

Satisfiability Modulo Theories and Z3

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Microsoft Research
ReRISE Winter School, Linz, Austria
February 4, 2014

Plan

Mon An invitation to SMT with Z3

Tue Equalities and Theory Combination

Wed Theories: Arithmetic, Arrays, Data types

Thu Quantifiers and Theories

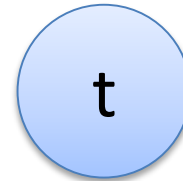
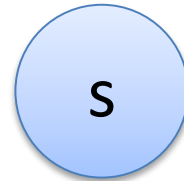
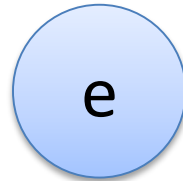
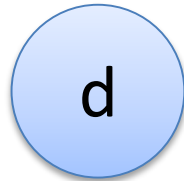
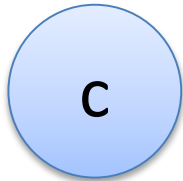
Fri Programming Z3: Interfacing and Solving

Lecture Overview

- Deciding Equality
- Uninterpreted Functions
- Nelson Oppen Combination
- Model-based Theory Combination

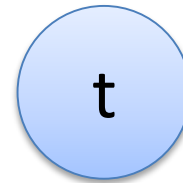
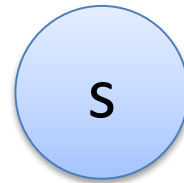
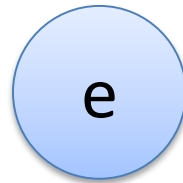
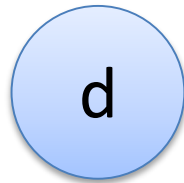
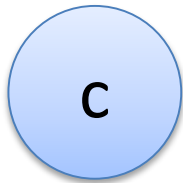
Deciding Equality

$a = b, b = c, d = e, b = s, d = t, a \neq e, a \neq s$



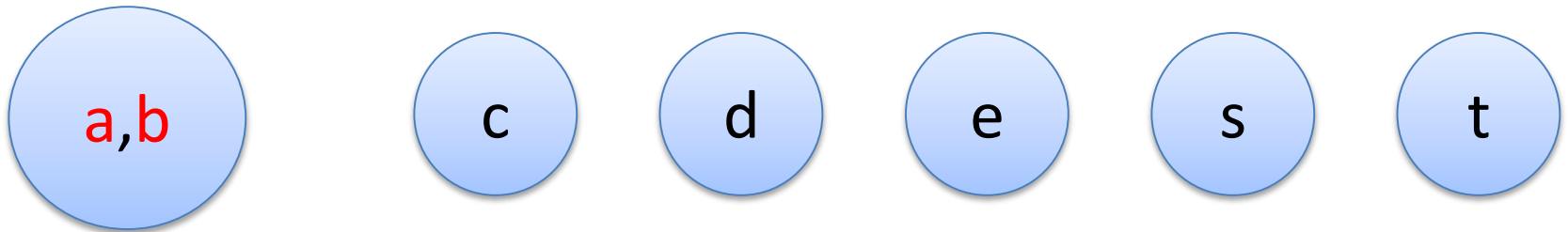
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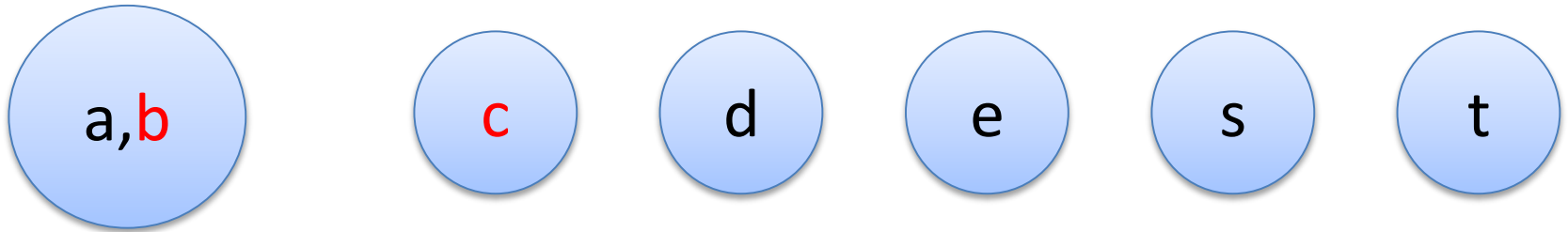
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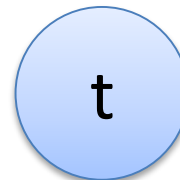
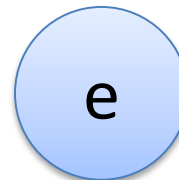
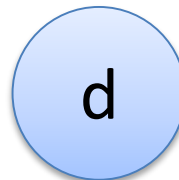
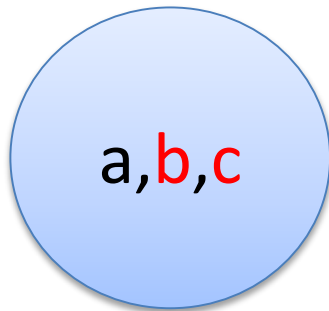
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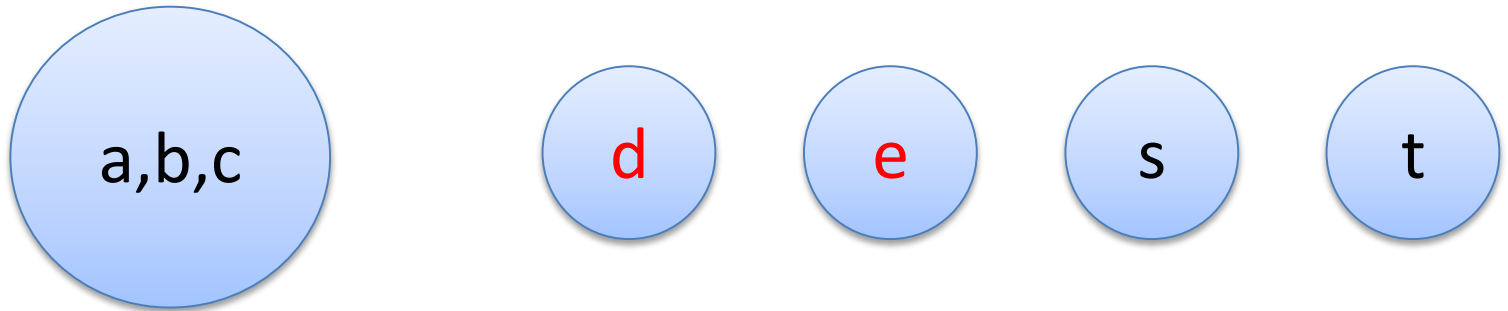
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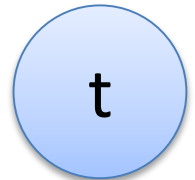
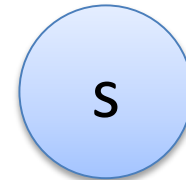
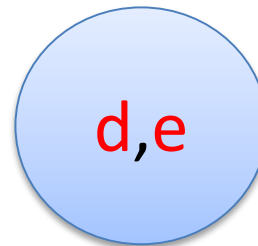
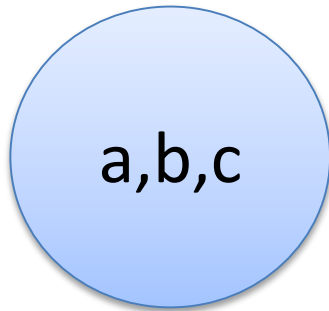
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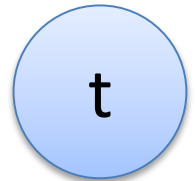
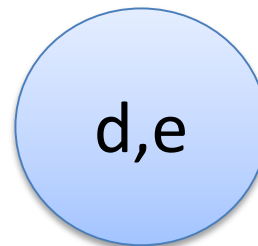
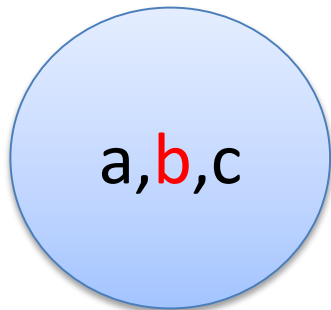
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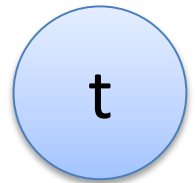
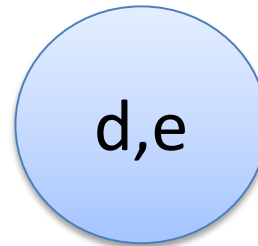
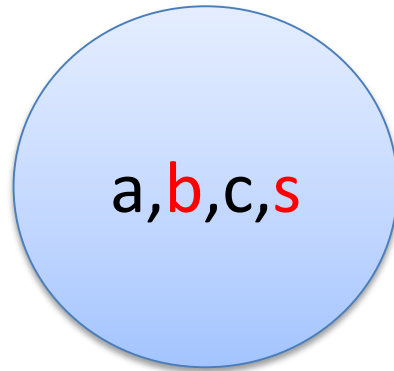
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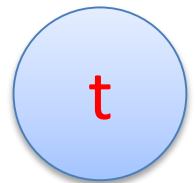
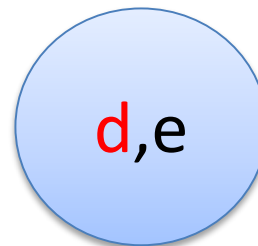
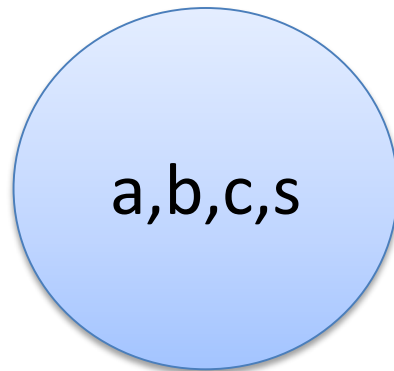
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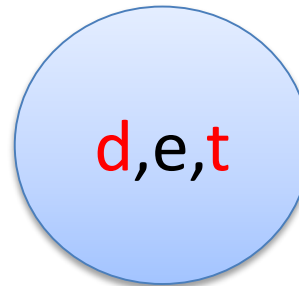
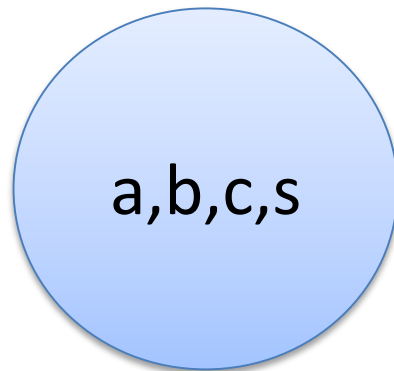
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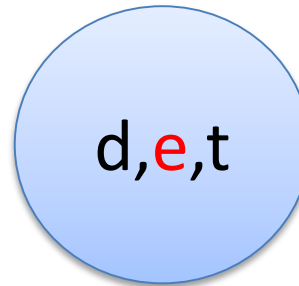
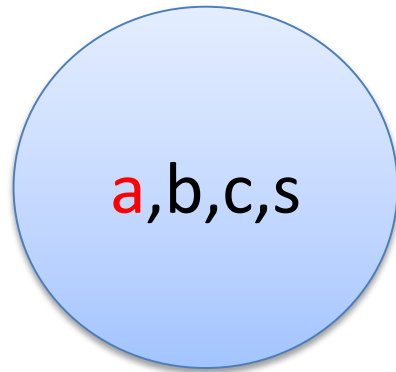
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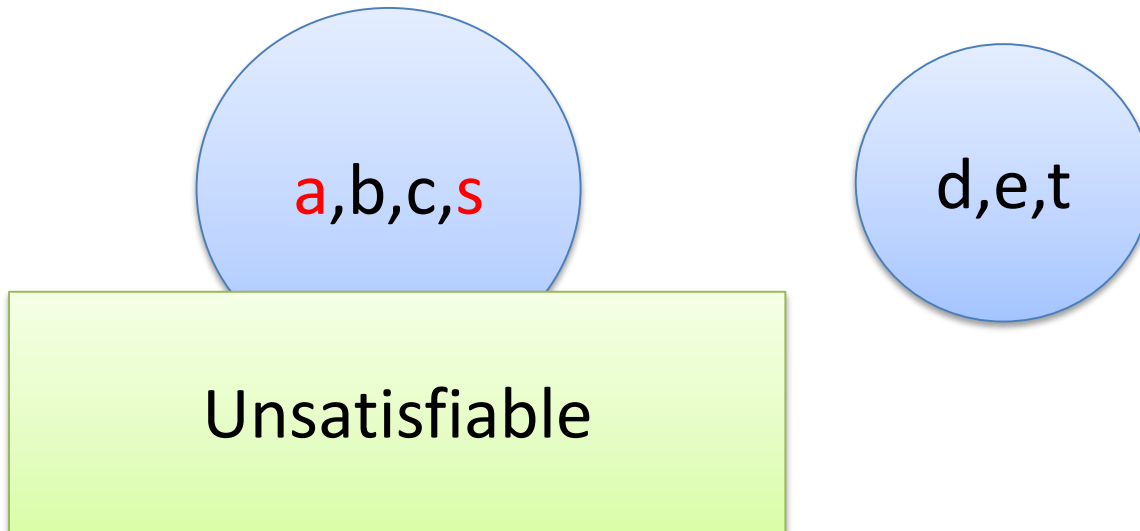
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Deciding Equality

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Deciding Equality

$a = b, b = c, d = e, b = s, d = t, a \neq e$



Model construction

Deciding Equality

$a = b, b = c, d = e, b = s, d = t, a \neq e$



Model construction

$|M| = \{\diamond_1, \diamond_2\}$ (universe, aka domain)

Deciding Equality

$a = b, b = c, d = e, b = s, d = t, a \neq e$



Model construction

$|M| = \{\diamond_1, \diamond_2\}$ (universe, aka domain)

$M(a) = \diamond_1$ (assignment)

Deciding Equality

$a = b, b = c, d = e, b = s, d = t, a \neq e$



Alternative notation:

$$a^M = \diamond_1$$

Model construction

$|M| = \{\diamond_1, \diamond_2\}$ (universe, aka domain)

$M(a) = \diamond_1$ (assignment)

Deciding Equality

$a = b, b = c, d = e, b = s, d = t, a \neq e$



Model construction

$|M| = \{\diamond_1, \diamond_2\}$ (universe, aka domain)

$M(a) = M(b) = M(c) = M(s) = \diamond_1$

$M(d) = M(e) = M(t) = \diamond_2$

Deciding Equality:

Termination, Soundness, Completeness

- Termination: easy
- Soundness
 - Invariant: all constants in a “ball” are known to be equal.
 - The “ball” merge operation is justified by:
 - Transitivity and Symmetry rules.
- Completeness
 - We can build a model if an inconsistency was not detected.
 - Proof template (by contradiction):
 - Build a candidate model.
 - Assume a literal was not satisfied.
 - Find contradiction.

Equality: Union-Find [Tarjan]

```
vector<int> F;
```

```
int new_node() { F.push_back(-1); return F.size()-1; }
```

```
int find(int node) {  
    if (F[node] != -1) { F[node] = find(node); return F[node]; }  
    return node;  
}
```

```
void merge(int n1, int n2) {  
    n1 = find(n1); n2 = find(n2);  
    if (F[n1] > F[n2]) swap(n1, n2);  
    if (n1 == n2) return;  
    F[n1] += F[n2];  
    F[n2] = n1;  
}
```

- Size of
equivalence
class

Lazy path
compression
Variant: Eager
Path
compression +
equivalence
class as doubly
linked list

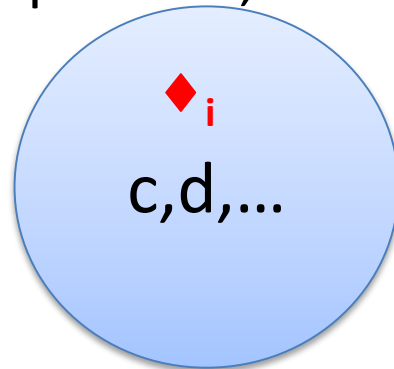
$n \log^*(n)$ amortized
time for n operations

Root for largest class
takes over

Deciding Equality:

Termination, Soundness, Completeness

- Completeness
 - We can build a model if an inconsistency was not detected.
 - Instantiating the template for our procedure:
 - Assume some literal $c = d$ is not satisfied by our model.
 - That is, $M(c) \neq M(d)$.
 - This is impossible, c and d must be in the same “ball”.

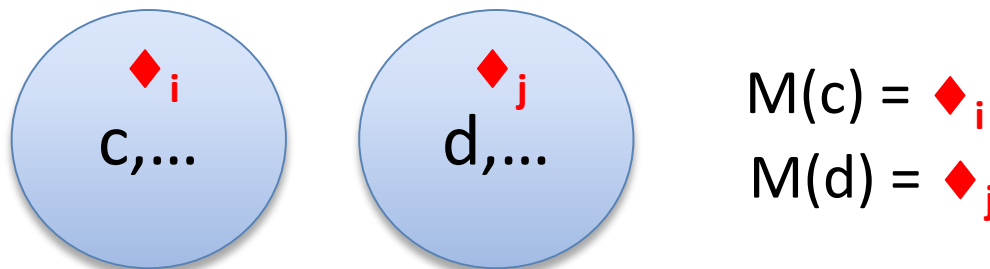


$$M(c) = M(d) = \color{red}{\blacklozenge}_i$$

Deciding Equality:

Termination, Soundness, Completeness

- Completeness
 - We can build a model if an inconsistency was not detected.
 - Instantiating the template for our procedure:
 - Assume some literal $c \neq d$ is not satisfied by our model.
 - That is, $M(c) = M(d)$.
 - Key property: we only check the disequalities after we processed all equalities.
 - This is impossible, c and d must be in the different “balls”



Deciding Equality + (uninterpreted) Functions

$a = b, b = c, d = e, b = s, d = t, f(a, g(d)) \neq f(b, g(e))$

Congruence Rule:

$x_1 = y_1, \dots, x_n = y_n$ implies $f(x_1, \dots, x_n) = f(y_1, \dots, y_n)$

Deciding Equality + (uninterpreted) Functions

$$a = b, b = c, d = e, b = s, d = t, f(a, g(d)) \neq f(b, g(e))$$

First Step: “Naming” subterms

Congruence Rule:

$$x_1 = y_1, \dots, x_n = y_n \text{ implies } f(x_1, \dots, x_n) = f(y_1, \dots, y_n)$$

Deciding Equality + (uninterpreted) Functions

$$a = b, b = c, d = e, b = s, d = t, f(a, v_1) \neq f(b, g(e))$$
$$v_1 \equiv g(d)$$

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Deciding Equality + (uninterpreted) Functions

$$a = b, b = c, d = e, b = s, d = t, f(a, v_1) \neq f(b, v_2)$$
$$v_1 \equiv g(d), v_2 \equiv g(e)$$

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Deciding Equality + (uninterpreted) Functions

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Deciding Equality + (uninterpreted) Functions

$a = b, b = c, d = e, b = s, d = t, v_3 \neq v_4$

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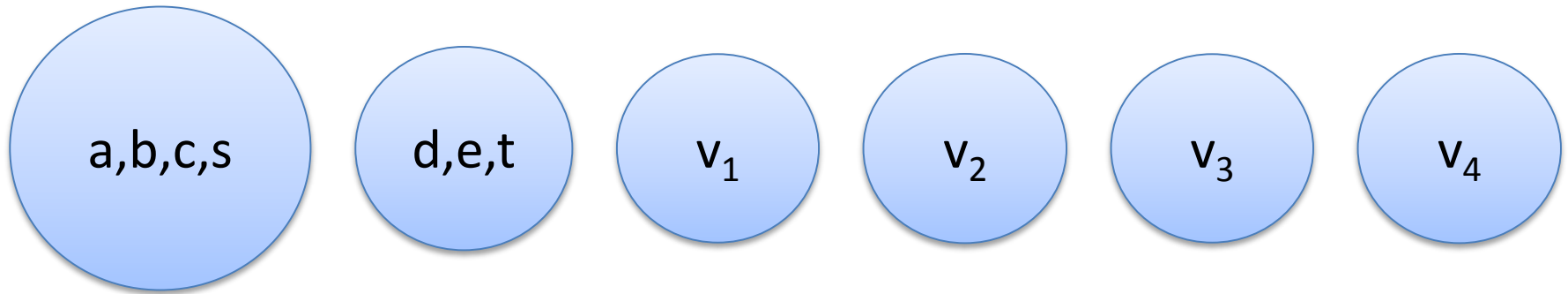
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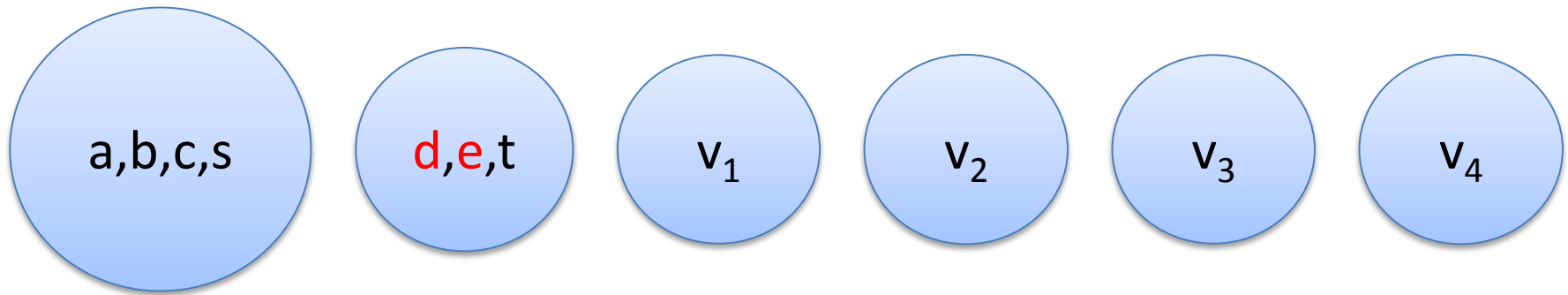
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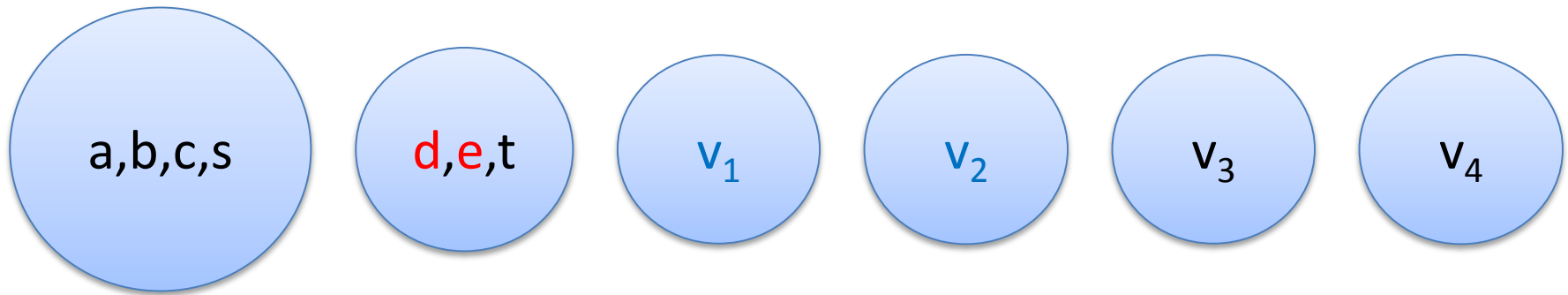
$x_1 = y_1, \dots, x_n = y_n$ implies $f(x_1, \dots, x_n) = f(y_1, \dots, y_n)$

$d = e$ implies $g(d) = g(e)$

Deciding Equality + (uninterpreted) Functions

$a = b, b = c, d = e, b = s, d = t, v_3 \neq v_4$

$v_1 \equiv g(d), v_2 \equiv g(e), v_3 \equiv f(a, v_1), v_4 \equiv f(b, v_2)$



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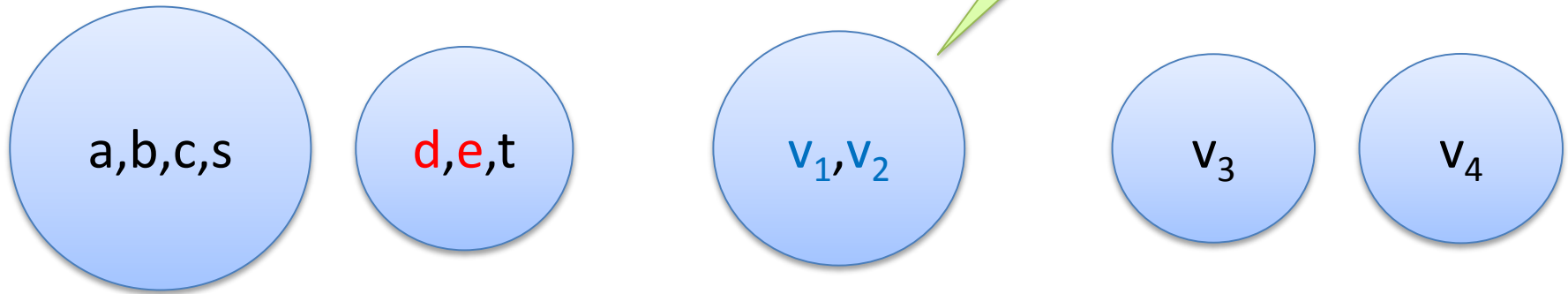
$d = e$ implies $v_1 = v_2$

Deciding Equality (uninterpreted) Functions

We say:
 v_1 and v_2 are **congruent**.

$$a = b, b = c, d = e, b = s, d = t, v_1 = v_4$$

$$v_1 \equiv g(d), v_2 \equiv g(e), v_3 \equiv f(a, v_1), v_4 \equiv f(b, v_2)$$



Congruence Rule:

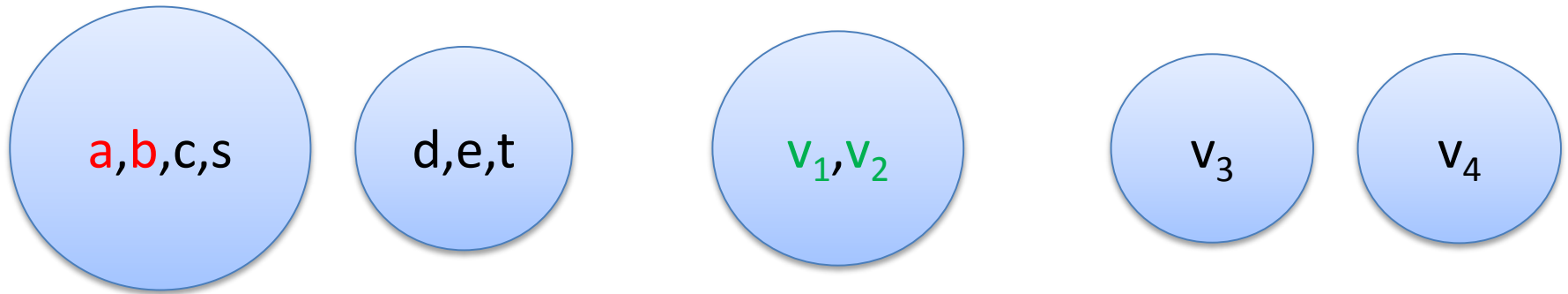
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Deciding Equality + (uninterpreted) Functions

$a = b, b = c, d = e, b = s, d = t, v_3 \neq v_4$

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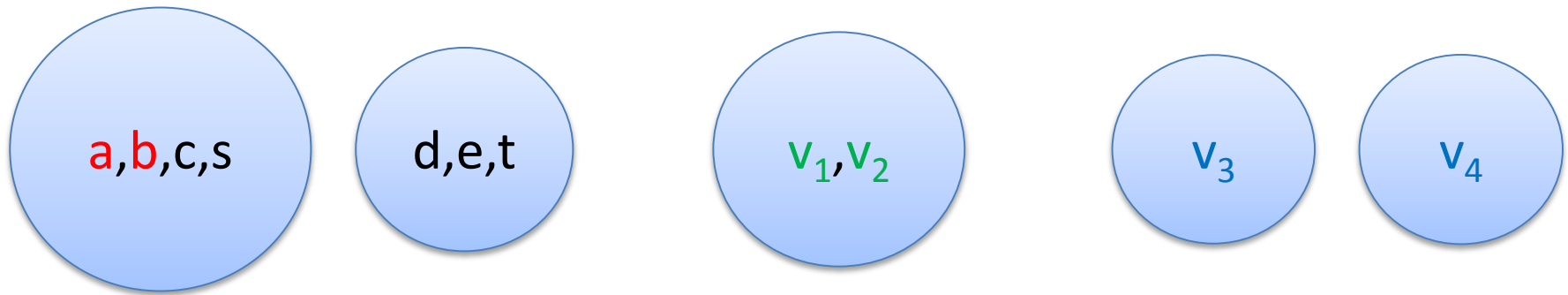
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$a = b, v_1 = v_2$ implies $f(a, v_1) = f(b, v_2)$

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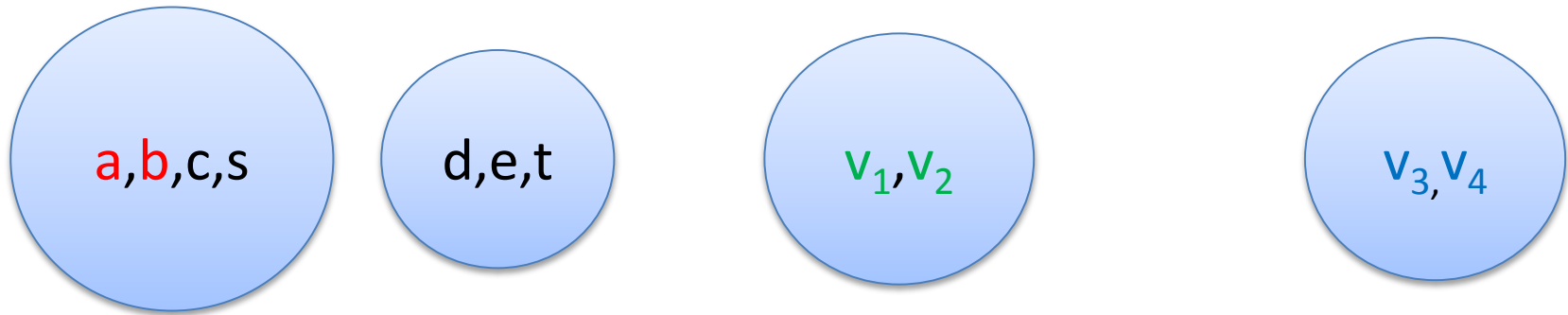
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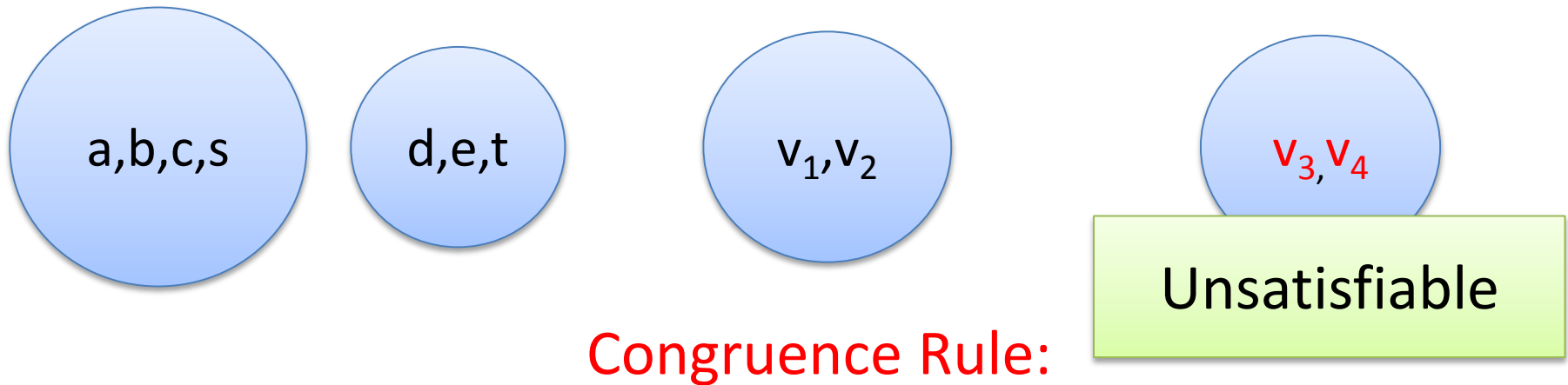
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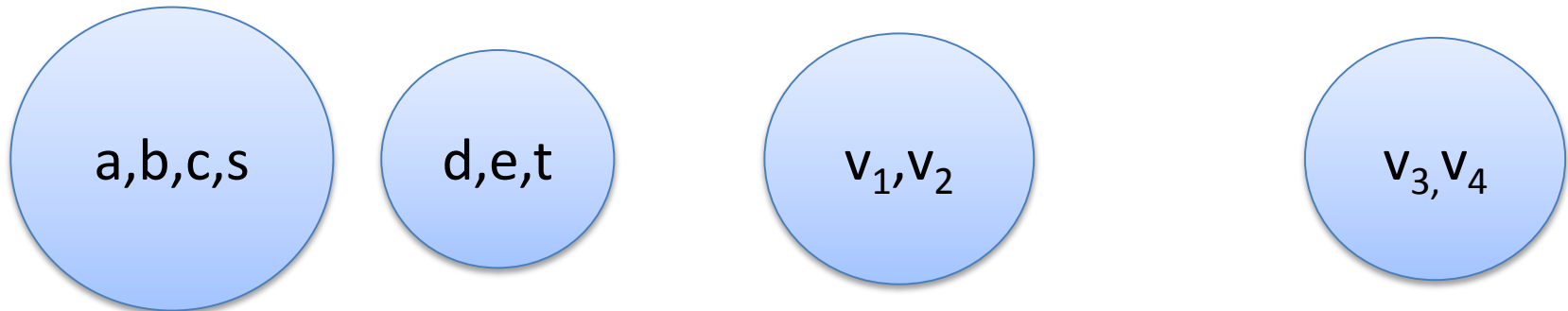
$x_1 = y_1, \dots, x_n = y_n$ implies $f(x_1, \dots, x_n) = f(y_1, \dots, y_n)$

Deciding Equality + (uninterpreted) Functions

$a = b, b = c, d = e, b = s, d = t, a \neq v_4, v_2 \neq v_3$

$v_1 \equiv g(d), v_2 \equiv g(e), v_3 \equiv f(a, v_1), v_4 \equiv f(b, v_2)$

Changing the problem

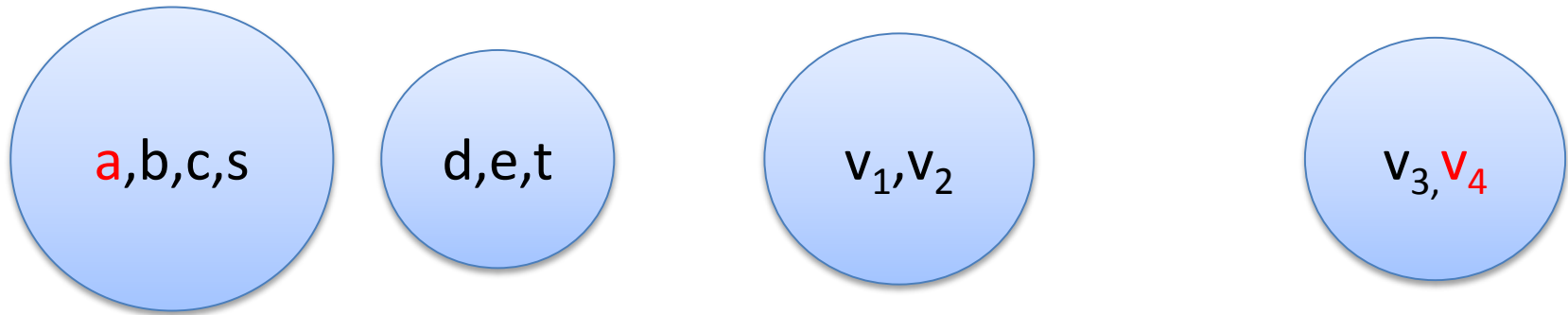


Congruence Rule:

$x_1 = y_1, \dots, x_n = y_n$ implies $f(x_1, \dots, x_n) = f(y_1, \dots, y_n)$

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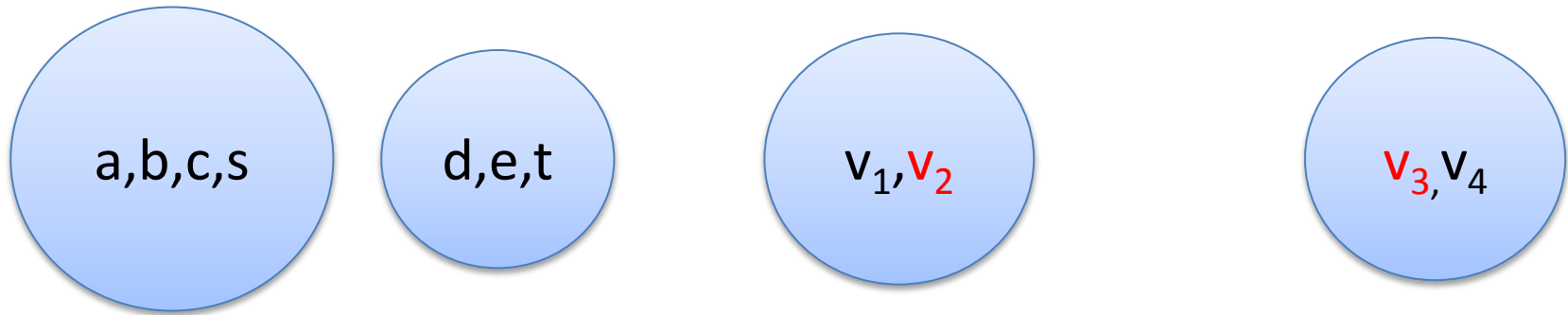
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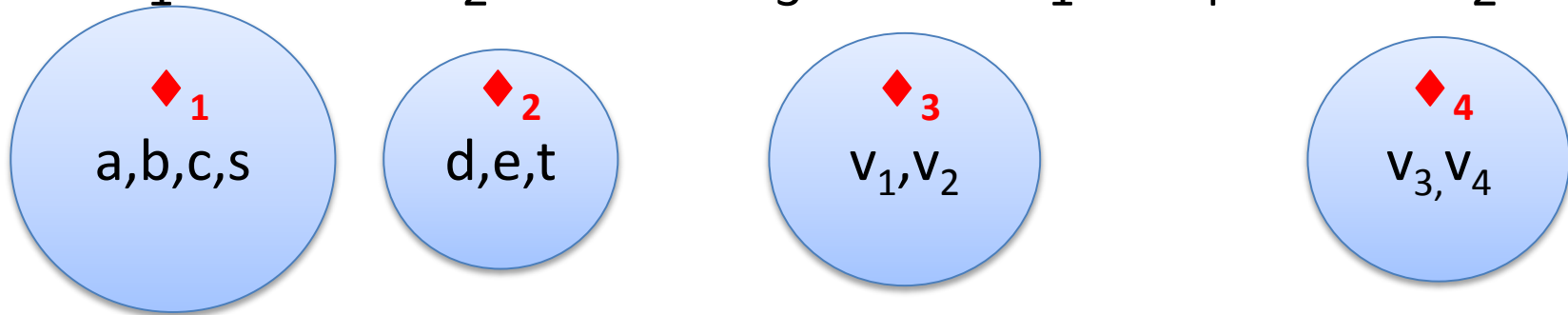
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$a = b, b = c, d = e, b = s, d = t, a \neq v_4, v_2 \neq v_3$

$v_1 \equiv g(d), v_2 \equiv g(e), v_3 \equiv f(a, v_1), v_4 \equiv f(b, v_2)$



Model construction:

$$|M| = \{\blacklozenge_1, \blacklozenge_2, \blacklozenge_3, \blacklozenge_4\}$$

$$M(a) = M(b) = M(c) = M(s) = \blacklozenge_1$$

$$M(d) = M(e) = M(t) = \blacklozenge_2$$

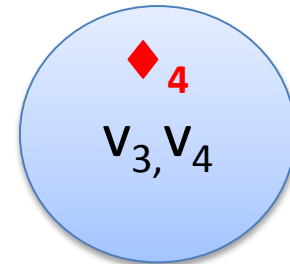
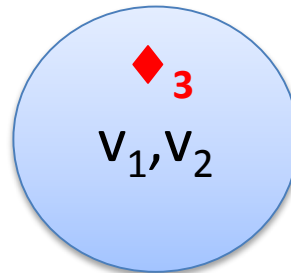
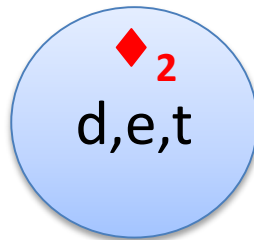
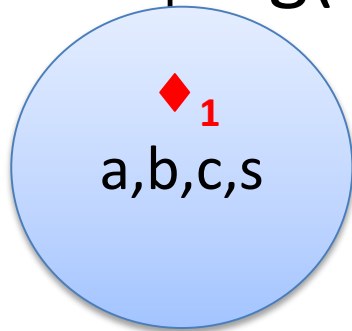
$$M(v_1) = M(v_2) = \blacklozenge_3$$

$$M(v_3) = M(v_4) = \blacklozenge_4$$

Deciding Equality + (uninterpreted) Functions

$a = b, b = c, d = e, b = s, d = t, a \neq v_4, v_2 \neq v_3$

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$$M(v_1) = M(v_2) = \text{◆}_3$$

$$M(v_3) = M(v_4) = \text{◆}_4$$

Missing:
Interpretation for
f and g.

Deciding Equality + (uninterpreted) Functions

Building the interpretation for function symbols

– $M(g)$ is a mapping from $|M|$ to $|M|$

– Defined as:

$M(g)(\diamond_i) = \diamond_j$ if there is $v \equiv g(a)$ s.t.

$M(a) = \diamond_i$

$M(v) = \diamond_j$

$= \diamond_k$, otherwise (\diamond_k is an arbitrary element)

Is $M(g)$ well-defined?

Deciding Equality + (uninterpreted) Functions

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Is $M(g)$ well-defined? Problem: we may have

$v \equiv g(a)$ and $w \equiv g(b)$ s.t.

$$M(a) = M(b) = \diamond_1 \text{ and } M(v) = \diamond_2 \neq \diamond_3 = M(w)$$

So, is $M(g)(\diamond_1) = \diamond_2$ or $M(g)(\diamond_1) = \diamond_3$?

Deciding Equality + (uninterpreted) Functions

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$$= \diamond_k, \text{ otherwise } (\diamond_i \text{ is an arbitrary element})$$

This is impossible because of the congruence rule!

a and b are in the same “ball”, then so are v and w

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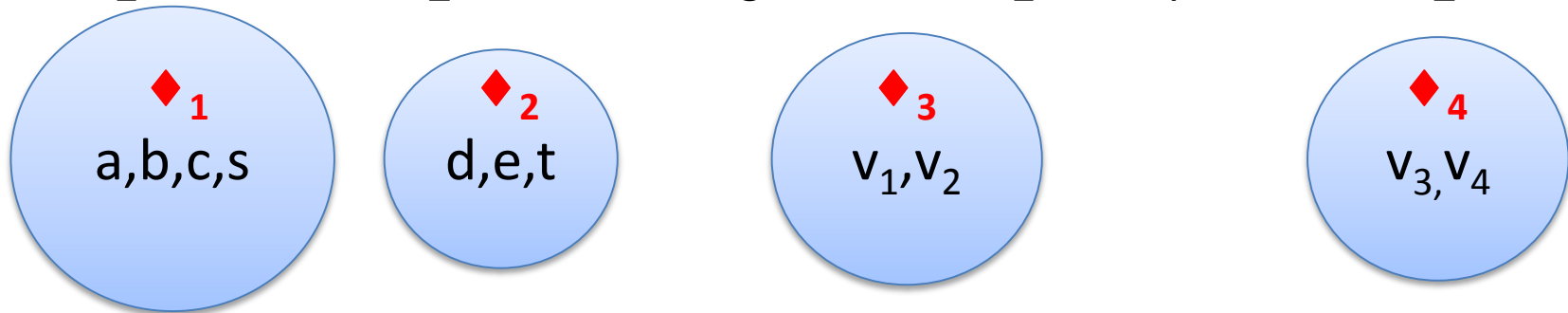
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$$M(g)(\diamond_i) = \diamond_j \text{ if there is } v \equiv g(a) \text{ s.t.}$$
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Deciding Equality + (uninterpreted) Functions

What about predicates?

$p(a, b), \neg p(c, b)$

Deciding Equality + (uninterpreted) Functions

What about predicates?

$p(a, b), \neg p(c, b)$



$f_p(a, b) = T, f_p(c, b) \neq T$

Deciding Equality + (uninterpreted) Functions

It is possible to implement our procedure in
 $O(n \log n)$

Case Analysis

Many verification/analysis problems require:

case-analysis

$$x \geq 0, y = x + 1, (y > 2 \vee y < 1)$$

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Naïve Solution: Convert to DNF

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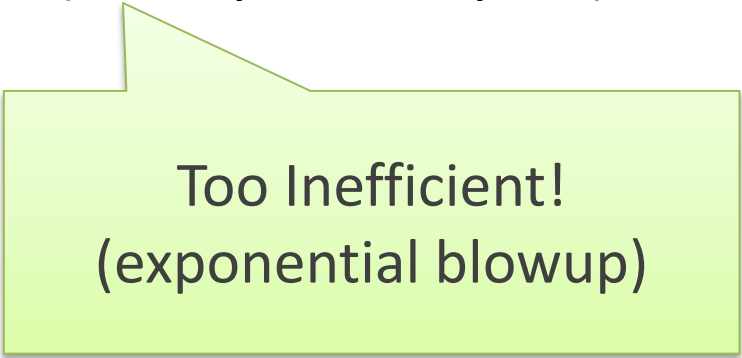
Case Analysis

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Naïve Solution: Convert to DNF

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Too Inefficient!
(exponential blowup)

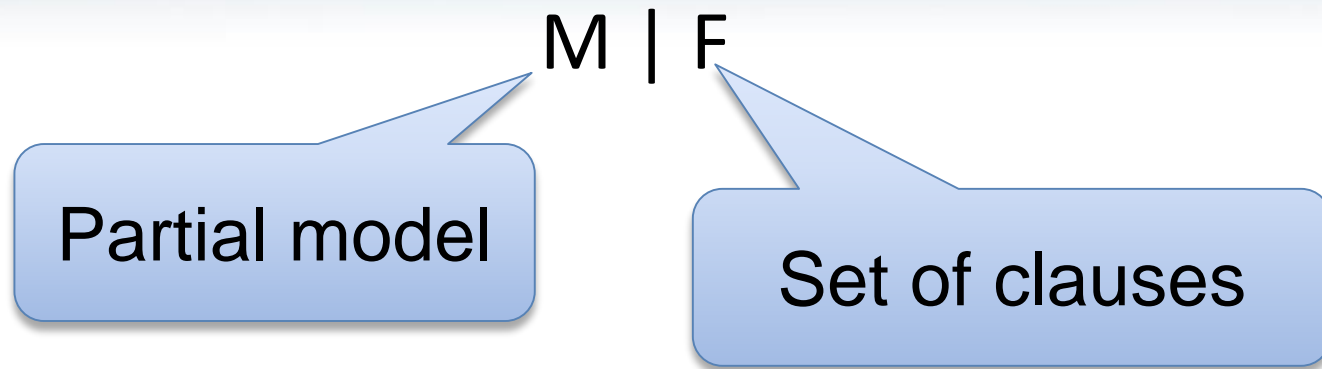
SMT : Basic Architecture



Case Analysis

- Equality + UF
- Arithmetic
- Bit-vectors
- ...

DPLL



DPLL

Guessing

$$p \mid p \vee q, \neg q \vee r$$



$$p, \neg q \mid p \vee q, \neg q \vee r$$

DPLL

Deducing

$p \mid p \vee q, \neg p \vee s$



$p, s \mid p \vee q, \neg p \vee s$

DPLL

Backtracking

$p, \neg s, q \mid p \vee q, s \vee q, \neg p \vee \neg q$



$p, s \mid p \vee q, s \vee q, \neg p \vee \neg q$

SAT + Theory solvers

Basic Idea

$$x \geq 0, y = x + 1, (y > 2 \vee y < 1)$$



Abstract (aka “naming” atoms)

$$p_1, p_2, (p_3 \vee p_4) \quad p_1 \equiv (x \geq 0), p_2 \equiv (y = x + 1), \\ p_3 \equiv (y > 2), p_4 \equiv (y < 1)$$

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SAT
Solver

SAT + Theory solvers

Basic Idea

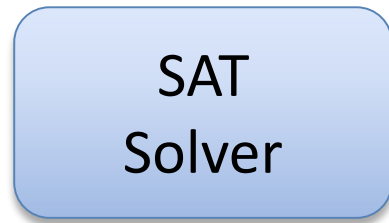
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Assignment

$p_1, p_2, \neg p_3, p_4$

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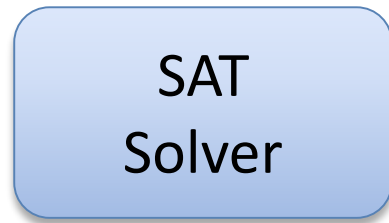
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$$p_1, p_2, \neg p_3, p_4$$



$$x \geq 0, y = x + 1, \\ \neg(y > 2), y < 1$$



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SAT Solver

Assignment

$$p_1, p_2, \neg p_3, p_4$$

$$x \geq 0, y = x + 1, \\ \neg(y > 2), y < 1$$

Unsatisfiable

$$x \geq 0, y = x + 1, y < 1$$

Theory Solver

SAT + Theory solvers

Basic Idea

$$x \geq 0, y = x + 1, (y > 2 \vee y < 1)$$

Abstract (aka “naming” atoms)

$$p_1, p_2, (p_3 \vee p_4) \quad p_1 \equiv (x \geq 0), p_2 \equiv (y = x + 1), \\ p_3 \equiv (y > 2), p_4 \equiv (y < 1)$$

SAT Solver

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Theory Solver

Unsatisfiable

$$x \geq 0, y = x + 1, y < 1$$

New Lemma

$$\neg p_1 \vee \neg p_2 \vee \neg p_4$$

SAT + Theory solvers

New Lemma

$\neg p_1 \vee \neg p_2 \vee \neg p_4$

Unsatisfiable

$x \geq 0, y = x + 1, y < 1$

Theory Solver

AKA
Theory conflict

SAT + Theory solvers: Main loop

```
procedure SmtSolver(F)
  (Fp, M) := Abstract(F)
  loop
    (R, A) := SAT_solver(Fp)
    if R = UNSAT then return UNSAT
    S := Concretize(A, M)
    (R, S') := Theory_solver(S)
    if R = SAT then return SAT
    L := New_Lemma(S', M)
    Add L to Fp
```

SAT + Theory solvers

Basic Idea

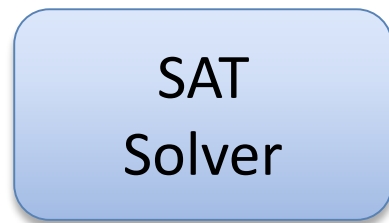
$$F: x \geq 0, y = x + 1, (y > 2 \vee y < 1)$$



Abstract (aka “naming” atoms)

$$F_p: p_1, p_2, (p_3 \vee p_4)$$

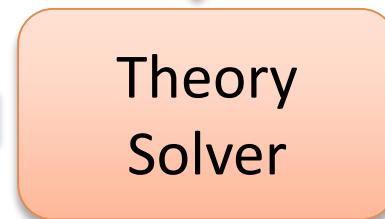
$$M: p_1 \equiv (x \geq 0), p_2 \equiv (y = x + 1), \\ p_3 \equiv (y > 2), p_4 \equiv (y < 1)$$



A: Assignment

$$p_1, p_2, \neg p_3, p_4$$

$$S: x \geq 0, y = x + 1, \\ \neg(y > 2), y < 1$$



S': Unsatisfiable

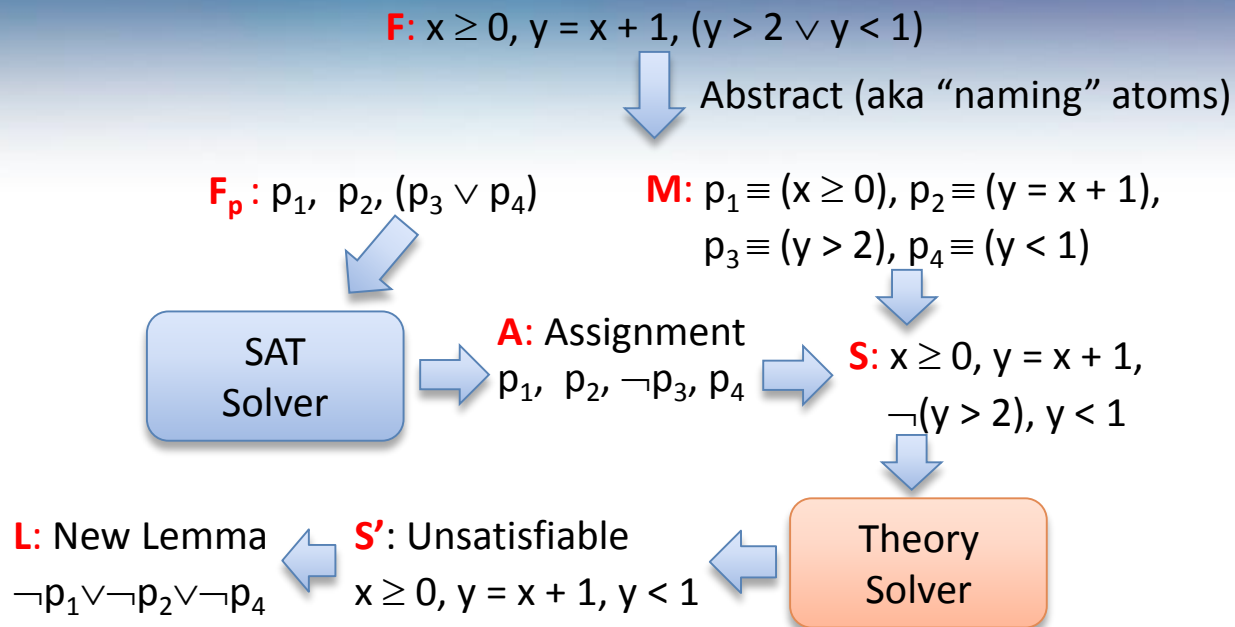
$$x \geq 0, y = x + 1, y < 1$$



L: New Lemma

$$\neg p_1 \vee \neg p_2 \vee \neg p_4$$

SAT + Theory solvers



procedure SMT_Solver(**F**)

(**F_p**, **M**) := Abstract(**F**)

loop

(**R**, **A**) := SAT_solver(**F_p**)

if **R** = UNSAT **then return** UNSAT

S = Concretize(**A**, **M**)

(**R**, **S'**) := Theory_solver(**S**)

if **R** = SAT **then return** SAT

L := New_Lemma(**S**, **M**)

Add **L** to **F_p**

“Lazy translation”
to
DNF

SAT + Theory solvers

State-of-the-art SMT solvers implement many improvements.

SAT + Theory solvers

Incrementality

Send the literals to the Theory solver as they are assigned by the SAT solver

$$p_1 \equiv (x \geq 0), p_2 \equiv (y = x + 1),$$

$$p_3 \equiv (y > 2), p_4 \equiv (y < 1), p_5 \equiv (x < 2),$$

$$p_1, p_2, p_4 \mid p_1, p_2, (p_3 \vee p_4), (p_5 \vee \neg p_4)$$

Partial assignment is already
Theory inconsistent.

SAT + Theory solvers

Efficient Backtracking

We don't want to restart from scratch after each backtracking operation.

SAT + Theory solvers

Efficient Lemma Generation (computing a small S')

Avoid lemmas containing redundant literals.

$$p_1 \equiv (x \geq 0), p_2 \equiv (y = x + 1),$$

$$p_3 \equiv (y > 2), p_4 \equiv (y < 1), p_5 \equiv (x < 2),$$

$$p_1, p_2, p_3, p_4 \mid p_1, p_2, (p_3 \vee p_4), (p_5 \vee \neg p_4)$$

$$\neg p_1 \vee \neg p_2 \vee \neg p_3 \vee \neg p_4$$

Imprecise Lemma

SAT + Theory solvers

Theory Propagation

It is the SMT equivalent of unit propagation.

$$p_1 \equiv (x \geq 0), p_2 \equiv (y = x + 1),$$

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$$p_1, p_2 \mid p_1, p_2, (p_3 \vee p_4), (p_5 \vee \neg p_4)$$



p_1, p_2 imply $\neg p_4$ by theory propagation

$$p_1, p_2, \neg p_4 \mid p_1, p_2, (p_3 \vee p_4), (p_5 \vee \neg p_4)$$

SAT + Theory solvers

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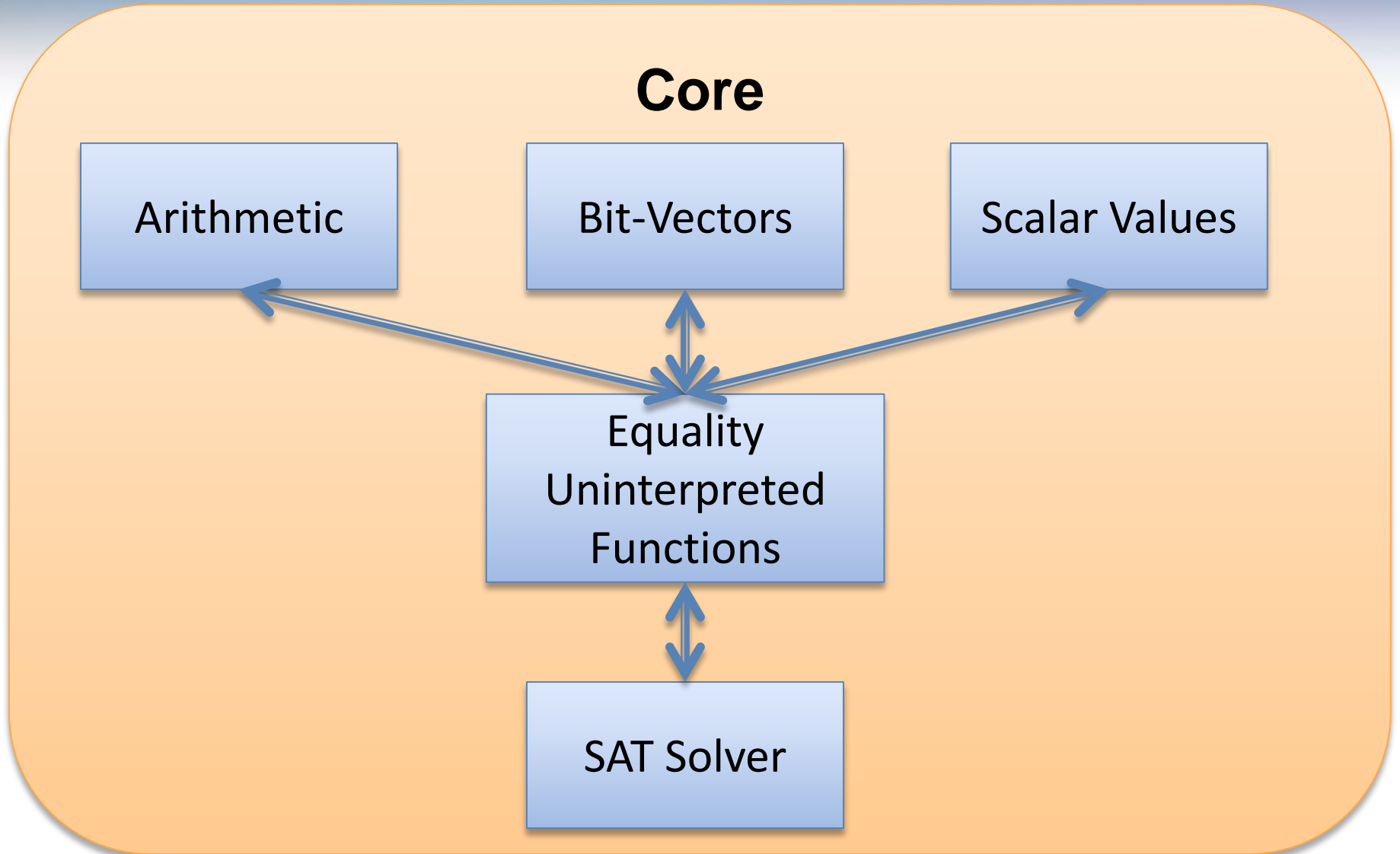


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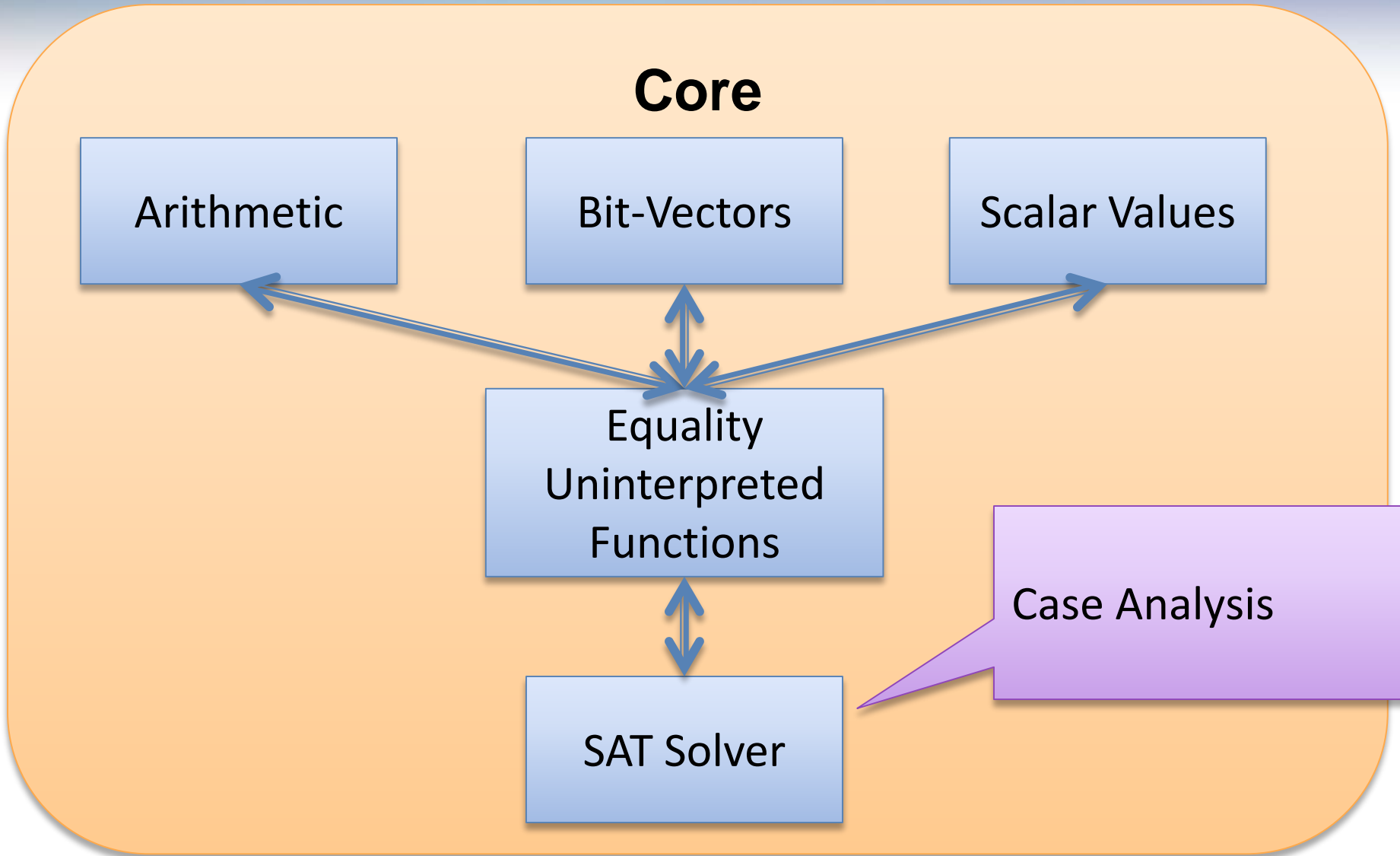
$$p_1, p_2, \neg p_4 \mid p_1, p_2, (p_3 \vee p_4), (p_5 \vee \neg p_4)$$

Tradeoff between precision \times performance.

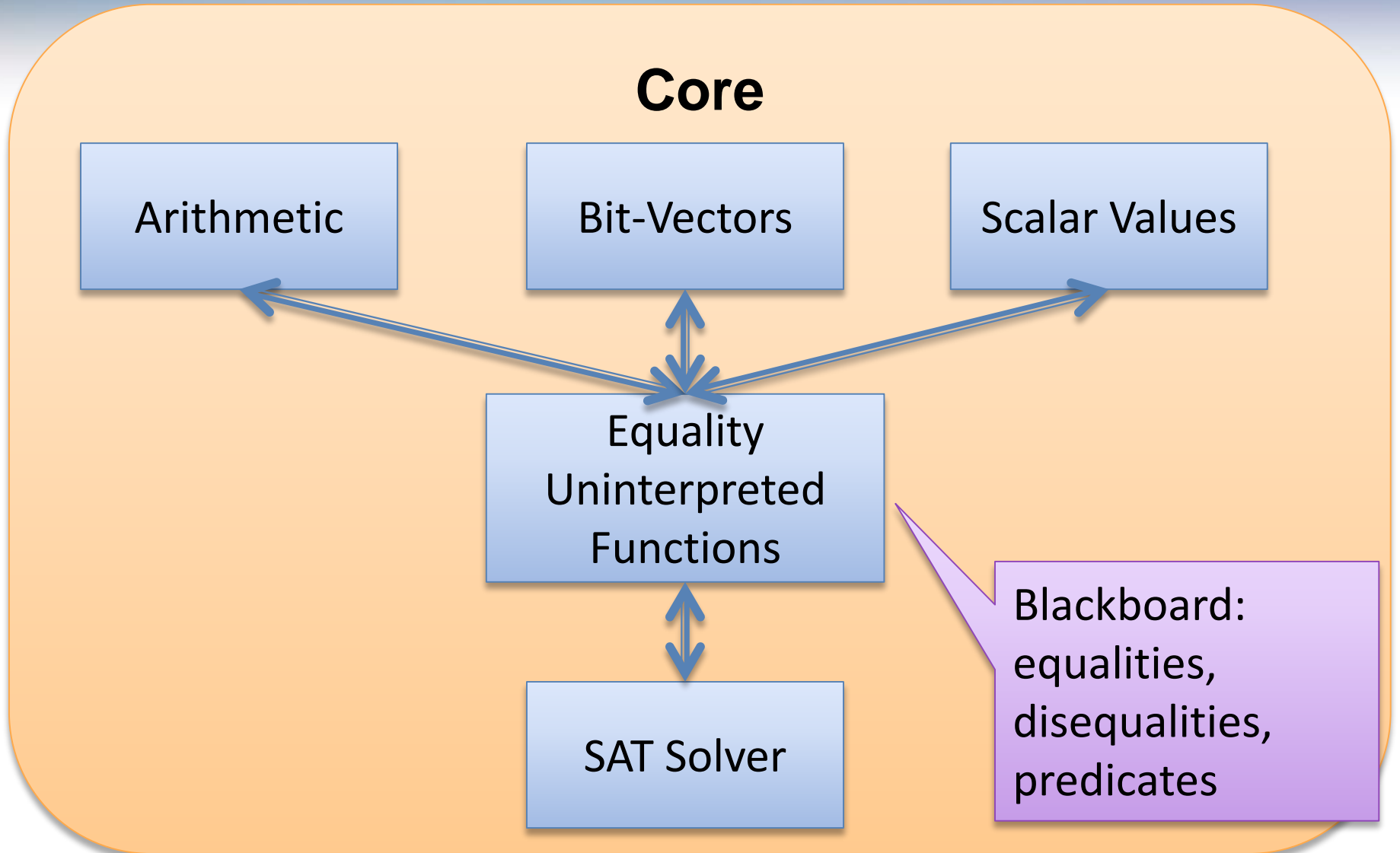
An Architecture: the core



An Architecture: the core



An Architecture: the core



Combining Theories

In practice, we need a combination of theories.

$b + 2 = c$ and $f(\text{read}(\text{write}(a,b,3), c-2)) \neq f(c-b+1)$

A theory is a set (potentially infinite) of first-order sentences.

Main questions:

Is the union of two theories $T1 \cup T2$ consistent?

Given a solvers for $T1$ and $T2$, how can we build a solver for $T1 \cup T2$?

A Combination History

Foundations

- 1979 Nelson, Oppen - Framework
- 1996 Tinelli & Harindi. N.O Fix
- 2000 Barrett et.al N.O + Rewriting
- 2002 Zarba & Manna. "Nice" Theories
- 2004 Ghilardi et.al. N.O. Generalized

Efficiency using rewriting

- 1984 Shostak. Theory solvers
- 1996 Cyrluk et.al Shostak Fix #1
- 1998 B. Shostak with Constraints
- 2001 Rueß & Shankar Shostak Fix #2
- 2004 Ranise et.al. N.O + Superposition



2001: Moskewicz et.al. Efficient DPLL made guessing cheap

2006 Bruttomesso et.al. Delayed Theory Combination

2007 de Moura & B. Model-based Theory Combination

... 2013 Jojanovich et.al. polite, shiny, etc.

Disjoint Theories

Two theories are disjoint if they do not share function/constant and predicate symbols.

= is the only exception.

Example:

The theories of arithmetic and arrays are disjoint.

Arithmetic symbols: $\{0, -1, 1, -2, 2, \dots, +, -, *, >, <, \geq, \leq\}$

Array symbols: $\{\text{read}, \text{write}\}$

Purification

It is a different name for our “naming” subterms procedure.

$$b + 2 = c, f(\text{read}(\text{write}(a, b, 3), c - 2)) \neq f(c - b + 1)$$



$$b + 2 = c, v_6 \neq v_7$$

$$v_1 \equiv 3, v_2 \equiv \text{write}(a, b, v_1), v_3 \equiv c - 2, v_4 \equiv \text{read}(v_2, v_3),$$

$$v_5 \equiv c - b + 1, v_6 \equiv f(v_4), v_7 \equiv f(v_5)$$

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$$v_5 \equiv c-b+1, v_6 \equiv f(v_4), v_7 \equiv f(v_5)$$



$$b + 2 = c, v_1 \equiv 3, v_3 \equiv c-2, v_5 \equiv c-b+1,$$

$$v_2 \equiv \text{write}(a, b, v_1), v_4 \equiv \text{read}(v_2, v_3),$$

$$v_6 \equiv f(v_4), v_7 \equiv f(v_5), v_6 \neq v_7$$

Stably Infinite Theories

A theory is stably infinite if every satisfiable QFF is satisfiable in an infinite model.

EUF and arithmetic are stably infinite.

Bit-vectors are not.

Important Result

The union of two consistent, disjoint, stably infinite theories is consistent.

Convexity

A theory T is **convex** iff

for all finite sets S of literals and

for all $a_1 = b_1 \vee \dots \vee a_n = b_n$

S implies $a_1 = b_1 \vee \dots \vee a_n = b_n$

iff

S implies $a_i = b_i$ for some $1 \leq i \leq n$

Convexity: Results

Every convex theory with non trivial models is stably infinite.

All **Horn equational** theories are convex.

formulas of the form $s_1 \neq r_1 \vee \dots \vee s_n \neq r_n \vee t = t'$

Linear rational arithmetic is convex.

Convexity: Negative Results

Linear integer arithmetic is not convex

$$1 \leq a \leq 2, b = 1, c = 2 \text{ implies } a = b \vee a = c$$

Nonlinear arithmetic

$$a^2 = 1, b = 1, c = -1 \text{ implies } a = b \vee a = c$$

Theory of bit-vectors

Theory of arrays

$$c_1 = \text{read}(\text{write}(a, i, c_2), j), c_3 = \text{read}(a, j) \\ \text{implies } c_1 = c_2 \vee c_1 = c_3$$

Combination of non-convex theories

EUF is convex ($O(n \log n)$)

IDL is non-convex ($O(nm)$)

EUF \cup IDL is NP-Complete

Reduce 3CNF to **EUF \cup IDL**

For each boolean variable p_i add $0 \leq a_i \leq 1$

For each clause $p_1 \vee \neg p_2 \vee p_3$ add

$$f(a_1, a_2, a_3) \neq f(0, 1, 0)$$

Combination of non-convex theories

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For each boolean variable p_i add $0 \leq a_i \leq 1$

For each clause $p_1 \vee \neg p_2 \vee p_3$ add

$$f(a_1, a_2, a_3) \neq f(0, 1, 0)$$



implies

$$a_1 \neq 0 \vee a_2 \neq 1 \vee a_3 \neq 0$$

Nelson-Oppen Combination

Let \mathcal{T}_1 and \mathcal{T}_2 be consistent, stably infinite theories over disjoint (countable) signatures. Assume satisfiability of conjunction of literals can be decided in $O(T_1(n))$ and $O(T_2(n))$ time respectively. Then,

1. The combined theory \mathcal{T} is consistent and stably infinite.
2. Satisfiability of quantifier free conjunction of literals in \mathcal{T} can be decided in $O(2^{n^2} \times (T_1(n) + T_2(n)))$.
3. If \mathcal{T}_1 and \mathcal{T}_2 are convex, then so is \mathcal{T} and satisfiability in \mathcal{T} is in $O(n^3 \times (T_1(n) + T_2(n)))$.

Nelson-Oppen Combination

The combination procedure:

Initial State: ϕ is a conjunction of literals over $\Sigma_1 \cup \Sigma_2$.

Purification: Preserving satisfiability transform ϕ into $\phi_1 \wedge \phi_2$,
such that, $\phi_i \in \Sigma_i$.

Interaction: Guess a partition of $\mathcal{V}(\phi_1) \cap \mathcal{V}(\phi_2)$ into disjoint
subsets. Express it as conjunction of literals ψ .

Example. The partition $\{x_1\}, \{x_2, x_3\}, \{x_4\}$ is represented
as $x_1 \neq x_2, x_1 \neq x_4, x_2 \neq x_4, x_2 = x_3$.

Component Procedures : Use individual procedures to decide
whether $\phi_i \wedge \psi$ is satisfiable.

Return: If both return yes, return yes. No, otherwise.

NO deterministic procedure (for convex theories)

Instead of **guessing**, we can **deduce** the equalities to be shared.

Purification: no changes.

Interaction: Deduce an equality $x = y$:

$$\mathcal{T}_1 \vdash (\phi_1 \Rightarrow x = y)$$

Update $\phi_2 := \phi_2 \wedge x = y$. And vice-versa. Repeat until no further changes.

Component Procedures : Use individual procedures to decide whether ϕ_i is satisfiable.

Remark: $\mathcal{T}_i \vdash (\phi_i \Rightarrow x = y)$ iff $\phi_i \wedge x \neq y$ is not satisfiable in \mathcal{T}_i .

NO deterministic procedure

Completeness

Assume the theories are convex.

- ▶ Suppose ϕ_i is satisfiable.
- ▶ Let E be the set of equalities $x_j = x_k$ ($j \neq k$) such that, $\mathcal{T}_i \not\vdash \phi_i \Rightarrow x_j = x_k$.
- ▶ By convexity, $\mathcal{T}_i \not\vdash \phi_i \Rightarrow \bigvee_E x_j = x_k$.
- ▶ $\phi_i \wedge \bigwedge_E x_j \neq x_k$ is satisfiable.
- ▶ The proof now is identical to the nondeterministic case.
- ▶ Sharing equalities is sufficient, because a theory \mathcal{T}_1 can assume that $x^B \neq y^B$ whenever $x = y$ is not implied by \mathcal{T}_2 and vice versa.

NO procedure: Example

$b + 2 = c, f(\text{read}(\text{write}(a, b, 3), c-2)) \neq f(c-b+1)$

Arithmetic

$b + 2 = c,$

$v_1 \equiv 3,$

$v_3 \equiv c-2,$

$v_5 \equiv c-b+1$

Arrays

$v_2 \equiv \text{write}(a, b, v_1),$

$v_4 \equiv \text{read}(v_2, v_3)$

EUUF

$v_6 \equiv f(v_4),$

$v_7 \equiv f(v_5),$

$v_6 \neq v_7$

NO procedure: Example

$$b + 2 = c, f(\text{read}(\text{write}(a, b, 3), c-2)) \neq f(c-b+1)$$

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$$v_6 \equiv f(v_4),$$

$$v_7 \equiv f(v_5),$$

$$v_6 \neq v_7$$

Substituting c

NO procedure: Example

$b + 2 = c, f(\text{read}(\text{write}(a, b, 3), c - 2)) \neq f(c - b + 1)$

Arithmetic

$b + 2 = c,$

$v_1 \equiv 3,$

$v_3 \equiv b,$

$v_5 \equiv 3$

Arrays

$v_2 \equiv \text{write}(a, b, v_1),$

$v_4 \equiv \text{read}(v_2, v_3),$

EUUF

$v_6 \equiv f(v_4),$

$v_7 \equiv f(v_5),$

$v_6 \neq v_7$

Propagating $v_3 = b$

NO procedure: Example

$$b + 2 = c, f(\text{read}(\text{write}(a, b, 3), c-2)) \neq f(c-b+1)$$

Arithmetic

$$b + 2 = c,$$

$$v_1 \equiv 3,$$

$$v_3 \equiv b,$$

$$v_5 \equiv 3$$

Arrays

$$v_2 \equiv \text{write}(a, b, v_1),$$

$$v_4 \equiv \text{read}(v_2, v_3),$$

$$v_3 = b$$

EUUF

$$v_6 \equiv f(v_4),$$

$$v_7 \equiv f(v_5),$$

$$v_6 \neq v_7,$$

$$v_3 = b$$

Deducing $v_4 = v_1$

NO procedure: Example

$b + 2 = c, f(\text{read}(\text{write}(a, b, 3), c - 2)) \neq f(c - b + 1)$

Arithmetic

$b + 2 = c,$

$v_1 \equiv 3,$

$v_3 \equiv b,$

$v_5 \equiv 3$

Arrays

$v_2 \equiv \text{write}(a, b, v_1),$

$v_4 \equiv \text{read}(v_2, v_3),$

$v_3 = b,$

$v_4 = v_1$

EUUF

$v_6 \equiv f(v_4),$

$v_7 \equiv f(v_5),$

$v_6 \neq v_7,$

$v_3 = b$

Propagating $v_4 = v_1$

NO procedure: Example

$b + 2 = c, f(\text{read}(\text{write}(a, b, 3), c - 2)) \neq f(c - b + 1)$

Arithmetic

$b + 2 = c,$

$v_1 \equiv 3,$

$v_3 \equiv b,$

$v_5 \equiv 3,$

$v_4 = v_1$

Arrays

$v_2 \equiv \text{write}(a, b, v_1),$

$v_4 \equiv \text{read}(v_2, v_3),$

$v_3 = b,$

$v_4 = v_1$

EUUF

$v_6 \equiv f(v_4),$

$v_7 \equiv f(v_5),$

$v_6 \neq v_7,$

$v_3 = b,$

$v_4 = v_1$

Propagating $v_5 = v_1$

NO procedure: Example

$b + 2 = c, f(\text{read}(\text{write}(a, b, 3), c - 2)) \neq f(c - b + 1)$

Arithmetic

$$b + 2 = c,$$

$$v_1 \equiv 3,$$

$$v_3 \equiv b,$$

$$v_5 \equiv 3,$$

$$v_4 = v_1$$

Arrays

$$v_2 \equiv \text{write}(a, b, v_1),$$

$$v_4 \equiv \text{read}(v_2, v_3),$$

$$v_3 = b,$$

$$v_4 = v_1$$

EUf

$$v_6 \equiv f(v_4),$$

$$v_7 \equiv f(v_5),$$

$$v_6 \neq v_7,$$

$$v_3 = b,$$

$$v_4 = v_1,$$

$$v_5 = v_1$$

Congruence: $v_6 = v_7$

NO procedure: Example

$$b + 2 = c, f(\text{read}(\text{write}(a, b, 3), c-2)) \neq f(c-b+1)$$

Arithmetic

$$b + 2 = c,$$

$$v_1 \equiv 3,$$

$$v_3 \equiv b,$$

$$v_5 \equiv 3,$$

$$v_4 = v_1$$

Unsatisfiable

Arrays

$$v_2 \equiv \text{write}(a, b, v_1),$$

$$v_4 \equiv \text{read}(v_2, v_3),$$

$$v_3 = b,$$

$$v_4 = v_1$$

EUUF

$$v_6 \equiv f(v_4),$$

$$v_7 \equiv f(v_5),$$

$$\mathbf{v_6 \neq v_7},$$

$$v_3 = b,$$

$$v_4 = v_1,$$

$$v_5 = v_1,$$

$$\mathbf{v_6 = v_7}$$

NO deterministic procedure

Deterministic procedure may **fail** for non-convex theories.

$$0 \leq a \leq 1, 0 \leq b \leq 1, 0 \leq c \leq 1,$$

$$f(a) \neq f(b),$$

$$f(a) \neq f(c),$$

$$f(b) \neq f(c)$$

Combining Procedures in Practice

Propagate all implied equalities.

- ▶ Deterministic Nelson-Oppen.
- ▶ Complete only for convex theories.
- ▶ It may be expensive for some theories.

Delayed Theory Combination.

- ▶ Nondeterministic Nelson-Oppen.
- ▶ Create set of interface equalities ($x = y$) between shared variables.
- ▶ Use SAT solver to guess the partition.
- ▶ Disadvantage: the number of additional equality literals is quadratic in the number of shared variables.

Combining Procedures in Practice

Common to these methods is that they are **pessimistic** about which equalities are propagated.

Model-based Theory Combination

- ▶ **Optimistic approach.**
- ▶ Use a candidate model M_i for one of the theories \mathcal{T}_i and propagate all equalities implied by the candidate model, hedging that other theories will agree.

if $M_i \models \mathcal{T}_i \cup \Gamma_i \cup \{u = v\}$ **then** propagate $u = v$.

- ▶ If not, use backtracking to fix the model.
- ▶ It is cheaper to enumerate equalities that are implied in a particular model than of all models.

Example

$$x = f(y - 1), f(x) \neq f(y), 0 \leq x \leq 1, 0 \leq y \leq 1$$

Purifying

Example

$$x = f(z), f(x) \neq f(y), 0 \leq x \leq 1, 0 \leq y \leq 1, z = y - 1$$

Example

\mathcal{T}_E			\mathcal{T}_A	
Literals	Eq. Classes	Model	Literals	Model
$x = f(z)$	$\{x, f(z)\}$	$E(x) = *1$	$0 \leq x \leq 1$	$A(x) = 0$
$f(x) \neq f(y)$	$\{y\}$	$E(y) = *2$	$0 \leq y \leq 1$	$A(y) = 0$
	$\{z\}$	$E(z) = *3$	$z = y - 1$	$A(z) = -1$
	$\{f(x)\}$	$E(f) = \{ *1 \mapsto *4,$		
	$\{f(y)\}$		$*2 \mapsto *5,$	
		$*3 \mapsto *1,$		
		$else \mapsto *6 \}$		

Assume $x = y$

Example

\mathcal{T}_E			\mathcal{T}_A	
Literals	Eq. Classes	Model	Literals	Model
$x = f(z)$	$\{x, y, f(z)\}$	$E(x) = *_1$	$0 \leq x \leq 1$	$A(x) = 0$
$f(x) \neq f(y)$	$\{z\}$	$E(y) = *_1$	$0 \leq y \leq 1$	$A(y) = 0$
$x = y$	$\{f(x), f(y)\}$	$E(z) = *_2$	$z = y - 1$	$A(z) = -1$
		$E(f) = \{*_1 \mapsto *_3,$	$x = y$	
		$*_2 \mapsto *_1,$		
		$\text{else} \mapsto *_4\}$		

Unsatisfiable

Example

\mathcal{T}_E			\mathcal{T}_A	
Literals	Eq. Classes	Model	Literals	Model
$x = f(z)$	$\{x, f(z)\}$	$E(x) = *1$	$0 \leq x \leq 1$	$A(x) = 0$
$f(x) \neq f(y)$	$\{y\}$	$E(y) = *2$	$0 \leq y \leq 1$	$A(y) = 0$
$x \neq y$	$\{z\}$	$E(z) = *3$	$z = y - 1$	$A(z) = -1$
	$\{f(x)\}$	$E(f) = \{ *1 \mapsto *4,$	$x \neq y$	
	$\{f(y)\}$	$*2 \mapsto *5,$		
		$*3 \mapsto *1,$		
		$else \mapsto *6 \}$		

Backtrack, and assert $x \neq y$.

\mathcal{T}_A model need to be fixed.

Example

\mathcal{T}_E			\mathcal{T}_A	
Literals	Eq. Classes	Model	Literals	Model
$x = f(z)$	$\{x, f(z)\}$	$E(x) = *_1$	$0 \leq x \leq 1$	$A(x) = 0$
$f(x) \neq f(y)$	$\{y\}$	$E(y) = *_2$	$0 \leq y \leq 1$	$A(y) = 1$
$x \neq y$	$\{z\}$	$E(z) = *_3$	$z = y - 1$	$A(z) = 0$
	$\{f(x)\}$	$E(f) = \{*_1 \mapsto *_4,$	$x \neq y$	
	$\{f(y)\}$	$*_2 \mapsto *_5,$		
		$*_3 \mapsto *_1,$		
		$else \mapsto *_6\}$		

Assume $x = z$

Example

\mathcal{T}_E			\mathcal{T}_A	
<i>Literals</i>	<i>Eq. Classes</i>	<i>Model</i>	<i>Literals</i>	<i>Model</i>
$x = f(z)$	$\{x, z,$	$E(x) = *_1$	$0 \leq x \leq 1$	$A(x) = 0$
$f(x) \neq f(y)$	$f(x), f(z)\}$	$E(y) = *_2$	$0 \leq y \leq 1$	$A(y) = 1$
$x \neq y$	$\{y\}$	$E(z) = *_1$	$z = y - 1$	$A(z) = 0$
$x = z$	$\{f(y)\}$	$E(f) = \{*_1 \mapsto *_1,$ $*_2 \mapsto *_3,$ $\text{else} \mapsto *_4\}$	$x \neq y$ $x = z$	

Satisfiable

Example

\mathcal{T}_E			\mathcal{T}_A	
<i>Literals</i>	<i>Eq. Classes</i>	<i>Model</i>	<i>Literals</i>	<i>Model</i>
$x = f(z)$	$\{x, z,$	$E(x) = *_1$	$0 \leq x \leq 1$	$A(x) = 0$
$f(x) \neq f(y)$	$f(x), f(z)\}$	$E(y) = *_2$	$0 \leq y \leq 1$	$A(y) = 1$
$x \neq y$	$\{y\}$	$E(z) = *_1$	$z = y - 1$	$A(z) = 0$
$x = z$	$\{f(y)\}$	$E(f) = \{*_1 \mapsto *_1,$	$x \neq y$	
		$*_2 \mapsto *_3,$	$x = z$	
		$else \mapsto *_4\}$		

Let h be the bijection between $|E|$ and $|A|$.

$$h = \{*_1 \mapsto 0, *_2 \mapsto 1, *_3 \mapsto -1, *_4 \mapsto 2, \dots\}$$

Example

\mathcal{T}_E		\mathcal{T}_A	
<i>Literals</i>	<i>Model</i>	<i>Literals</i>	<i>Model</i>
$x = f(z)$	$E(x) = *_1$	$0 \leq x \leq 1$	$A(x) = 0$
$f(x) \neq f(y)$	$E(y) = *_2$	$0 \leq y \leq 1$	$A(y) = 1$
$x \neq y$	$E(z) = *_1$	$z = y - 1$	$A(z) = 0$
$x = z$	$E(f) = \{*_1 \mapsto *_1,$ $*_2 \mapsto *_3,$ $\text{else} \mapsto *_4\}$	$x \neq y$	$A(f) = \{0 \mapsto 0$ $1 \mapsto -1$ $\text{else} \mapsto 2\}$

Extending A using h .

$$h = \{*_1 \mapsto 0, *_2 \mapsto 1, *_3 \mapsto -1, *_4 \mapsto 2, \dots\}$$