-based approach aimed at **better exploiting SMT** technology
 - ◆ **Less explicit search** on the ART, **more symbolic** search within the SMT solver
 - ◆ **Empirical evidence** of the benefits on a set of standard benchmark C programs

Outline



- ◆ Background
- ◆ Large-Block Encoding
- ◆ Experimental evaluation



Background – Programs and CFAs

Programs represented as control-flow automata (CFAs)

- ◆ A **CFA** is a pair (L, G) , where:
 - ◆ L : set of **program locations**
 - ◆ G : set of **edges** $L \times Op \times L$
- ◆ l_0 entry point of a program,
 l_E error location

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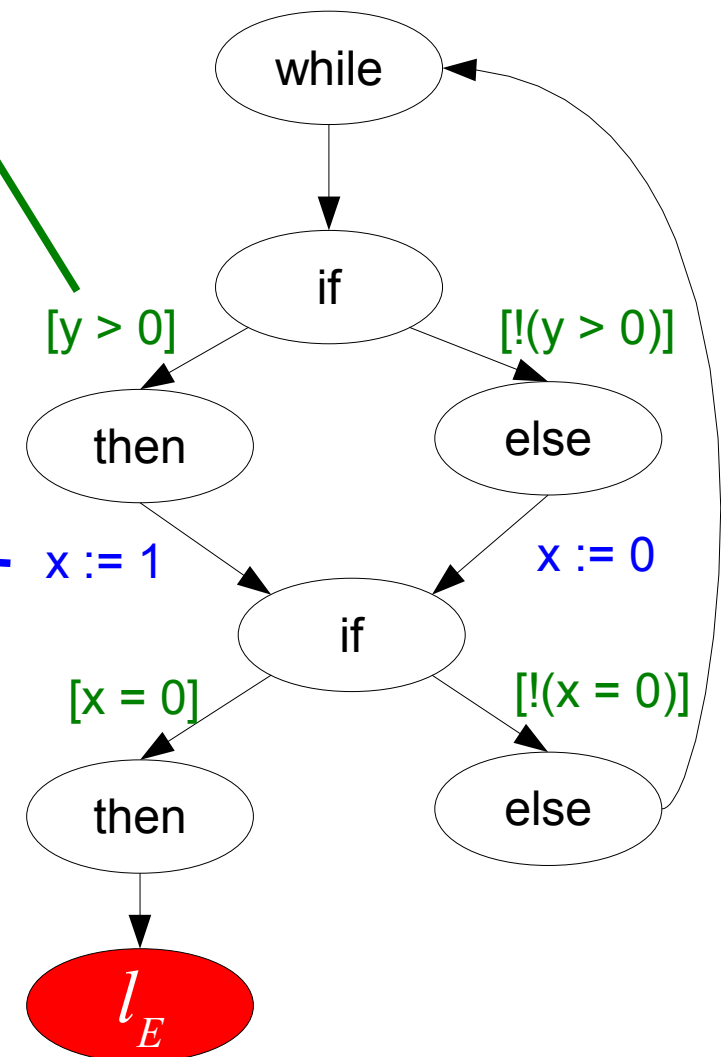
l_E error location

◆ **Example:**

```
while (1) {  
    if (y > 0) x = 1;  
    else x = 0;  
    if (x == 0) goto ERROR;  
}
```

“Assume” operation

“Assign” operation



Background – semantics

- ◆ **Concrete state** of a program: (l, s) , where
 - ◆ l is a location
 - ◆ s is an assignment to program variables (a formula $\bigwedge_i x_i = v_i$)
- ◆ Concrete **semantics** of an operation op given by SP_{op} :
 - ◆ **Assign:** $SP_{x:=e}(\varphi) = \exists \hat{x} : \varphi_{[x \mapsto \hat{x}]} \wedge (x = e_{[x \mapsto \hat{x}]})$
 - ◆ **Assume:** $SP_p(\varphi) = \varphi \wedge p$
- ◆ **Path:** seq. $\sigma = \langle (op_p, l_p) \dots (op_n, l_n) \rangle$ where (l_{i-1}, op_i, l_i) is a CFA edge
 - ◆ Semantics $SP_\sigma(\varphi) = SP_{op_n}(\dots SP_{op_1}(\varphi) \dots)$
 - ◆ **Feasible** if $SP_\sigma(true)$ is **satisfiable**
- ◆ Location l **reachable** iff exists feasible path $\langle (op_p, l_p) \dots (op_n, l) \rangle$
- ◆ Program **safe** iff l_E not reachable

Background – ART-based SW MC

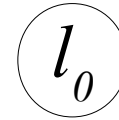
- ◆ **Abstraction** of φ : $\alpha(\varphi)$ such that $\varphi \models \alpha(\varphi)$
 - ◆ Abstract SP: $\text{SP}_{op}^\alpha(\varphi) = \alpha(\text{SP}_{op}(\varphi))$
- ◆ **Abstract Reachability Tree (ART)**: unwinding of the CFA in an abstract space
 - ◆ Each node is an abstract state (l, φ)
 - ◆ children of (l, φ) : **abstract successors**: $\{(l_i, \hat{\varphi}_i)\}_i$
 - ◆ (l, op_i, l_i) is an edge in the CFA
 - ◆ $\hat{\varphi}_i = \text{SP}_{op_i}^\alpha(\varphi)$ and $\hat{\varphi}_i \neq \perp$
 - ◆ (l, φ) has children only if not **covered**
 - ◆ there is no (l, ψ) in the ART s.t. $\varphi \models \psi$
 - ◆ ART **safe** if there is no (l_E, \cdot)



Background – ART-based SW MC (2)

On-the-fly ART construction with counterexample-guided abstraction refinement (CEGAR)

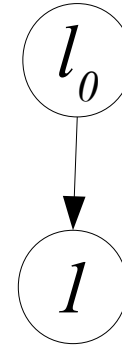
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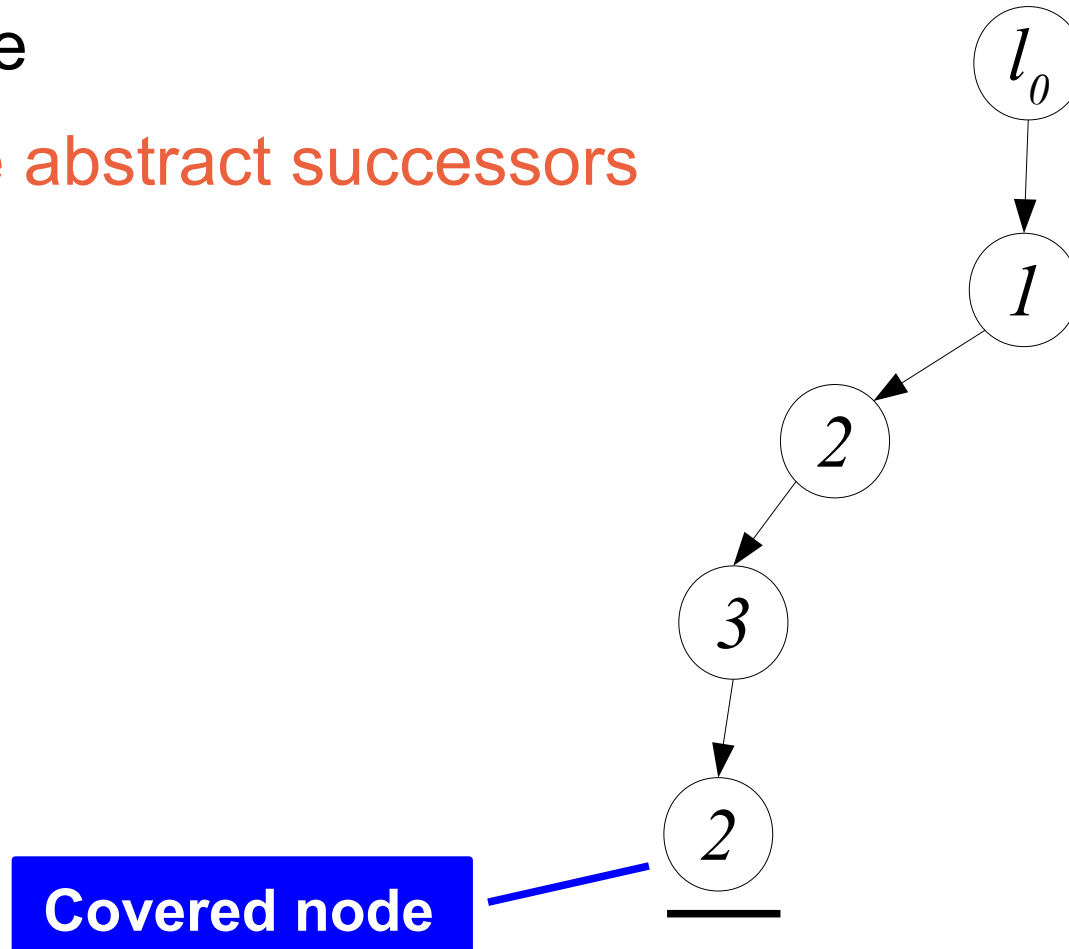
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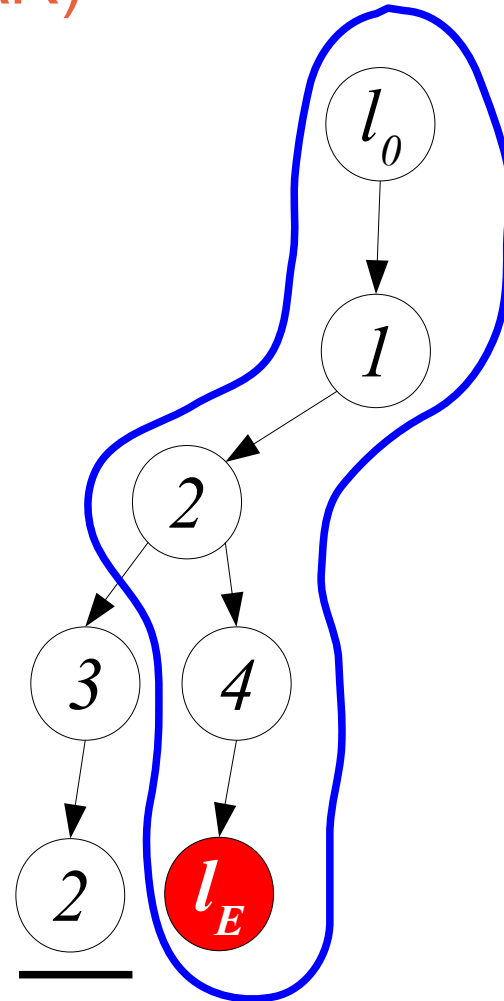
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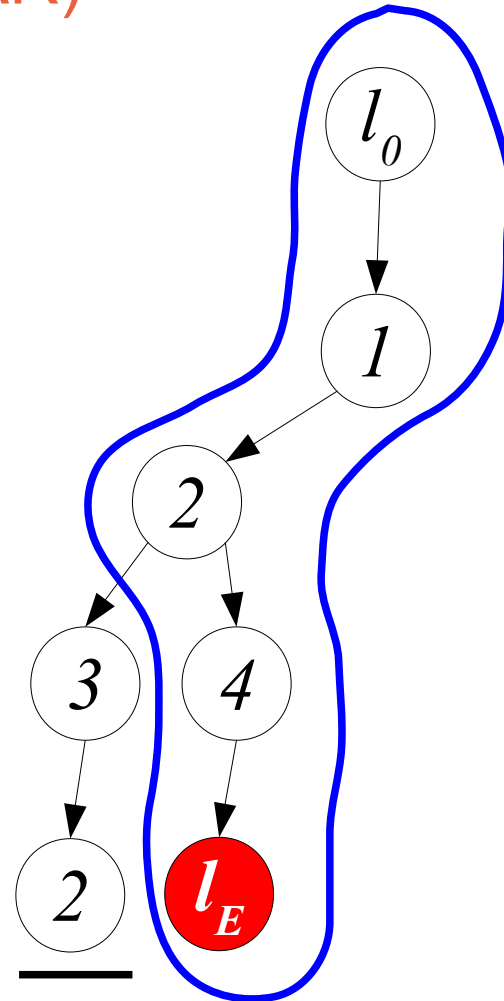
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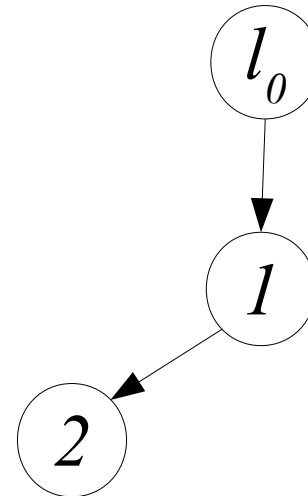
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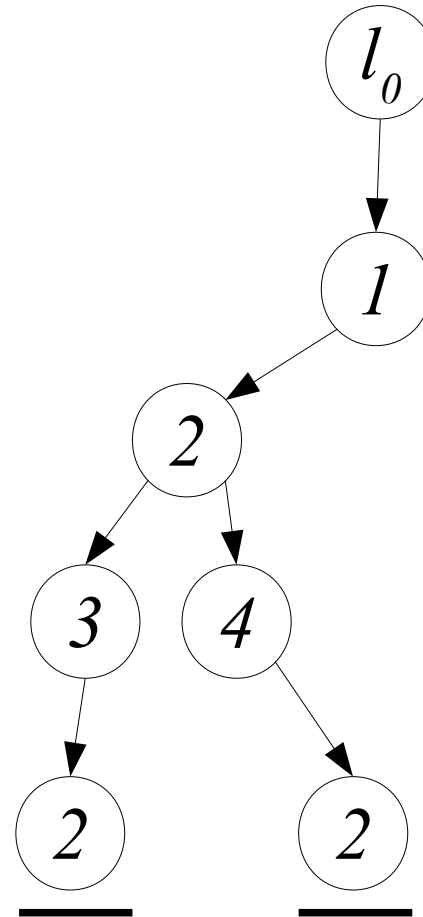
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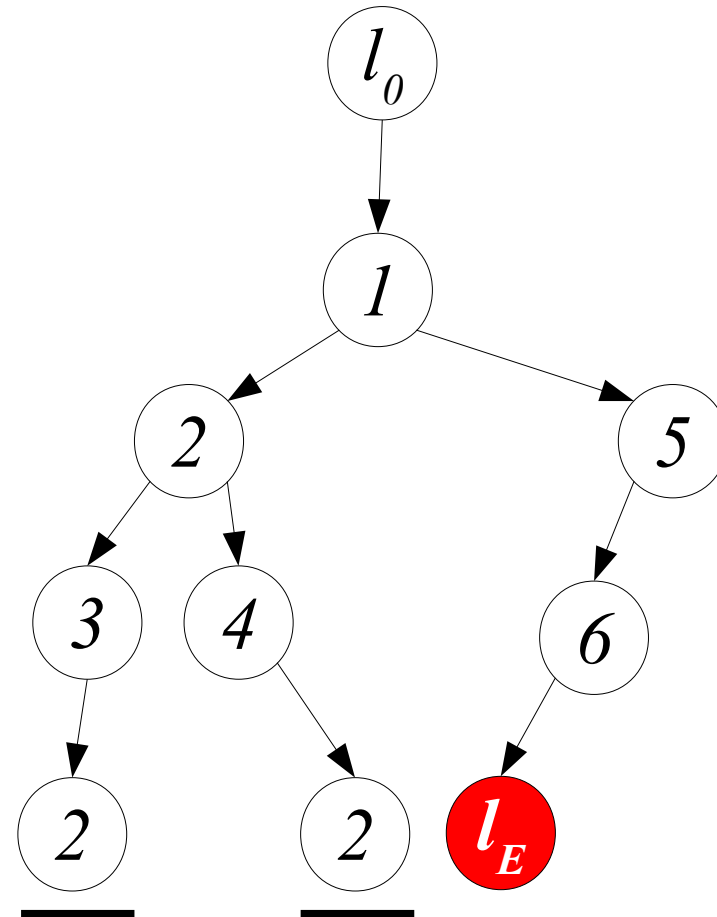
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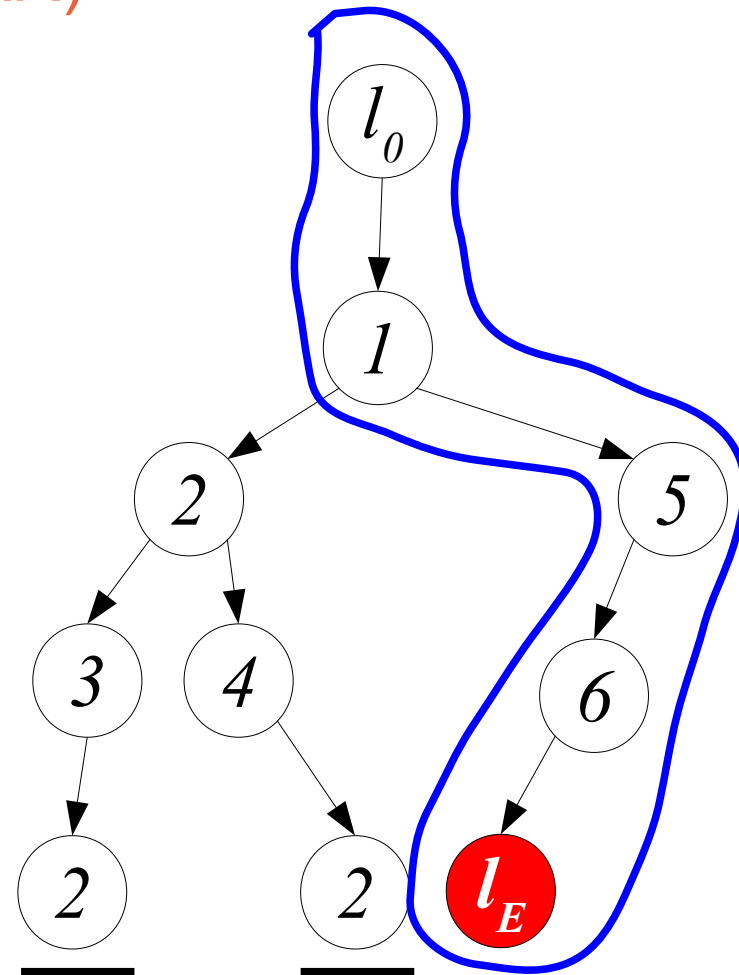
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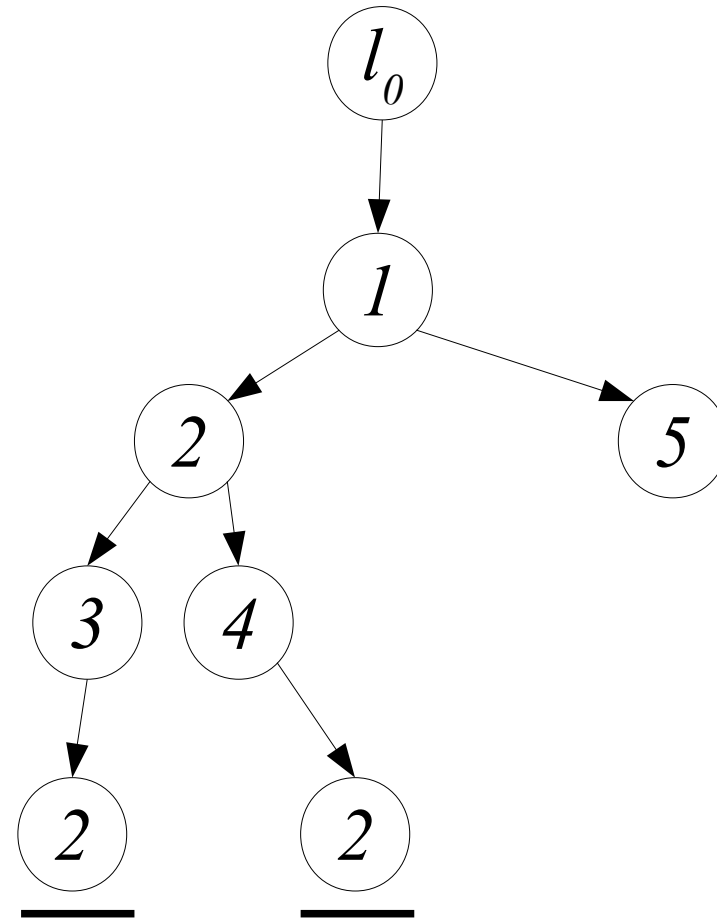
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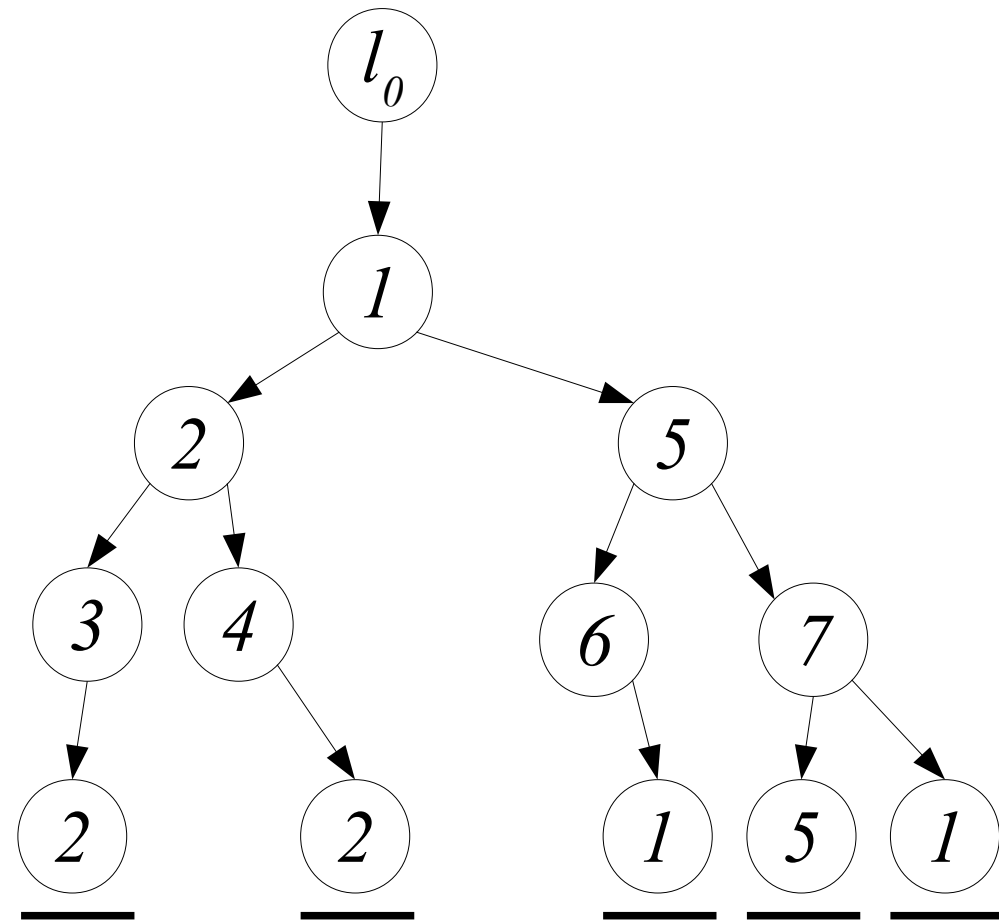
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- ◆ Pick node
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 - ◆ refine abstraction
 - ◆ undo part of the ART
 - ◆ Rebuild subtree
- ◆ **ART safe \Rightarrow Program safe**





Background – Predicate abstraction

- ◆ Abstraction of φ as a Boolean combination of a **set of predicates** P
- ◆ **Boolean abstraction**
 - ◆ $\alpha_P^{\mathbb{B}}(\varphi)$ strongest Boolean combination of P s.t. $\varphi \models \alpha^{\mathbb{B}}(\varphi)$
 - ◆ Expensive to compute
 - ◆ Traditional approach: $2^{|P|}$ calls to a decision procedure
- ◆ **Cartesian abstraction**
 - ◆ $\alpha_P^{\mathbb{C}}(\varphi) = \bigwedge \{p \in P \mid \varphi \models p\} \cup \bigwedge \{\neg p \mid p \in P \text{ and } \varphi \models \neg p\}$
 - ◆ Much cheaper to compute
 - ◆ Much weaker
- ◆ **Abstraction refinement**: add more predicates to P

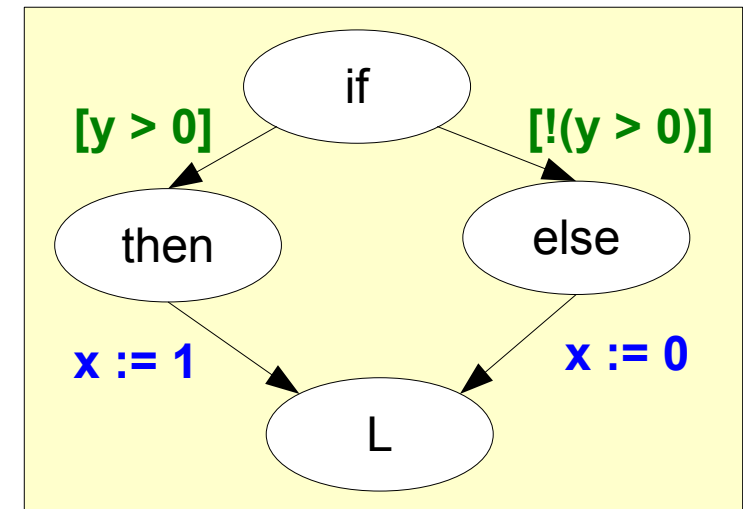
Background – Cartesian vs Boolean abst.



◆ Example

$$\varphi = ((y > 0) \wedge (x = 1)) \vee (\neg(y > 0) \wedge (x = 0))$$

$$P = \{(x = 0), (y = 0)\}$$



Background – Cartesian vs Boolean abst.

- ◆ Example

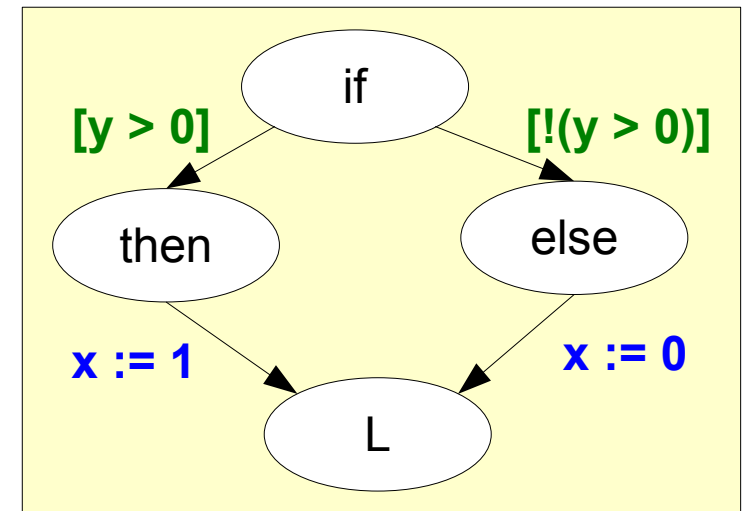
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- ◆ $\alpha_P^C(\varphi) = \top$, since

$$\varphi \not\models (x = 0) \quad \varphi \not\models \neg(x = 0)$$

$$\varphi \not\models (y = 0) \quad \varphi \not\models \neg(y = 0)$$



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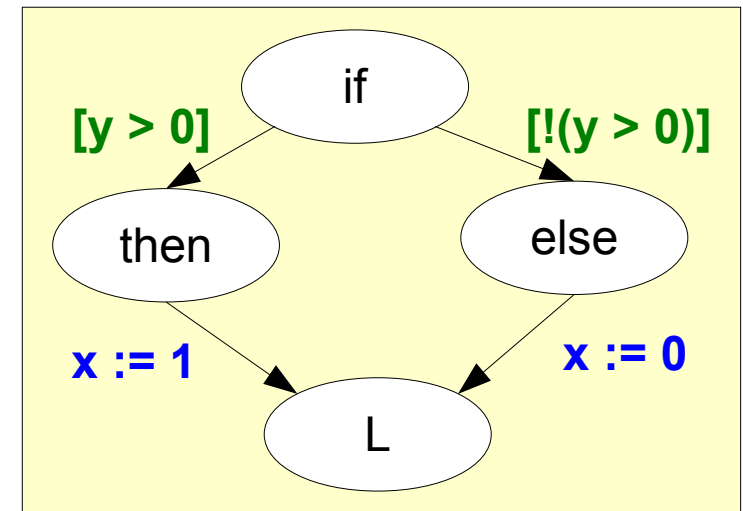
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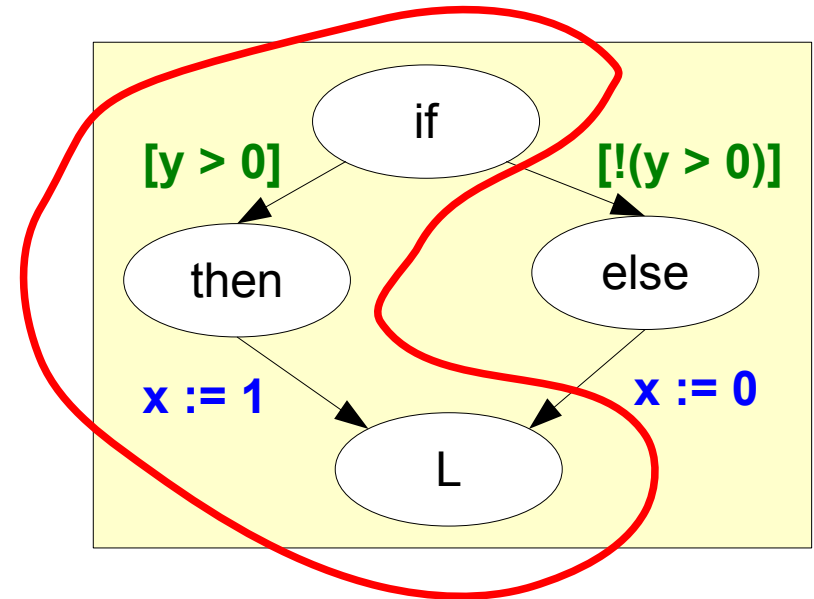
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- ◆ $\alpha_P^{\mathbb{B}}(\varphi) = (y = 0) \rightarrow (x = 0)$

- ◆ However, e.g. for $\varphi_{then} = (y > 0) \wedge (x = 1)$

$$\alpha_P^{\mathbb{C}}(\varphi_{then}) = \alpha_P^{\mathbb{B}}(\varphi_{then}) = \neg(x = 0) \wedge \neg(y = 0)$$



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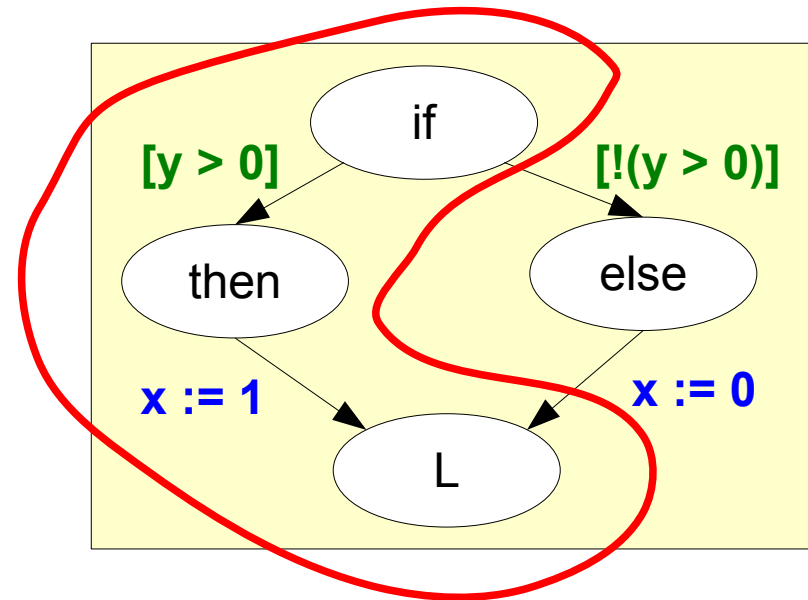
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ART and SMT solvers

- ◆ Using an ART, **reduced cost** in computing abstractions
 - ◆ Separate SP_{op}^{α} computation for each edge (*single block*)
 - ◆ Cartesian abstraction works well in practice
 - ◆ *Consequence: very simple queries to the SMT solver*
- ◆ However, up to **exponential number of paths** to explore *explicitly* in the ART
 - ◆ *Exponentially-many trivial SMT solver calls*

Power, scalability and features of modern SMT solvers
not fully exploited



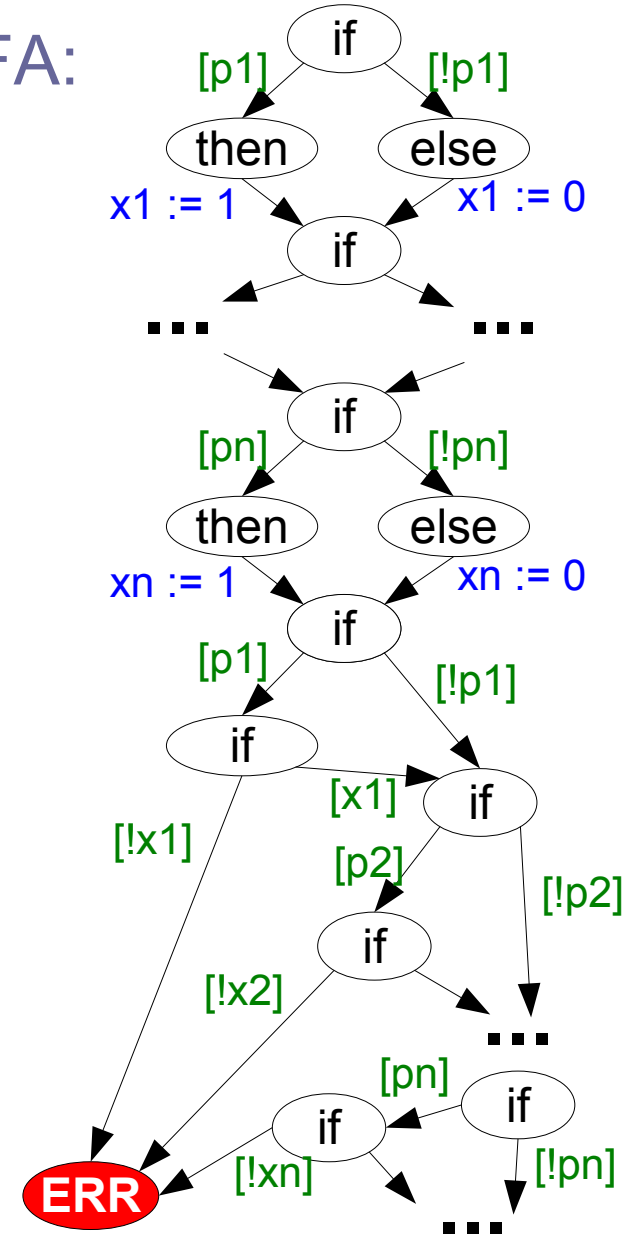
Example of exponential ART

```
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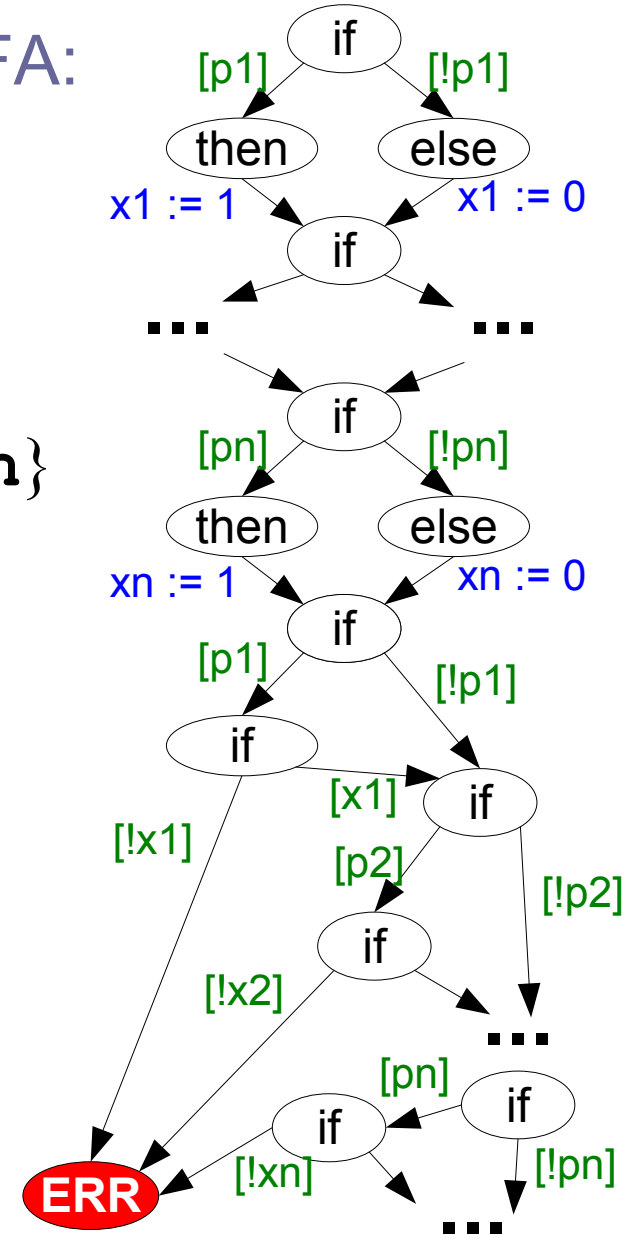
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Preds needed: $\{ (x1=0), \dots, (xn=0), p1, \dots, pn \}$

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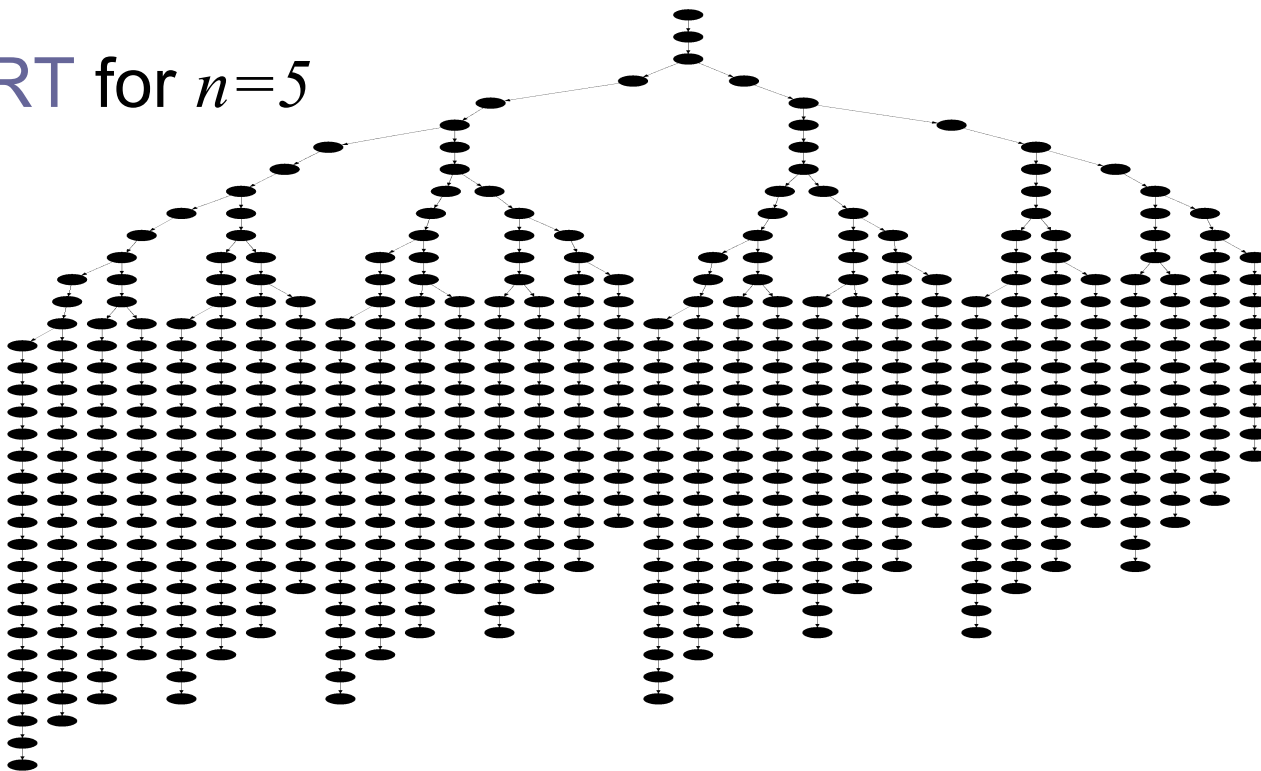
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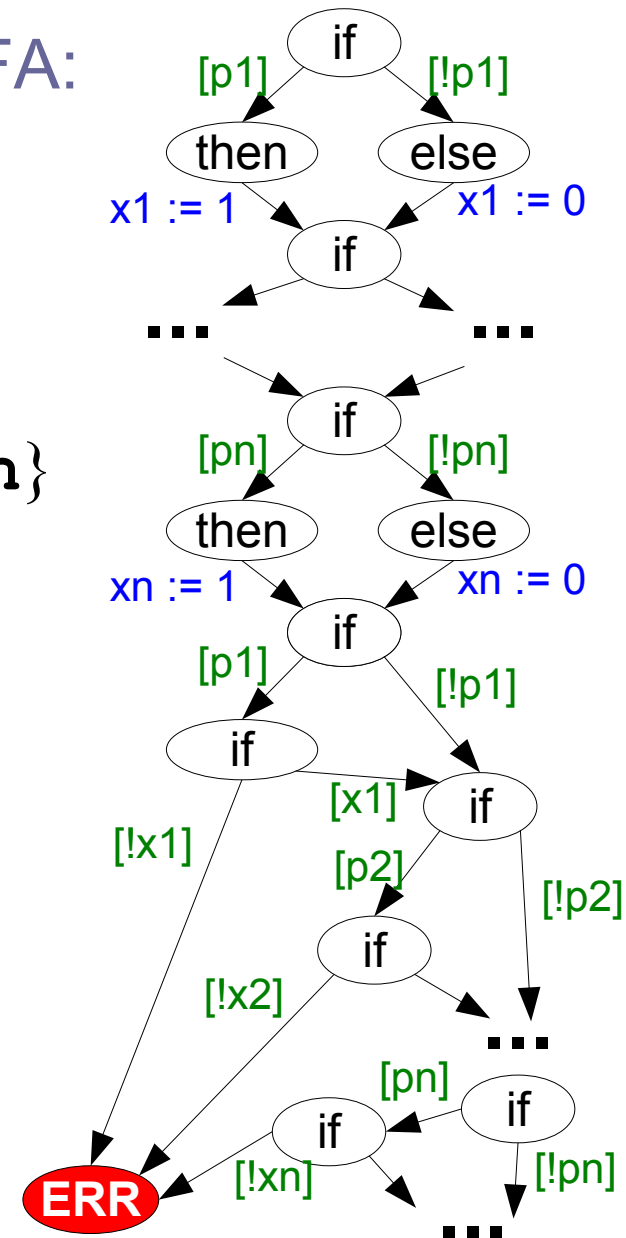
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ART for $n=5$



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Large-Block Encoding

- ◆ *Main idea: use a “more coarse-grained” ART*
 - ◆ No more 1:1 mapping between ART paths and program paths
 - ◆ Each ART edge encodes a loop-free subpart of the program
 - ◆ Each ART path encodes a set of program paths
- ◆ *Consequences:*
 - ◆ reduce size of the ART (up to exponentially)
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Less explicit search, more (symbolic) work for the SMT solver



Large-Block Encoding: implementation

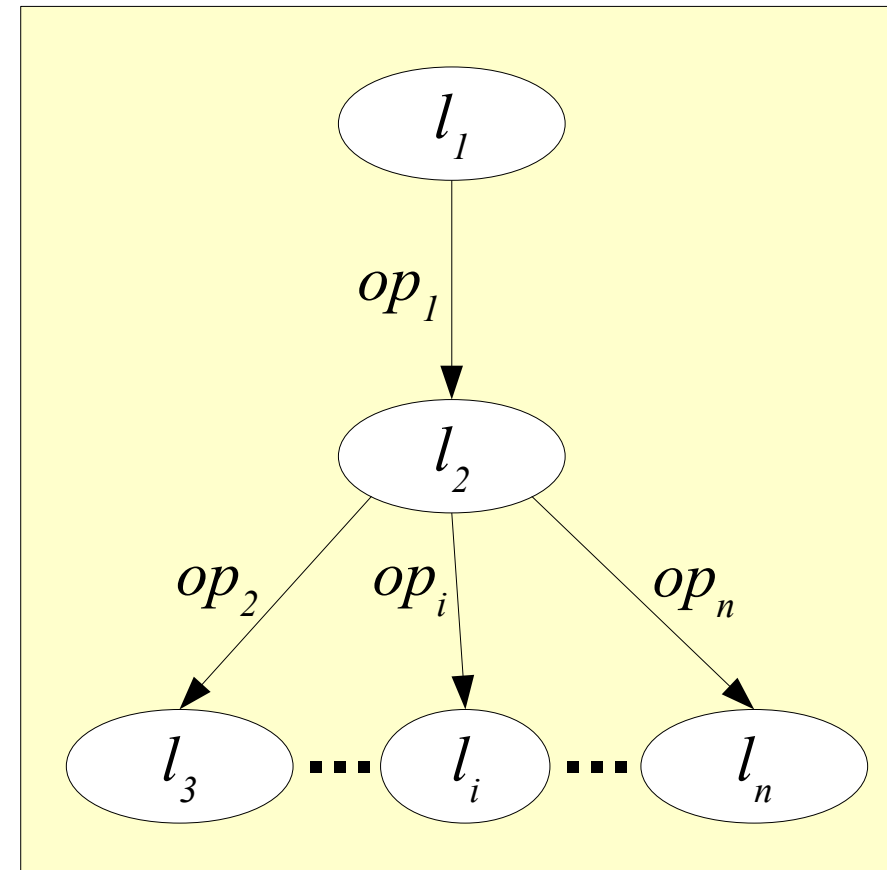
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- ◆ Conditions:
 - ◆ $l_1 \neq l_2$
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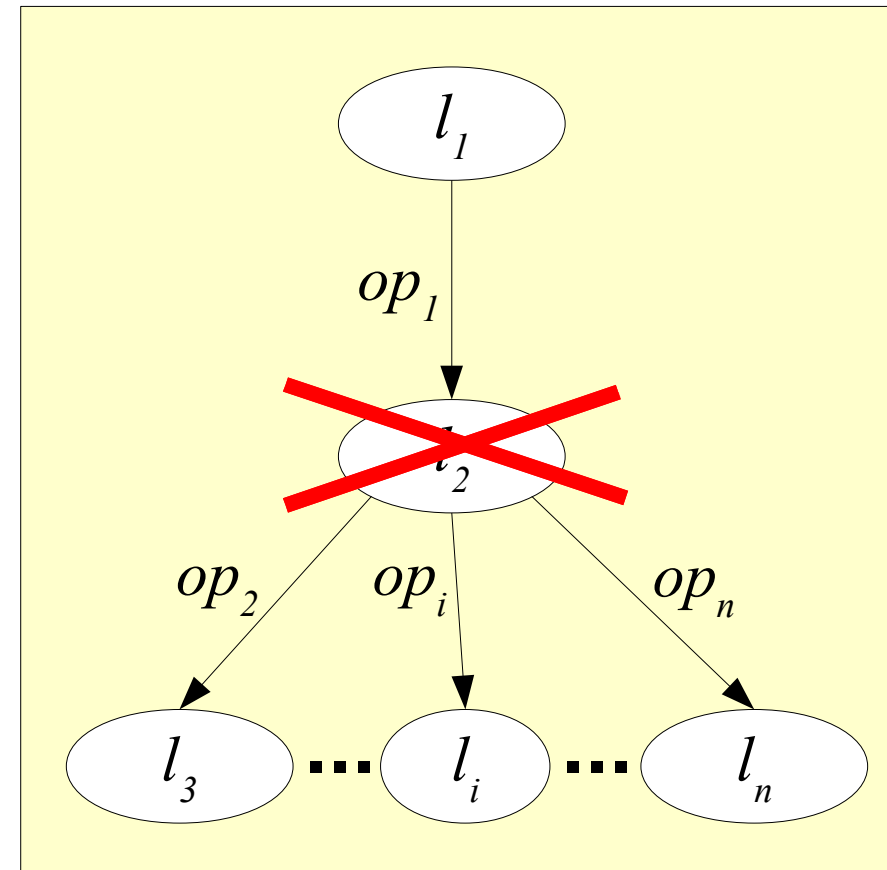


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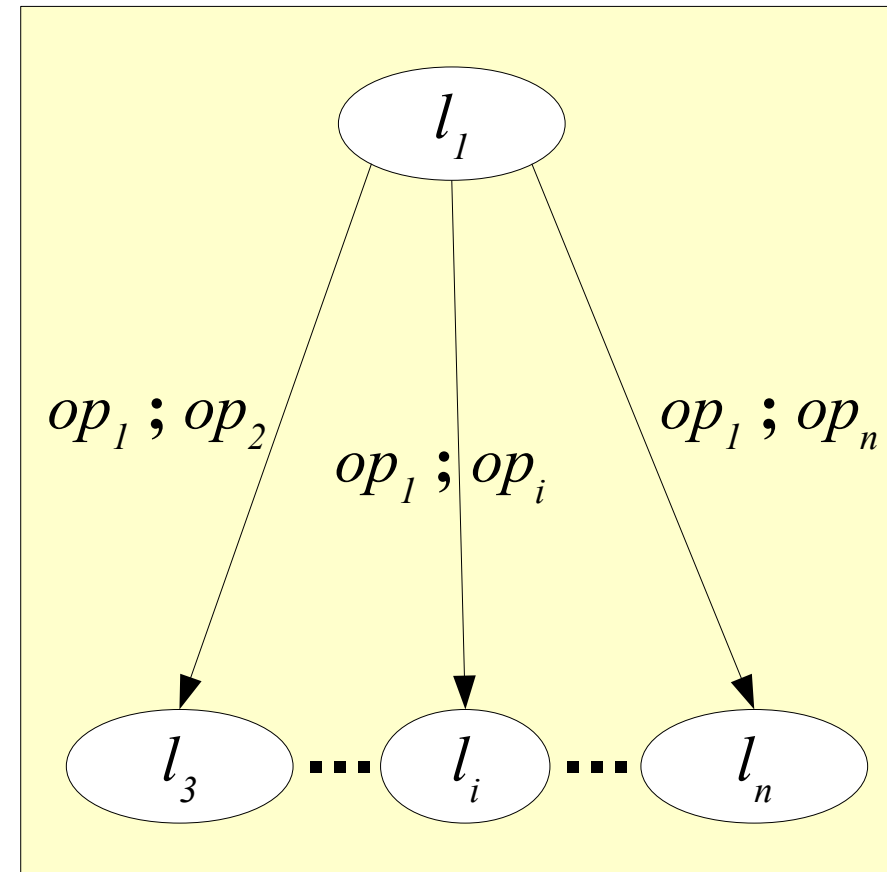
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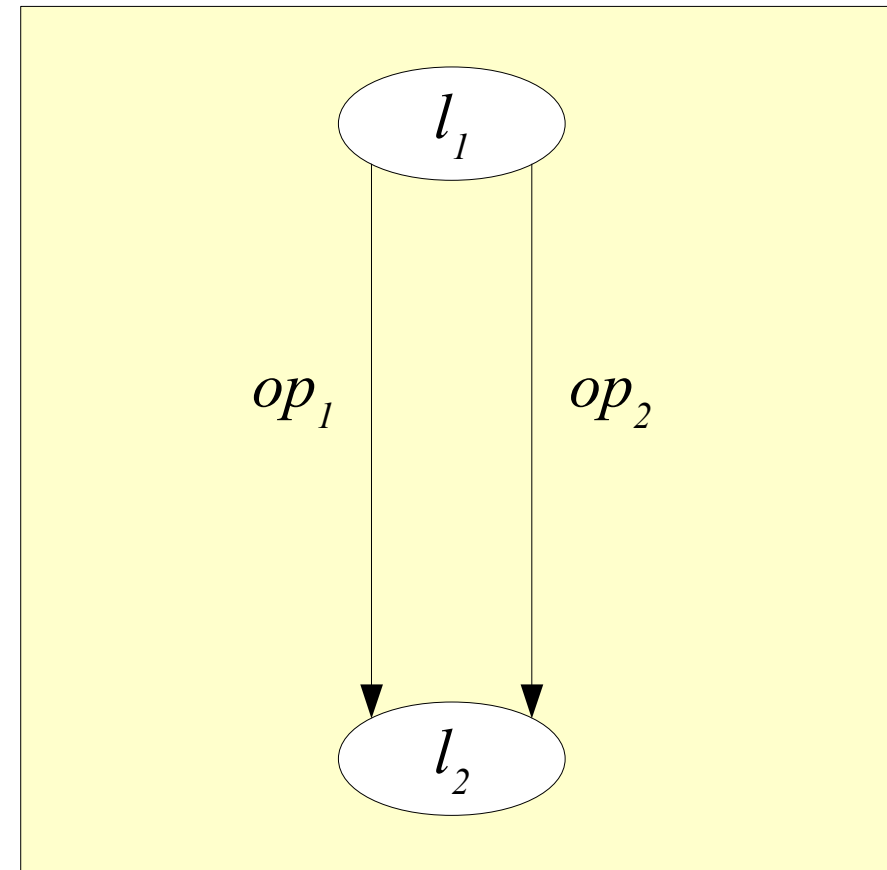
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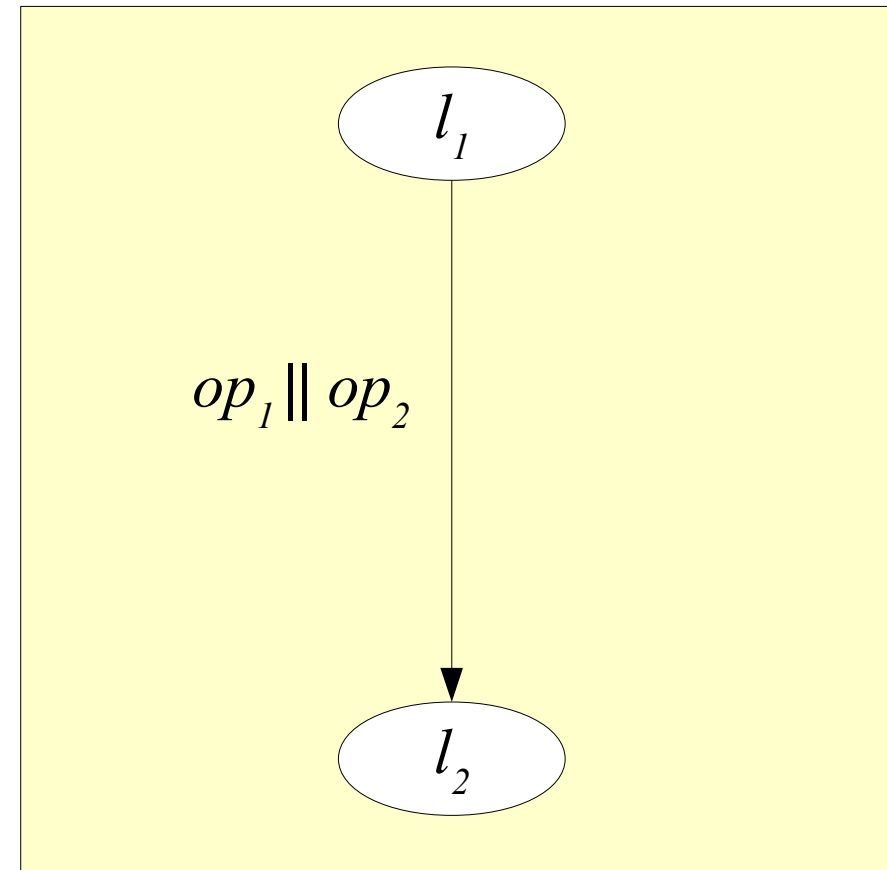


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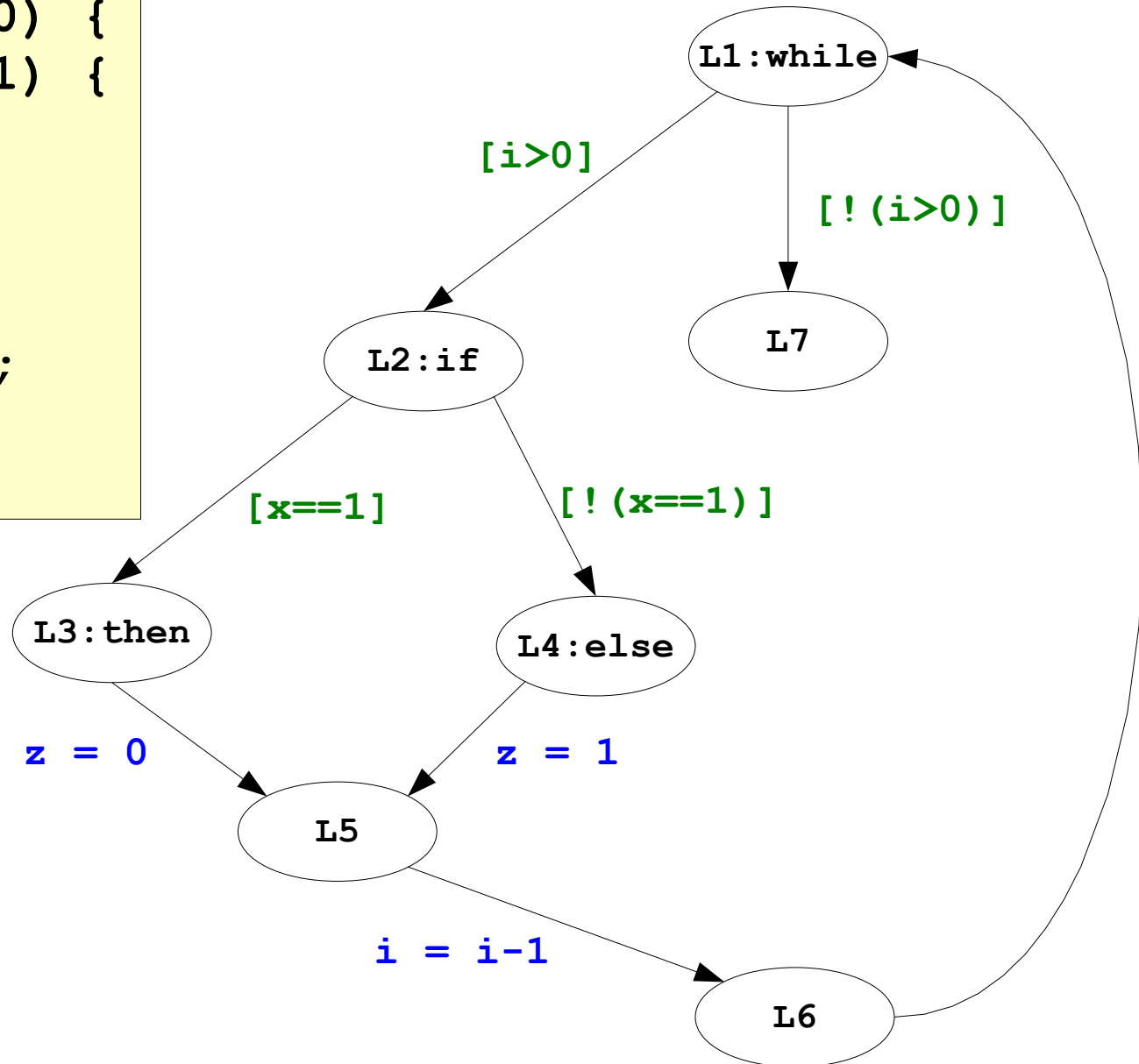
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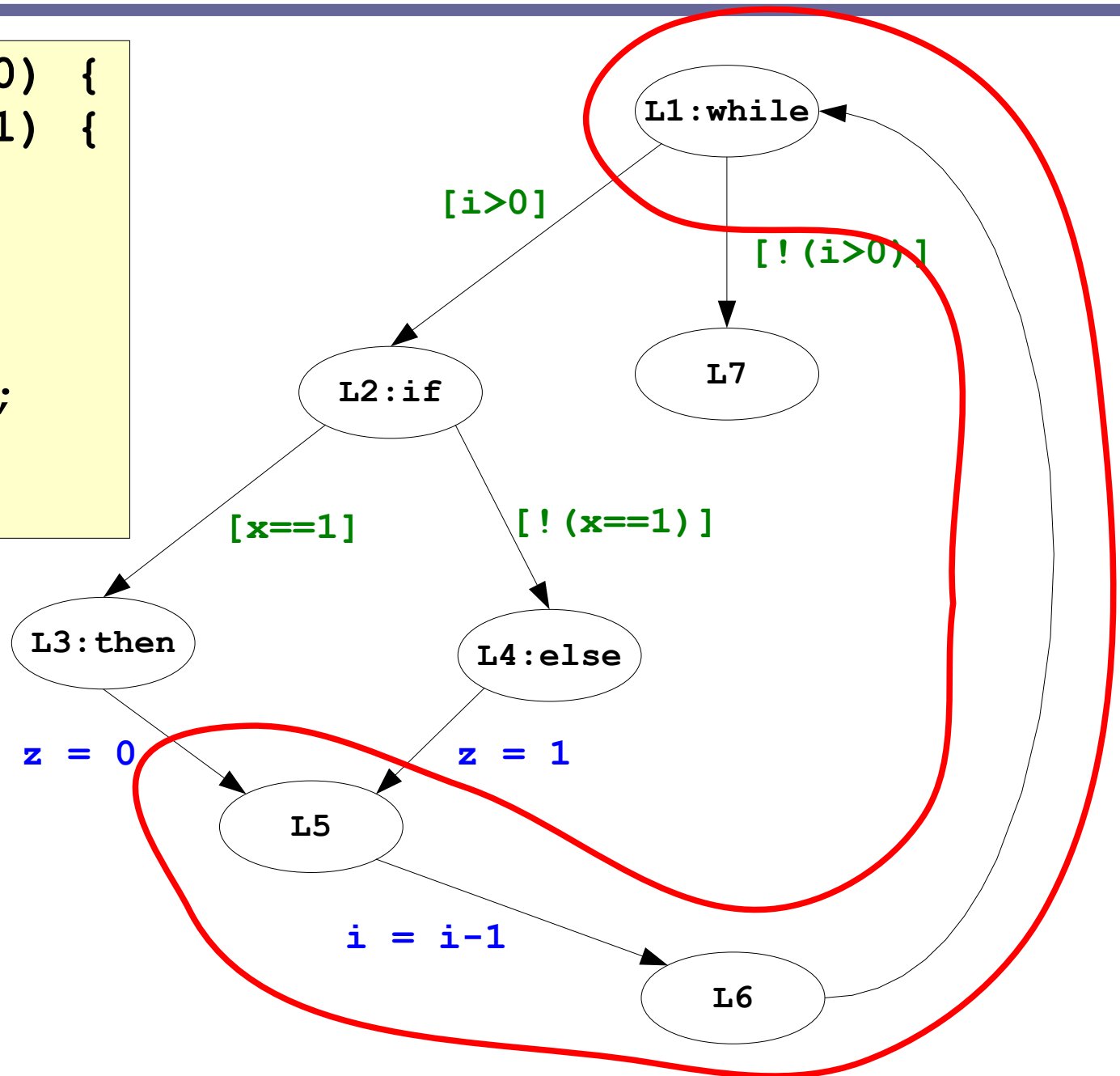
CFA summarization – Example

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L1: while (i > 0) {  
L2:   if (x == 1) {  
L3:     z = 0;  
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L6: }  
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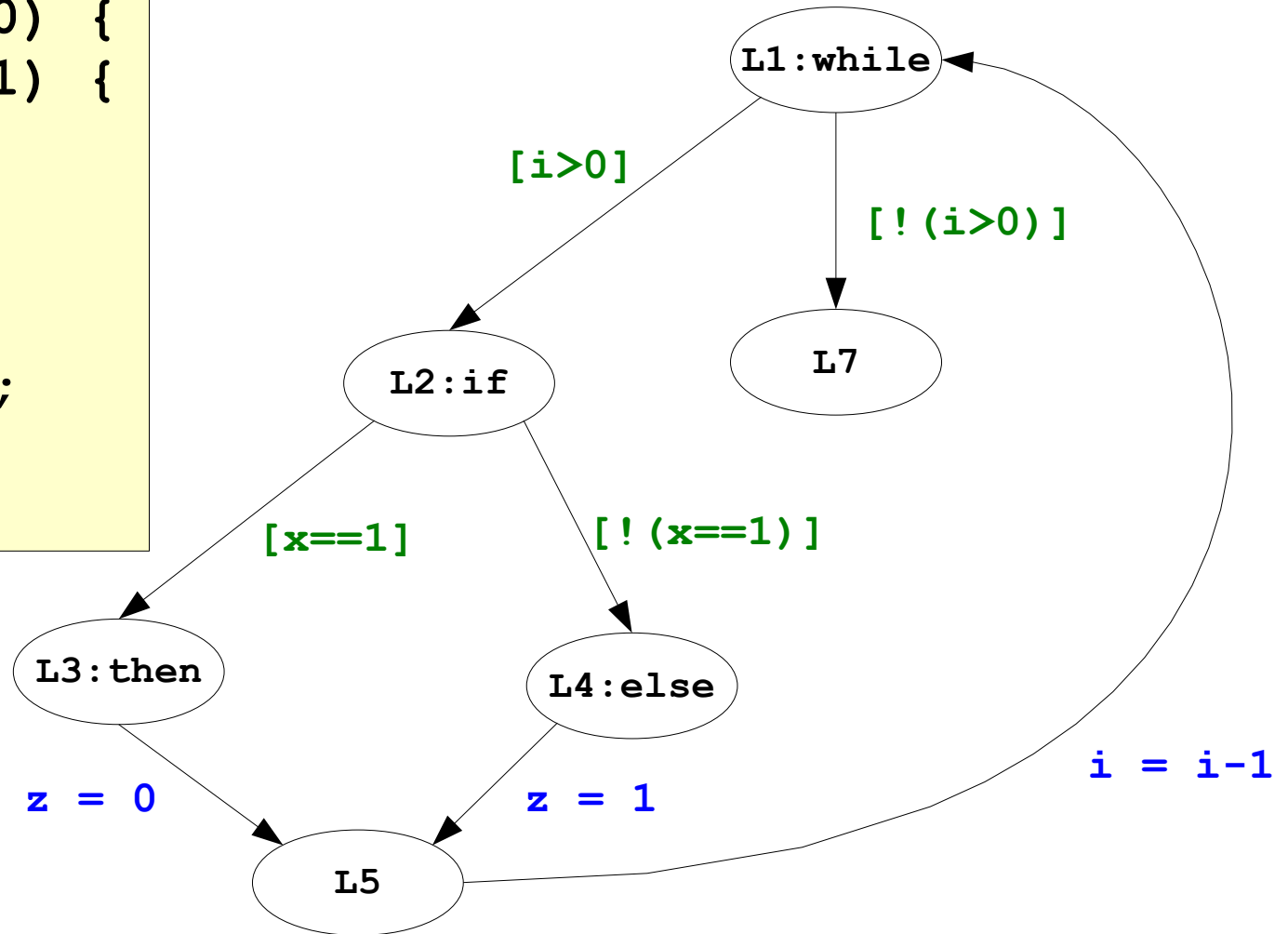
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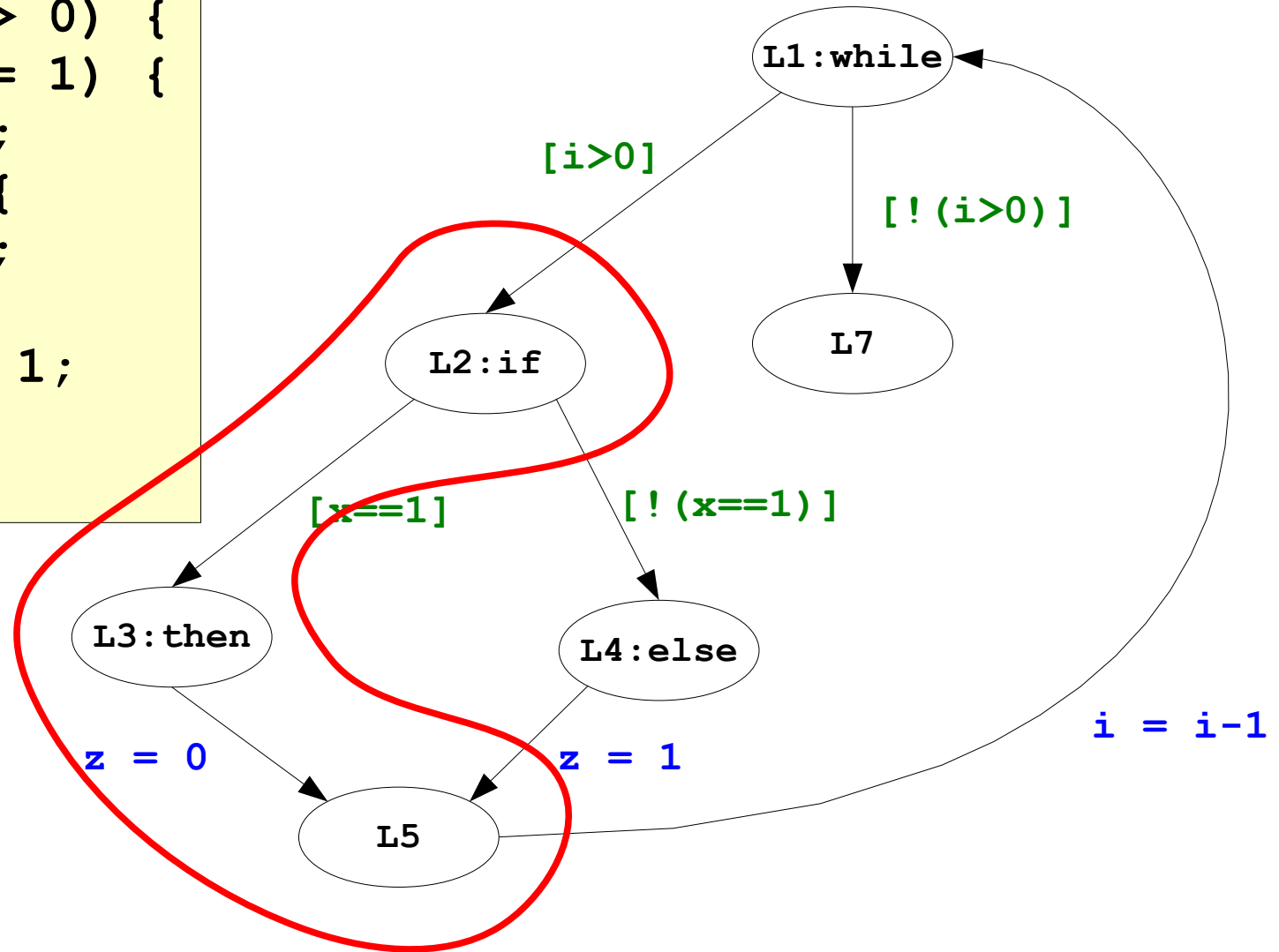
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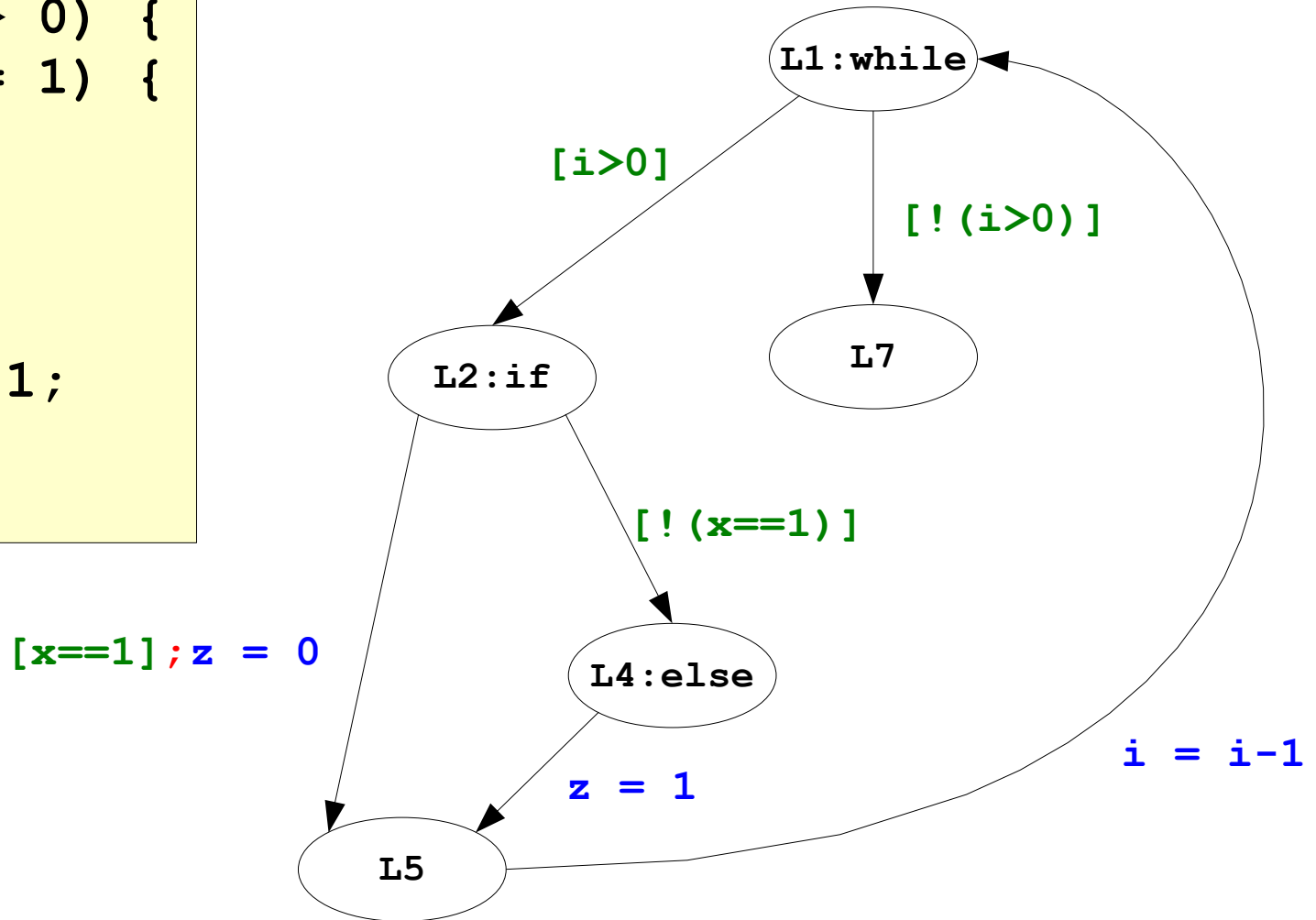
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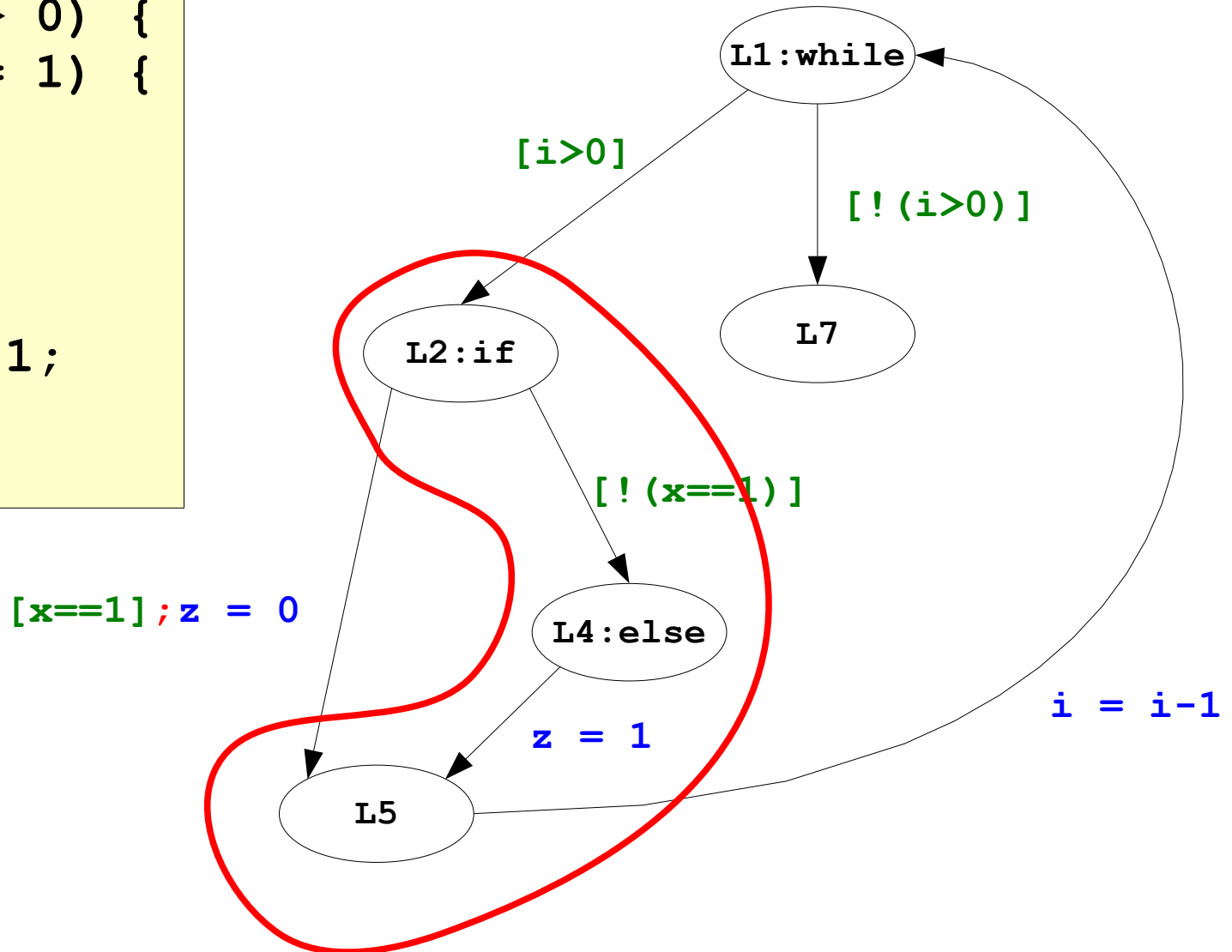
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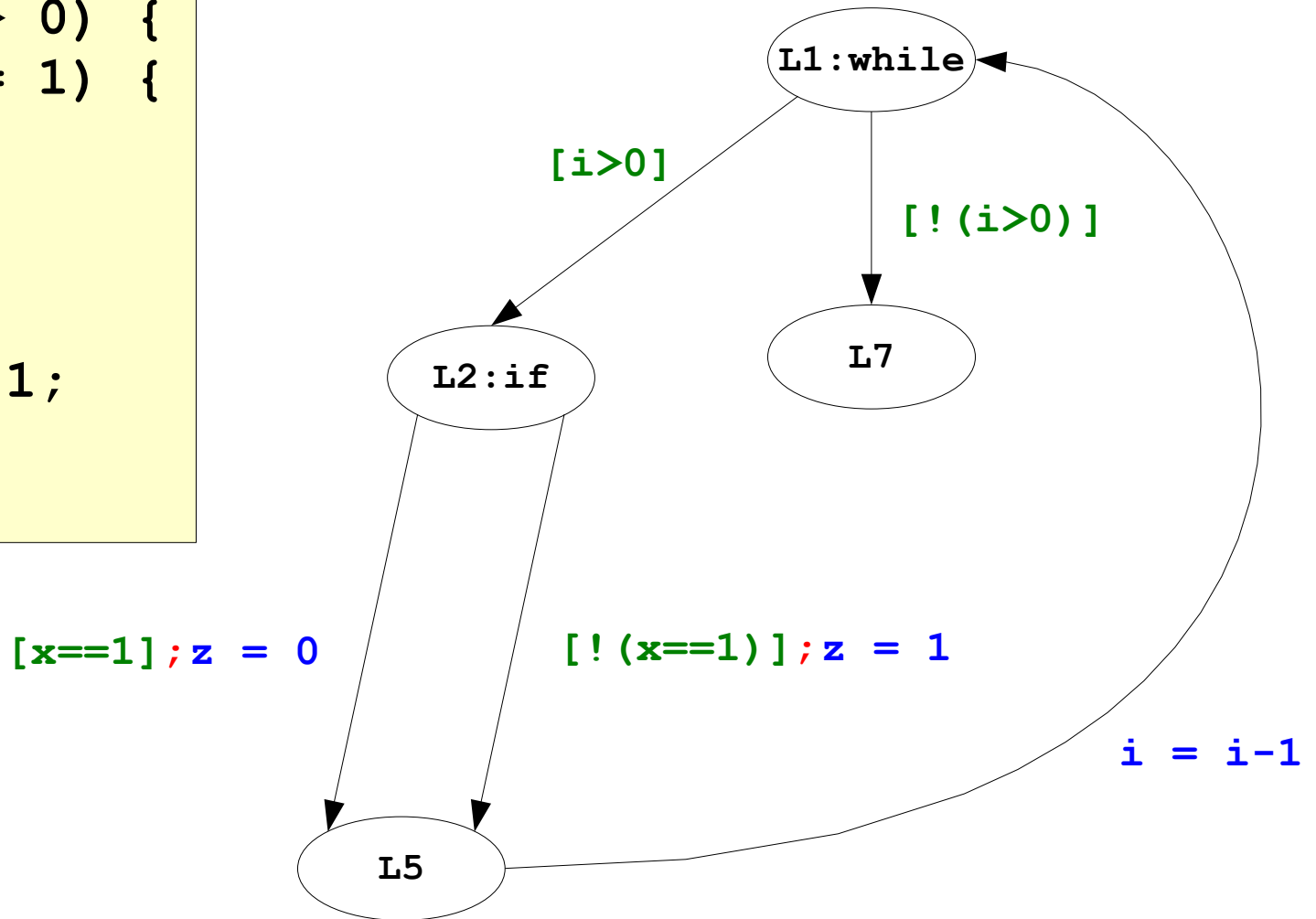
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L8: }
```



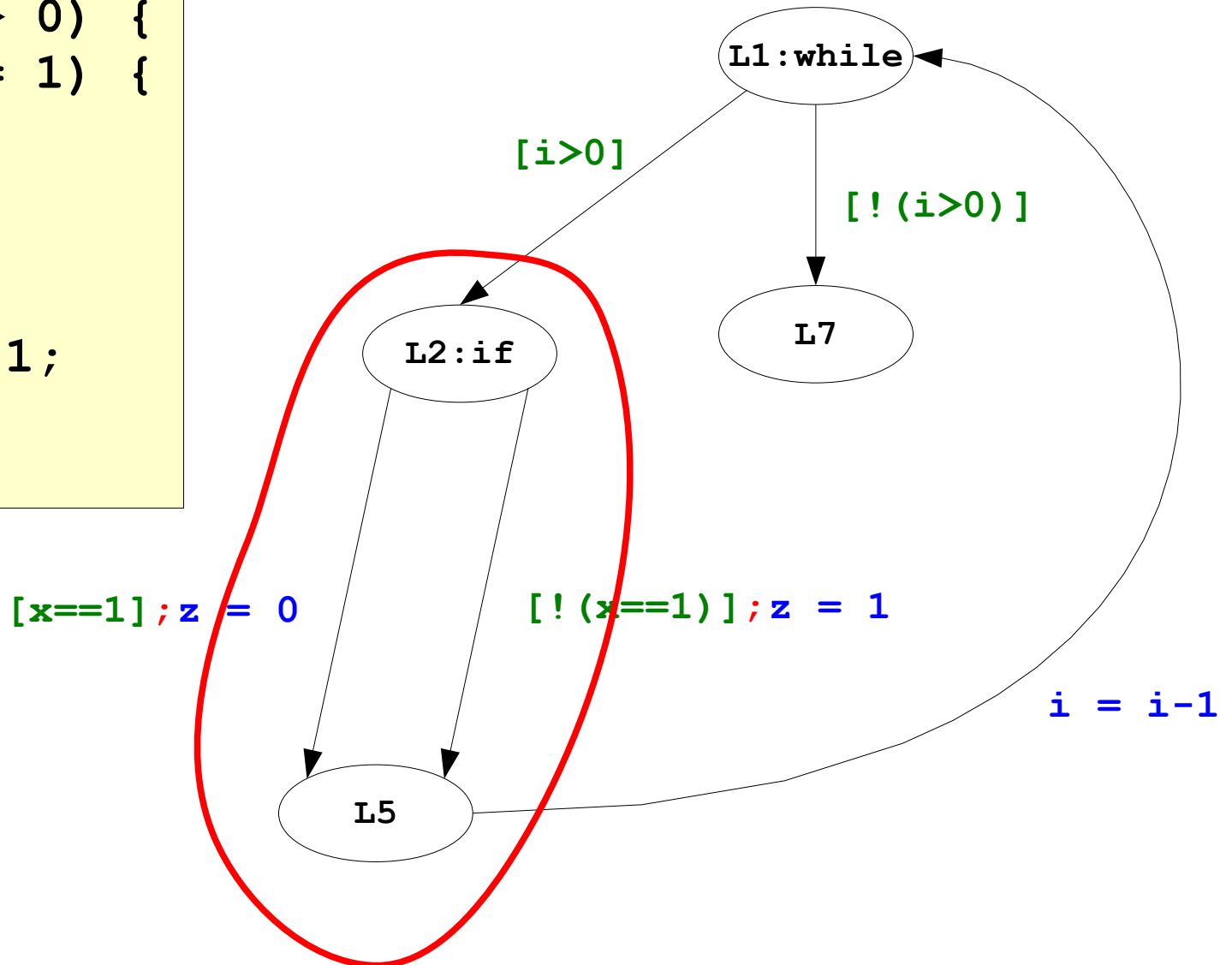
CFA summarization – Example

```
L1: while (i > 0) {  
L2:   if (x == 1) {  
L3:     z = 0;  
L4:   } else {  
L5:     z = 1;  
L6:   }  
L7:   i = i - 1;  
L8: }
```



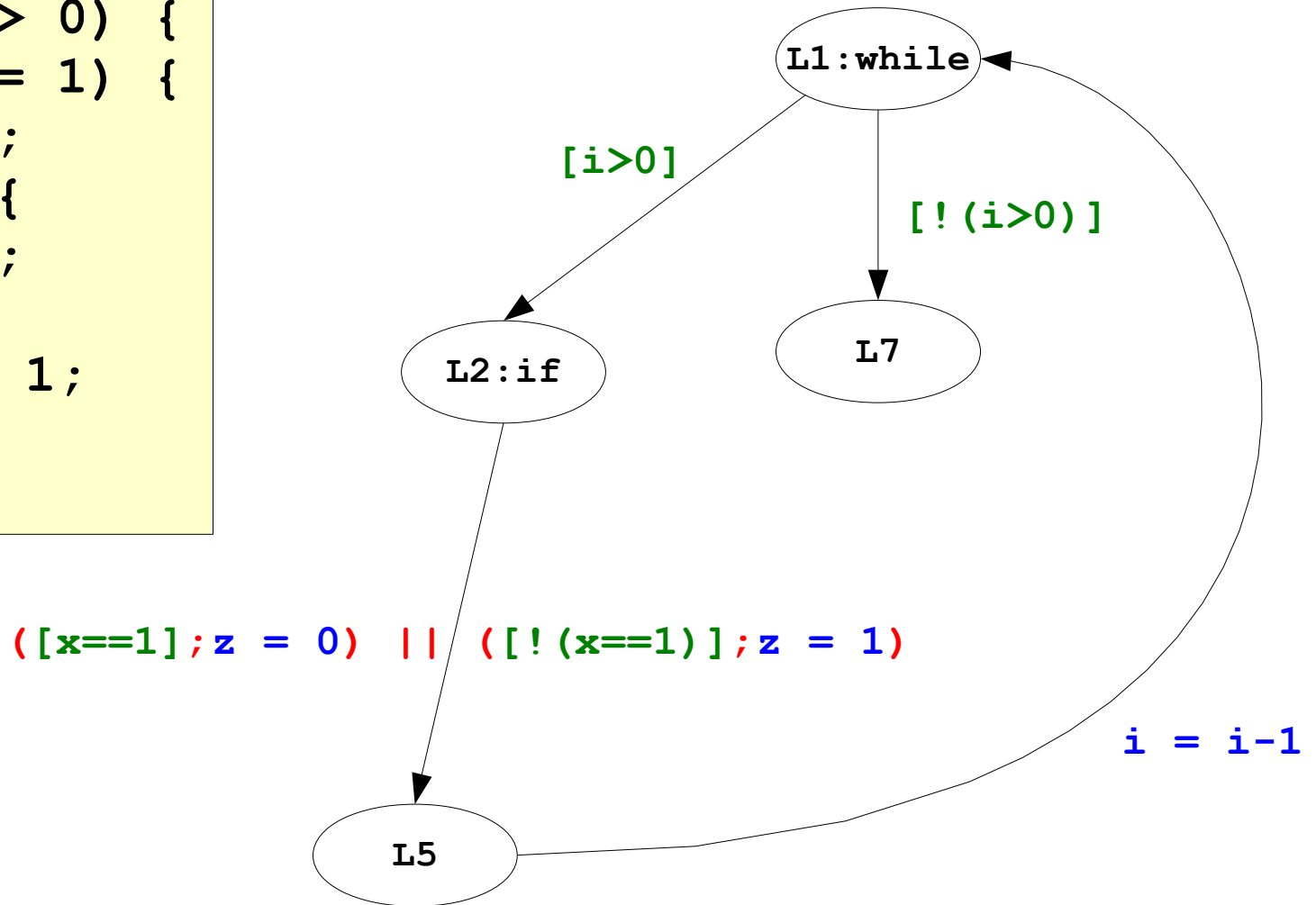
CFA summarization – Example

```
L1: while (i > 0) {  
L2:   if (x == 1) {  
L3:     z = 0;  
L4:   } else {  
L5:     z = 1;  
L6:   }  
L7:   i = i - 1;  
L8: }
```



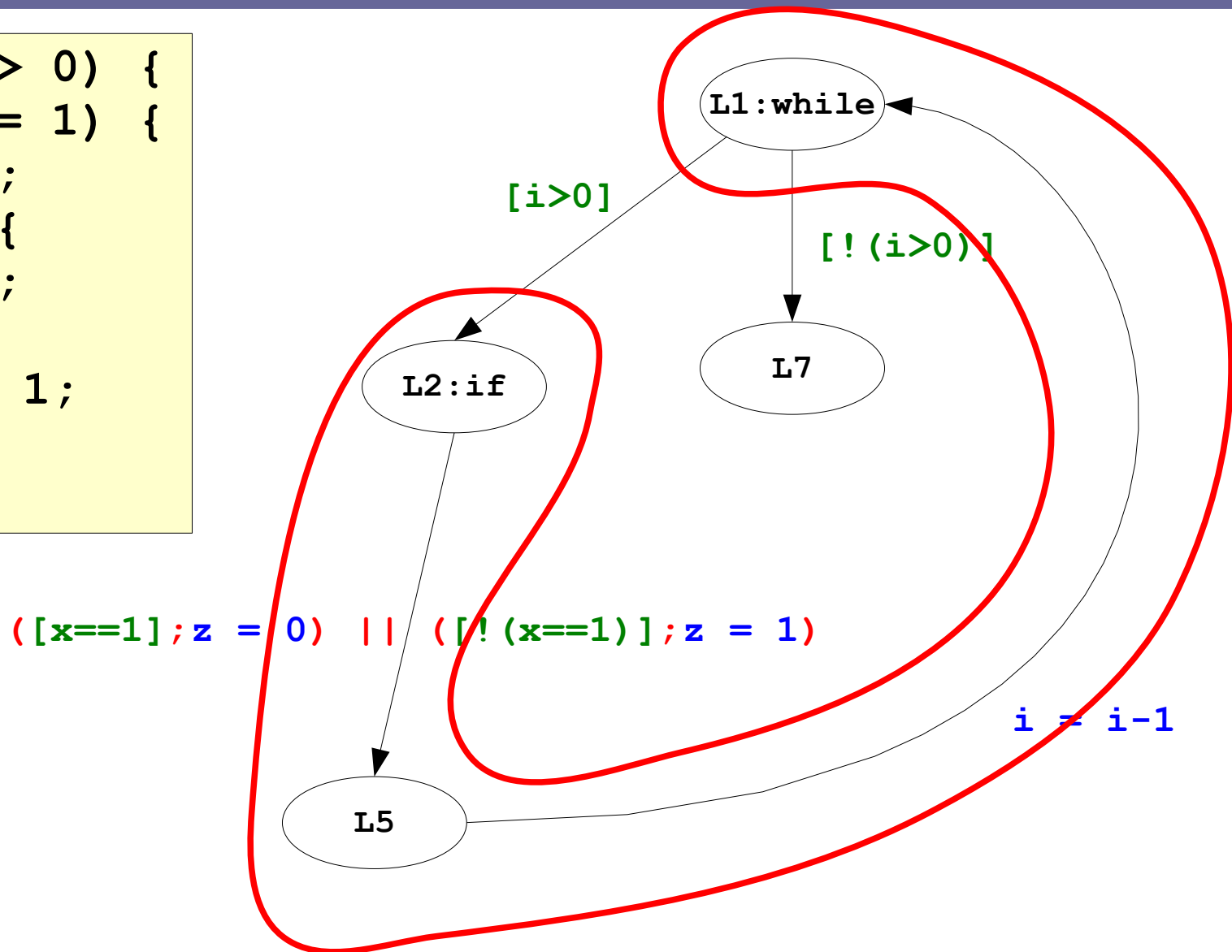
CFA summarization – Example

```
L1: while (i > 0) {  
L2:   if (x == 1) {  
L3:     z = 0;  
L4:   } else {  
L5:     z = 1;  
L6:   }  
L7:   i = i - 1;  
L8: }
```



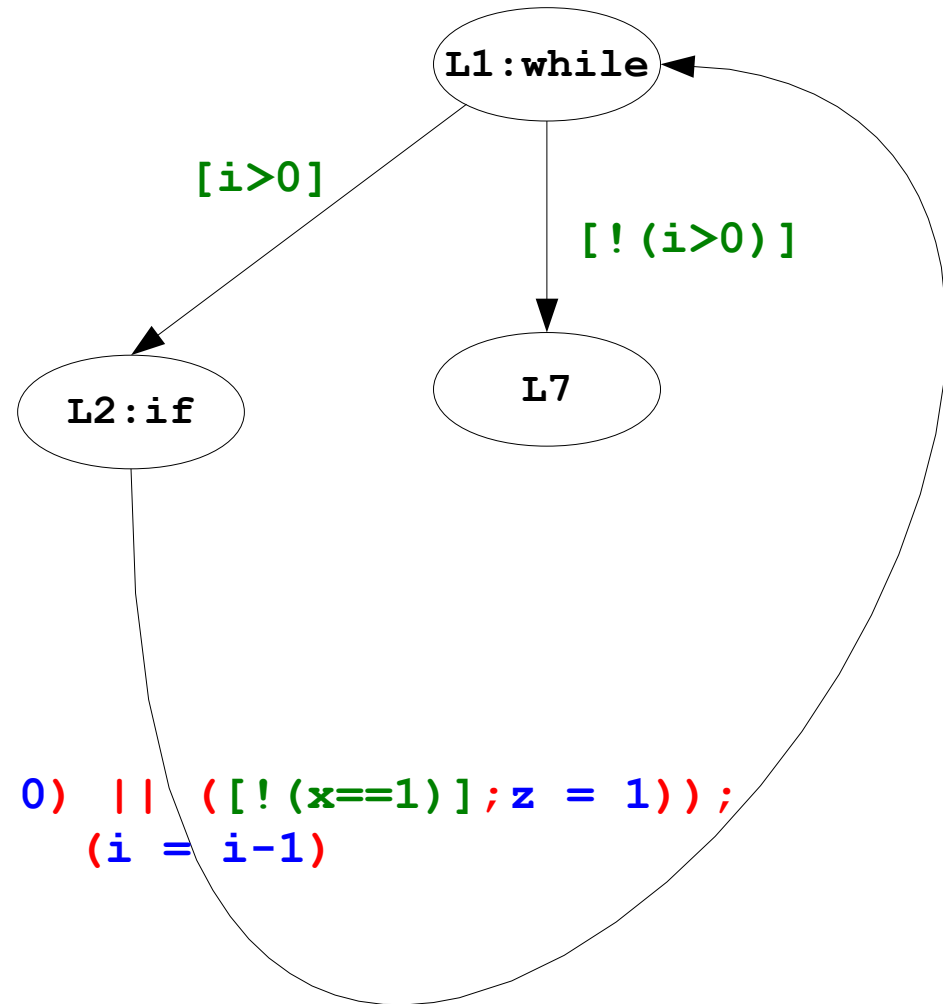
CFA summarization – Example

```
L1: while (i > 0) {  
L2:   if (x == 1) {  
L3:     z = 0;  
L4:   } else {  
L5:     z = 1;  
L6:   }  
L7:   i = i - 1;  
L8: }
```



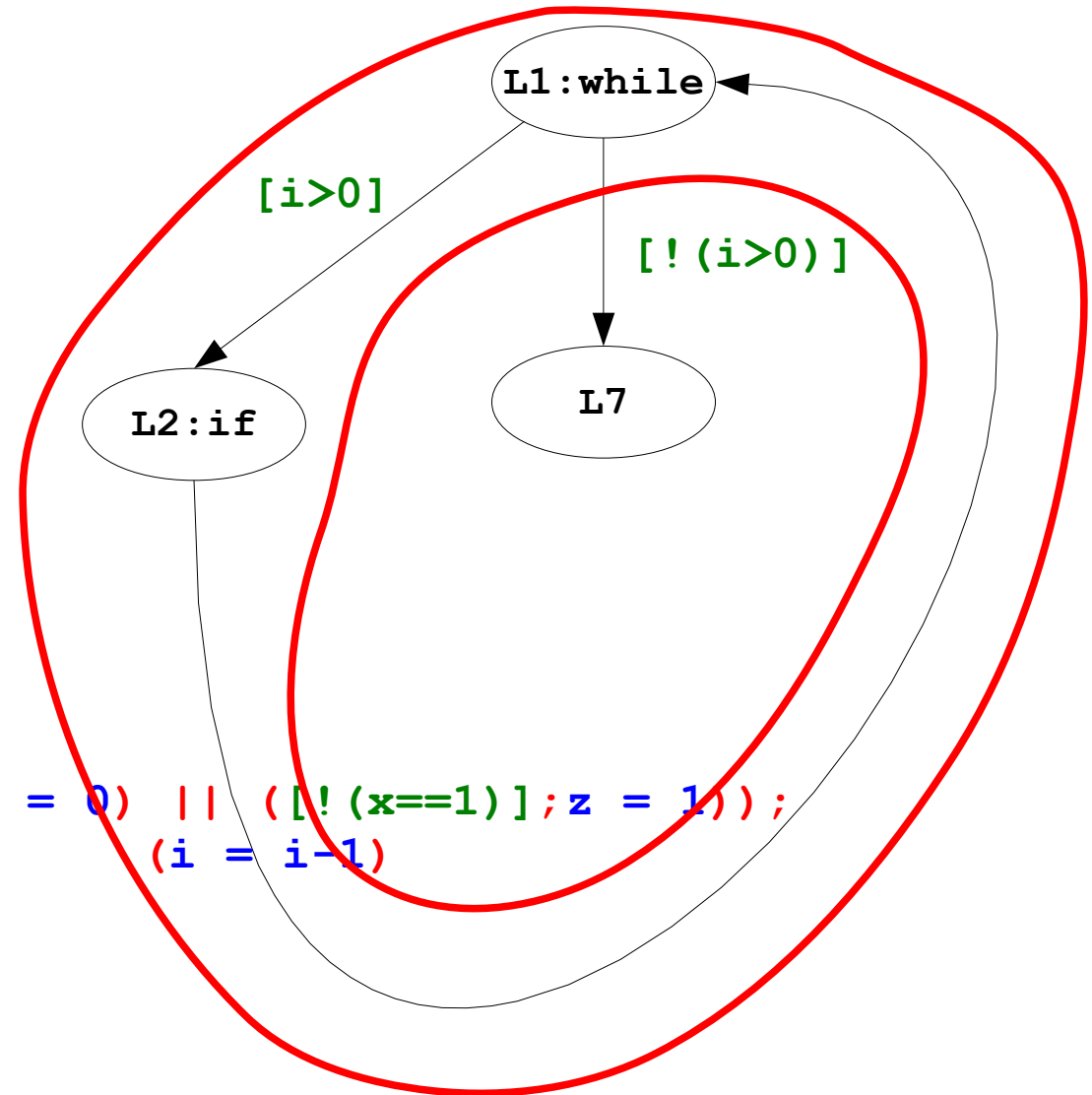
CFA summarization – Example

```
L1: while (i > 0) {  
L2:   if (x == 1) {  
L3:     z = 0;  
L4:   } else {  
L5:     z = 1;  
L6:   }  
L7:   i = i - 1;  
L8: }
```



CFA summarization – Example

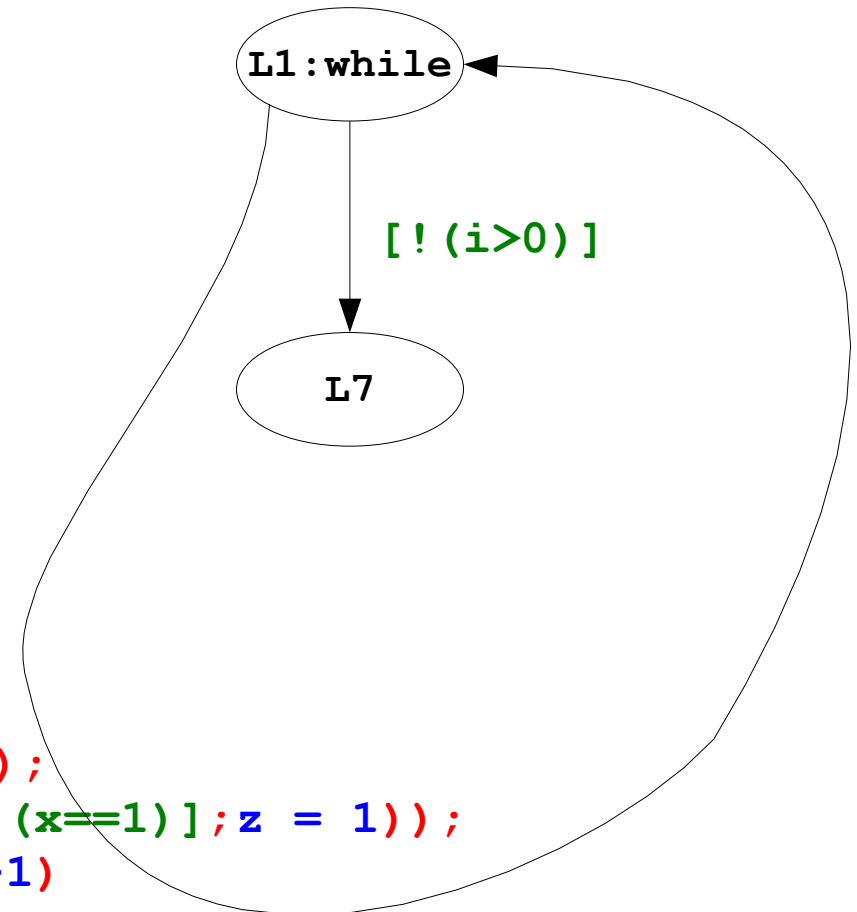
```
L1: while (i > 0) {  
L2:   if (x == 1) {  
L3:     z = 0;  
L4:   } else {  
L5:     z = 1;  
L6:   }  
L7:   i = i - 1;  
L8: }
```



```
(( [x==1] ; z = 0 ) || ( [!(x==1)] ; z = 1 ) ) ;  
( i = i - 1 )
```

CFA summarization – Example

```
L1: while (i > 0) {  
L2:   if (x == 1) {  
L3:     z = 0;  
L4:   } else {  
L5:     z = 1;  
L6:   }  
L7:   i = i - 1;  
L8: }
```



```
([i>0]);  
(( [x==1]; z = 0 ) || ( ![x==1]; z = 1 ));  
(i = i-1)
```



Large blocks and predicate abstraction

- ◆ **With Large-Block Encoding:**
 - ◆ Each edge represents a whole loop-free subpart of a program
 - ◆ ART paths represent sets of program paths
- ◆ **Consequence: Cartesian abstraction can't be used anymore**
 - ◆ Too weak
 - ◆ Need to keep track of dependencies among predicates
- ◆ **In this work: experiment with Boolean abstraction**
 - ◆ Exponential in the worst case, but can exploit recent work in computation of Boolean abstraction with SMT ([Lahiri et al CAV06], [Cavada et al FMCAD07])
 - ◆ Huge progress wrt. previous techniques
- ◆ Cost of the analysis moved from explicit path enumeration to symbolic SP^α computation



Large blocks and abstraction refinement

- ◆ One error trace in the ART corresponds to a set of concrete traces
 - ◆ Complexity increased also for counterexample analysis and abstraction-refinement
 - ◆ With interpolation-based refinement [Henzinger et al POPL04], exploit improvements in Craig interpolant computation with SMT ([Cimatti et al TACAS08, CADE09], [Fuchs et al TACAS09], [Goel et al CADE09])



Outline

- ◆ Background
- ◆ Large-Block Encoding
- ◆ Experimental evaluation



Experimental evaluation

- ◆ **Implementation within CPAchecker**
 - ◆ <http://www.cs.sfu.ca/~dbeyer/cpachecker>
 - ◆ Not only Large-Block Encoding (**LBE**), but also traditional “Single-Block” (**SBE**)
- ◆ **Use MathSAT as SMT backend**
 - ◆ Boolean abstraction via All-SMT, efficient interpolation for refinement
- ◆ **Comparison of CPAchecker-LBE vs**
 - ◆ CPAchecker-SBE
 - ◆ Same language, same infrastructure, ...
 - ◆ BLAST
 - ◆ State-of-the-art ART-based SW MC
 - ◆ 4 different configurations tested



Benchmark instances

- ◆ **test_locks**
 - ◆ Artificial instances that show exponential blowup of ART with SBE
- ◆ **ntdrivers**
 - ◆ Windows NT device drivers
 - ◆ “standard” instances used in previous work
 - ◆ Taken from BLAST distribution
- ◆ **SSH**
 - ◆ Check properties of SSH client and server protocols
 - ◆ Taken from BLAST distribution, used in previous work
- ◆ For ntdrivers and SSH, test also programs with artificial bugs

Results - test_locks



Program	Blast		CPAchecker	
	Best result	-dfs -predH 7	SBE	LBE
test_locks5.c	4.50	4.96	4.01	0.29
test_locks6.c	7.81	8.81	7.22	0.34
test_locks7.c	13.91	15.15	12.63	0.34
test_locks8.c	25.00	26.49	23.93	0.57
test_locks9.c	46.84	49.29	52.04	0.38
test_locks10.c	94.57	97.85	131.39	0.40
test_locks11.c	204.55	208.78	MO	0.70
test_locks12.c	529.16	533.97	MO	0.46
test_locks13.c	1229.27	1232.87	MO	0.49
test_locks14.c	>1800.00	>1800.00	MO	0.50
test_locks15.c	>1800.00	>1800.00	MO	0.29
TOTAL	9 / 2155.61	9 / 2178.17	6 / 231.22	11 / 4.76



Results - test_locks

Program	Blast		CPAchecker	
	Best result	-dfs -predH 7	SBE	LBE
test_locks5.c	4.50	4.96	4.01	0.29
test_locks6.c	7.81	8.81	7.22	0.34
test_locks7.c	13.91	15.15	12.63	0.34
test_locks8.c	25.00	26.49	23.93	0.57
test_locks9.c	9.29	9.29	52.04	0.38
test_locks10.c	7.85	7.85	131.39	0.40
test_locks11.c	8.78	8.78	MO	0.70
test_locks12.c	529.16	533.97	MO	0.46
test_locks13.c	1229.27	1232.87	MO	0.49
test_locks14.c	>1800.00	>1800.00	MO	0.50
test_locks15.c	>1800.00	>1800.00	MO	0.29
TOTAL	9 / 2155.61	9 / 2178.17	6 / 231.22	11 / 4.76

2 more instances,
>500x faster



Results – ntdrivers and SSH – safe

Program	Blast		CPAchecker	
	Best result	-dfs -predH 7	SBE	LBE
cdaudio	175.76	264.12	MO	53.55
diskperf	>1800.00	>1800.00	MO	232.00
floppy	218.26	>1800.00	MO	56.36
kbfiltr	23.55	32.80	41.12	7.82
parport	738.82	915.79	MO	378.04
s3_clnt.01	33.01	1000.41	755.81	19.51
s3_clnt.02	62.65	312.77	1075.45	16.00
s3_clnt.03	60.62	314.74	746.31	49.50
s3_clnt.04	63.96	197.65	730.80	25.45
s3_srvr.01	811.27	1036.89	>1800.00	125.33
s3_srvr.02	360.47	360.47	>1800.00	122.83
s3_srvr.03	276.19	276.19	>1800.00	98.47
s3_srvr.04	175.64	301.85	>1800.00	71.77
s3_srvr.06	304.63	304.63	>1800.00	59.70
s3_srvr.07	478.05	666.53	>1800.00	85.82
s3_srvr.08	115.76	115.76	>1800.00	61.29
s3_srvr.09	445.21	1037.09	>1800.00	126.47
s3_srvr.10	115.10	115.10	>1800.00	63.36
s3_srvr.11	367.98	844.28	>1800.00	162.76
s3_srvr.12	304.05	304.05	>1800.00	170.33
s3_srvr.13	580.33	878.54	>1800.00	74.49
s3_srvr.14	303.21	303.21	>1800.00	50.38
s3_srvr.15	115.88	115.88	>1800.00	21.01
s3_srvr.16	305.11	305.11	>1800.00	127.82
TOTAL	23 / 6435.51	22 / 10003.06	5 / 3349.48	24 / 2260.07



Results – ntdrivers and SSH – safe

Program	Blast		CPAchecker	
	Best result	-dfs -predH 7	SBE	LBE
cdaudio	175.76	264.12	MO	53.55
diskperf	>1800.00	>1800.00	MO	232.00
floppy	218.26	>1800.00	MO	56.36
kbfiltr	23.55	32.80	41.12	7.82
parport	738.82	915.79	MO	378.04
s3_clnt.01	33.01	1000.41	755.81	19.51
s3_clnt.02	62.65	312.77	1075.45	16.00
s3_clnt.03	60.62	314.74	746.31	49.50
s3_clnt.04	63.96	197.65	730.80	25.45
s3_srvr.01	811.27	1036.89	>1800.00	125.33
s3_srvr.02	360.47	360.47	>1800.00	122.83
s3_srvr.03	276.19	276.19	>1800.00	98.47
s3_srvr.04	175.64	301.85	>1800.00	71.77
s3_srvr.06	4.63	>1800.00	>1800.00	59.70
s3_srvr.07	6.53	>1800.00	>1800.00	85.82
s3_srvr.08	5.76	>1800.00	>1800.00	61.29
s3_srvr.09	7.09	>1800.00	>1800.00	126.47
s3_srvr.10	115.10	115.10	>1800.00	63.36
s3_srvr.11	367.98	344.28	>1800.00	162.76
s3_srvr.12	304.05	304.05	>1800.00	170.33
s3_srvr.13	580.33	878.54	>1800.00	74.49
s3_srvr.14	303.21	303.21	>1800.00	50.38
s3_srvr.15	115.88	115.88	>1800.00	21.01
s3_srvr.16	305.11	305.11	>1800.00	127.82
TOTAL	23 / 6435.51	22 / 10003.06	5 / 3349.40	24 / 2260.07

1 more instance,
~3.2x faster



Results – ntdrivers and SSH – safe

Program	Blast		CPAchecker	
	Best result	-dfs -predH 7	SBE	LBE
cdaudio	175.76	264.12	MO	53.55
diskperf	>1800.00	>1800.00	MO	232.00
floppy	218.26	>1800.00	MO	56.36
kbfiltr	23.55	32.80	41.12	7.82
parport	738.82	915.79	MO	378.04
s3_clnt.01	33.01	1000.41	755.81	19.51
s3_clnt.02	62.65	312.77	1075.45	16.00
s3_clnt.03	60.62	314.74	746.31	49.50
s3_clnt.04	63.96	197.65	730.80	25.45
s3_srvr.01	811.27	1036.89	>1800.00	125.33
s3_srvr.02	360.47	360.47	>1800.00	122.83
s3_srvr.03	276.19	276.19	>1800.00	98.47
s3_srvr.04	175.64	301.85	>1800.00	71.77
s3_srvr.06	4.63	>1800.00	>1800.00	59.70
s3_srvr.07	6.53	>1800.00	>1800.00	85.82
s3_srvr.08	5.76	>1800.00	>1800.00	61.29
s3_srvr.09	7.09	>1800.00	>1800.00	126.47
s3_srvr.10	115.10	115.10	>1800.00	63.36
s3_srvr.11	367.98	344.28	>1800.00	162.76
s3_srvr.12	304.05	304.05	>1800.00	170.33
s3_srvr.13	530.33	878.54	>1800.00	74.49
s3_srvr.14	303.21	303.21	>1800.00	50.38
s3_srvr.15	115.88	115.88	>1800.00	21.01
s3_srvr.16	305.11	305.11	>1800.00	127.82
TOTAL	23 / 6435.51	22 / 10003.06	5 / 3349.48	24 / 2260.07

2 more instances,
~5x faster



Results – ntdrivers and SSH – unsafe

Program	Blast		CPAchecker	
	Best result	-bfs -predH 7	SBE	LBE
cdaudio	18.79	99.82	74.39	9.85
diskperf	889.79	>1800.00	26.53	6.78
floppy	119.60	>1800.00	36.49	4.30
kbfiltr	46.80	144.25	75.45	11.52
parport	1.67	10.95	14.62	2.64
s3_clnt.01	8.84	28.30	1514.90	3.33
s3_clnt.02	9.02	9.02	843.42	3.27
s3_clnt.03	6.64	6.64	780.72	2.61
s3_clnt.04	9.78	9.78	724.04	3.18
s3_srvr.01	7.59	7.59	MO	2.09
s3_srvr.02	7.16	7.16	>1800.00	2.10
s3_srvr.03	7.42	7.42	>1800.00	2.08
s3_srvr.04	7.33	7.33	>1800.00	1.93
s3_srvr.06	39.81	56.11	MO	5.08
s3_srvr.07	310.84	310.84	>1800.00	28.35
s3_srvr.08	40.51	73.59	>1800.00	36.47
s3_srvr.09	265.48	265.48	>1800.00	4.94
s3_srvr.10	40.24	66.88	>1800.00	12.01
s3_srvr.11	49.05	49.05	>1800.00	4.80
s3_srvr.12	38.66	38.66	>1800.00	6.11
s3_srvr.13	251.56	251.56	>1800.00	15.20
s3_srvr.14	39.94	53.93	1656.54	4.63
s3_srvr.15	40.19	77.51	>1800.00	10.19
s3_srvr.16	39.54	55.97	>1800.00	5.21
TOTAL	24 / 2296.25	22 / 1637.84	10 / 5747.10	24 / 188.67



Results – ntdrivers and SSH – unsafe

Program	Blast		CPAchecker	
	Best result	-bfs -predH 7	SBE	LBE
cdaudio	18.79	99.82	74.39	9.85
diskperf	889.79	>1800.00	26.53	6.78
floppy	119.60	>1800.00	36.49	4.30
kbfiltr	46.80	144.25	75.45	11.52
parport	1.67	10.95	14.62	2.64
s3_clnt.01	8.84	28.30	1514.90	3.33
s3_clnt.02	9.02	9.02	843.42	3.27
s3_clnt.03	6.64	6.64	780.72	2.61
s3_clnt.04	9.78	9.78	724.04	3.18
s3_srvr.01	7.59	7.59	MO	2.09
s3_srvr.02	7.16	7.16	>1800.00	2.10
s3_srvr.03	7.42	7.42	>1800.00	2.08
s3_srvr.04	7.33	7.33	>1800.00	1.93
s3_srvr.06		6.11	MO	5.08
s3_srvr.07		0.84	>1800.00	28.35
s3_srvr.08		3.59	>1800.00	36.47
s3_srvr.09		5.48	>1800.00	4.94
s3_srvr.10		6.88	>1800.00	12.01
s3_srvr.11	49.05	49.05	>1800.00	4.80
s3_srvr.12	38.66	38.66	>1800.00	6.11
s3_srvr.13	251.56	251.56	>1800.00	15.20
s3_srvr.14	39.94	53.93	1656.54	4.63
s3_srvr.15	40.19	77.51	>1800.00	10.19
s3_srvr.16	39.54	55.97	>1800.00	5.21
TOTAL	24 / 2296.25	22 / 1637.84	10 / 5747.10	24 / 188.67

~12x faster



Results – ntdrivers and SSH – unsafe

Program	Blast		CPAchecker	
	Best result	-bfs -predH 7	SBE	LBE
cdaudio	18.79	99.82	74.39	9.85
diskperf	889.79	>1800.00	26.53	6.78
floppy	119.60	>1800.00	36.49	4.30
kbfiltr	46.80	144.25	75.45	11.52
parport	1.67	10.95	14.62	2.64
s3_clnt.01	8.84	28.30	1514.90	3.33
s3_clnt.02	9.02	9.02	843.42	3.27
s3_clnt.03	6.64	6.64	780.72	2.61
s3_clnt.04	9.78	9.78	724.04	3.18
s3_srvr.01	7.59	7.59	MO	2.09
s3_srvr.02	7.16	7.16	>1800.00	2.10
s3_srvr.03	7.42	7.42	>1800.00	2.08
s3_srvr.04	7.33	7.33	>1800.00	1.93
s3_srvr.06		6.11	MO	5.08
s3_srvr.07		0.84	>1800.00	28.35
s3_srvr.08		3.59	>1800.00	36.47
s3_srvr.09		5.48	>1800.00	4.94
s3_srvr.10		6.88	>1800.00	12.01
s3_srvr.11	49.05	49.05	>1800.00	4.80
s3_srvr.12	38.66	38.66	>1800.00	6.11
s3_srvr.13	251.56	251.56	>1800.00	15.20
s3_srvr.14	39.94	53.93	1656.54	4.63
s3_srvr.15	40.19	77.51	>1800.00	10.19
s3_srvr.16	39.54	55.97	>1800.00	5.21
TOTAL	24 / 2296.25	22 / 1637.84	10 / 5747.10	24 / 188.67

2 more instances,
~9.2x faster



Conclusions

- ◆ **Large-Block Encoding**: new approach to ART-based SW MC, for **better exploiting** modern **SMT** solvers
 - ◆ Move cost from explicit path enumeration to symbolic computations within the SMT solver
 - ◆ Nice improvements on standard benchmark programs
- ◆ **Future work**
 - ◆ Dynamic computation of large blocks
 - ◆ Allows for adjusting the symbolic/explicit tradeoff “on the fly”
 - ◆ Experiment with **approximated abstractions**, cheaper than Boolean
 - ◆ Extend to McMillan's CAV'06 approach (no predicate abstraction, use interpolants directly)

