SMT and Z3

Nikolaj Bjørner Microsoft Research ReRISE Winter School, Linz, Austria February 5, 2014

Plan

Mon An invitation to SMT with Z3

Tue Equalities and Theory Combination

Wed Theories: Arithmetic, Arrays, Data types

Thu Quantifiers and Theories

Fri Programming Z3: Interfacing and Solving

Quiz

Show: A *difference logic graph* without negative cycles has a model. Give a procedure for extracting a model.

True or false: A formula over difference logic has a model over reals **iff** it has a model over integers?

Give an *efficient* algorithm to extract models for UTVPI over integers.

Encode lambda Calculus into *map*, *K*, *read* (without *I*).

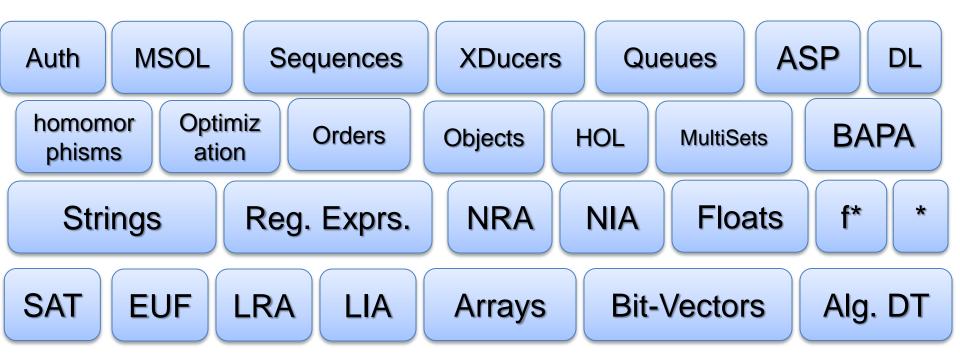
Plan

- Arithmetic
- Arrays and friends
- Data types [Introduction]

What Theories?

Overall aim:

Rich Theories (and logics) with **Efficient** Decision Procedures



Be afraid!

🥔 http://icwww.epfl.ch/~piskac/softwa 🔎 ▾ 🗟 🖒 🗙 🛛 🧟 MUNCH - Automated Reas... 🗴

The MUNCH Tool: automated reasoner for collections

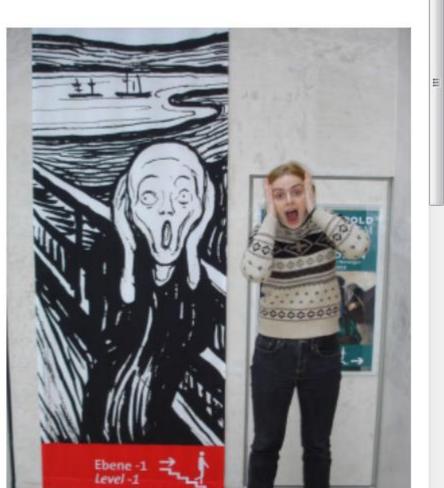
This is the web page for the MUNCH tool. Currently the following is available for download:

- paper describing the tool
- implementation
- some examples and their output

Examples are written in the separate file (examples.txt). The tool then parses this input into a language corresponding to the grammar described in the paper and in the file ASTMultisets.scala. MUNCH invokes z3 .

Playing with the MUNCH tool

The MUNCH tool is written in Scala and for testing MUNCH you need to have Scala installed. To run MUNCH, on your machine, first download the 4 4 14 14



Linear Real Arithmetic

- Many approaches
 - Graph-based for difference logic: $a b \le 3$
 - Fourier-Motzkin elimination:

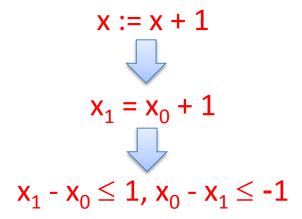
$$t_1 \leq ax, \ bx \leq t_2 \ \Rightarrow \ bt_1 \leq at_2$$

- Standard Simplex
- General Form Simplex
- GDPLL [McMillan],
 Unate Resolution [Coton],
 Conflict Resolution [Korovin et.al.]

Difference Logic: $a - b \le 5$

Very useful in practice!

Most arithmetical constraints in software verification/analysis are in this fragment.



Job shop scheduling

$d_{i,j}$	Machine 1	Machine 2
Job 1	2	1
Job 2	3	1
Job $\frac{1}{2}$	2	3
max = 8	_	

Solution

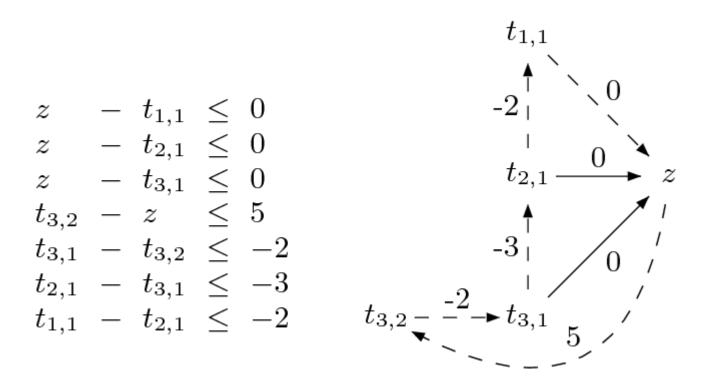
$$t_{1,1} = 5, t_{1,2} = 7, t_{2,1} = 2, t_{2,2} = 6, t_{3,1} = 0, t_{3,2} = 3$$

Encoding

$$\begin{array}{l} (t_{1,1} \geq 0) \land (t_{1,2} \geq t_{1,1} + 2) \land (t_{1,2} + 1 \leq 8) \land \\ (t_{2,1} \geq 0) \land (t_{2,2} \geq t_{2,1} + 3) \land (t_{2,2} + 1 \leq 8) \land \\ (t_{3,1} \geq 0) \land (t_{3,2} \geq t_{3,1} + 2) \land (t_{3,2} + 3 \leq 8) \land \\ ((t_{1,1} \geq t_{2,1} + 3) \lor (t_{2,1} \geq t_{1,1} + 2)) \land \\ ((t_{1,1} \geq t_{3,1} + 2) \lor (t_{3,1} \geq t_{1,1} + 2)) \land \\ ((t_{2,1} \geq t_{3,1} + 2) \lor (t_{3,1} \geq t_{2,1} + 3)) \land \\ ((t_{1,2} \geq t_{2,2} + 1) \lor (t_{2,2} \geq t_{1,2} + 1)) \land \\ ((t_{1,2} \geq t_{3,2} + 3) \lor (t_{3,2} \geq t_{1,2} + 1)) \land \\ ((t_{2,2} \geq t_{3,2} + 3) \lor (t_{3,2} \geq t_{2,2} + 1)) \end{array}$$

Difference Logic

Chasing negative cycles! Algorithms based on Bellman-Ford (O(mn)).



Unit Two Variables Per Inequality

$x + y \le 5 \land -x + y \le -4 \land y + y \ge 1$

Unit Two Variables Per Inequality

$x + y \le 5 \land -x + y \le -4 \land 2y \ge 1$

 $2y \le 1 \land 2y \ge 1$

Unit Two Variables Per Inequality

 $x + y \le 5 \land -x + y \le -4 \land 2y \ge 1$

 $2y \le 1 \land 2y \ge 1$

 $y \le 0 \land y \ge 1$

Unit Two Variables Per Inequality: UTVPI

Reduce to Difference Logic:

- For every variable x introduce fresh variables
 x⁺, x⁻
- Meaning: $2x \coloneqq x^+ x^-$
- Rewrite constraints as follows:

•
$$x - y \le k \Rightarrow \begin{cases} x^+ - y^+ \le k \\ y^- - x^- \le k \end{cases}$$

• $x - y \le k$ $\Rightarrow \begin{cases} x^+ - y^+ \le k \\ y^- - x^- \le k \end{cases}$

•
$$x \leq k \Rightarrow x^+ - x^- \leq 2k$$

•
$$x + y \le k \Rightarrow \begin{cases} x^+ - y^- \le k \\ y^+ - x^- \le k \end{cases}$$

• $x + y \le k \Rightarrow$ chalkboard

$x + y \le 5 \land -x + y \le -4 \land 2y \ge 1$

 $x^+ - y^- \le 5 \land y^+ - x^- \le 5 \land$ $-x^{+} + y^{+} \le -4 \land x^{-} - y^{-} \le -4 \land$ $y^- - y^+ \le 1$

• Solve for x^+ and x^-

•
$$M(x) := (M(x^+) - M(x^-))/2$$

• Nothing can go wrong... $2y \le 1 \land 2y \ge 1$

- $M(x) := (M(x^+) M(x^-))/2$
- Nothing can go wrong... as if
- What if:
 - -x is an integer
 - $-M(x^+)$ is odd and
 - $-M(x^{-})$ is **even**
- Thm: Parity can be fixed **iff** there is no tight loop forcing the wrong parity

General Form

General Form: Ax = 0 and $l_j \le x_j \le u_j$ Example:

$$x \ge 0, (x + y \le 2 \lor x + 2y \ge 6), (x + y = 2 \lor x + 2y > 4)$$

$$s_1 \equiv x + y, s_2 \equiv x + 2y,$$

$$x \ge 0, (s_1 \le 2 \lor s_2 \ge 6), (s_1 = 2 \lor s_2 > 4)$$

Only bounds (e.g., $s_1 \leq 2$) are asserted during the search.

Unconstrained variables can be eliminated before the beginning of the search.

 $s_1 \equiv x + y$, $s_2 \equiv x + 2y$

$$s_1 \equiv x + y, \quad s_2 \equiv x + 2y$$

 $s_1 = x + y,$
 $s_1 = x + y,$
 $s_2 = x + 2y$

$$s_{1} \equiv x + y, \quad s_{2} \equiv x + 2y$$

$$s_{1} = x + y,$$

$$s_{2} = x + 2y$$

$$s_{1} - x - y = 0$$

$$s_{1} - x - y = 0$$

$$s_{2} - x - 2y = 0$$

$$s_{1} \equiv x + y, \quad s_{2} \equiv x + 2y$$

$$s_{1} = x + y,$$

$$s_{2} = x + 2y$$

$$s_{2} = x + 2y$$

$$s_{1} - x - y = 0 \quad s_{1}, s_{2} \text{ are basic (dependent)}$$

$$s_{2} - x - 2y = 0 \quad x, y \text{ are non-basic}$$

A way to swap a basic with a non-basic variable! It is just equational reasoning. Key invariant: a basic variable occurs in only one equation.

Example: swap s₁ and y

$$s_1 - x - y = 0$$

 $s_2 - x - 2y = 0$

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$$s_1 - x - y = 0$$

 $s_2 - x - 2y = 0$
 $-s_1 + x + y = 0$
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It is just substituting equals.

Definition: An assignment (model) is a mapping from variables to values

A way to swap a basic with a non-basic variable!

It is just equational reasoning.

Key invariant: a basic variable occurs in only one equation. Example: swap s₁ and y

> $S_1 - x - y = 0$ $s_2 - x - 2y = 0$ $-s_1 + x + y = 0$ $s_{2} - x - 2y = 0$ $-s_1 + x + y = 0$ $s_2 - 2s_1 + x = 0$

It is just substituting equals by equals.

Key Property:

If an assignment satisfies the equations before a pivoting step, then it will also satisfy them after!

Definition: An assignment (model) is a mapping from variables to values

A way to swap a basic with a non-basic variable!

It is just equational reasoning.

Key invariant: a basic variable occurs in only one equation. Example: swap s₂ and y

Example: M(x) = 1 M(y) = 1 $M(s_1) = 2$ $M(s_2) = 3$

$\mathbf{s_1} - \mathbf{x} - \mathbf{y} = 0$	
$s_2 - x - 2y = 0$	
$-s_1 + x + y = 0$)
$s_2 - x - 2y = 0$	K
	li
	e
$-s_1 + x + y = 0$	S S
$s_2 - 2s_1 + x = 0$) <mark>+</mark>

It is just substituting equals by equals.

Key Property:

If an assignment satisfies the equations before a pivoting step, then it will also satisfy them after!

Equations + Bounds + Assignment

An assignment (model) is a mapping from variables to values.

We maintain an assignment that satisfies all equations and bounds.

The assignment of non dependent variables implies the assignment of dependent variables.

Equations + Bounds can be used to derive new bounds.

Example: $x = y - z, y \le 2, z \ge 3 \rightsquigarrow x \le -1$.

The new bound may be inconsistent with the already known bounds.

Example: $x \leq -1, x \geq 0$.

If the assignment of a non-basic variable does not satisfy a bound, then fix it and propagate the change to all dependent variables.

a = c - d	a = c - d
<mark>b</mark> = c + d	<mark>b</mark> = c + d
M(a) = 0	M(a) = 1
M(b) = 0	M(b) = 1
M(c) = 0	M(c) = 1
M(d) = 0	M(d) = 0
$1 \le c$	$1 \le c$

If the assignment of a non-basic variable does not satisfy a bound, then fix it and propagate the change to all dependent variables. Of course, we may introduce new "problems".

a = c - d	a = c - d
<mark>b</mark> = c + d	<mark>b</mark> = c + d
M(a) = 0	M(a) = 1
M(b) = 0	M(b) = 1
M(c) = 0	M(c) = 1
M(d) = 0	M(d) = 0
$1 \le c$	$1 \le c$
$a \le 0$	a ≤ 0

If the assignment of a basic variable does not satisfy a bound, then pivot it, fix it, and propagate the change to its new dependent variables.

a = c - d	<mark>c</mark> = a + d	<mark>c</mark> = a + d
<mark>b</mark> = c + d	<mark>b</mark> = a + 2d	<mark>b</mark> = a + 2d
M(a) = 0	M(a) = 0	M(a) = 1
M(b) = 0	M(b) = 0 🔷	M(b) = 1
M(c) = 0	M(c) = 0	M(c) = 1
M(d) = 0	M(d) = 0	M(d) = 0
$1 \le a$	$1 \le a$	$1 \le a$

Sometimes, a model cannot be repaired. It is pointless to

pivot.

The value of M(a) is too big. We can reduce it by: $a \le 0, 1 \le b, c \le 0$ M(a) = 1 M(b) = 1 M(c) = 0

Extracting proof from failed repair attempts is easy.

$$\begin{split} s_1 &\equiv a + d, \ s_2 &\equiv c + d \\ a &= s_1 - s_2 + c \\ a &\leq 0, \ 1 \leq s_1, \ s_2 \leq 0, \ 0 \leq c \\ M(a) &= 1 \\ M(s_1) &= 1 \\ M(s_2) &= 0 \\ M(c) &= 0 \end{split}$$

"Repairing Models"

Extracting proof from failed repair attempts is easy.

$$\begin{split} s_1 &\equiv a + d, \ s_2 &\equiv c + d \\ a &= s_1 - s_2 + c \\ a &\leq 0, \ 1 \leq s_1, \ s_2 \leq 0, \ 0 \leq c \\ M(a) &= 1 \\ M(s_1) &= 1 \\ M(s_2) &= 0 \\ M(c) &= 0 \end{split}$$

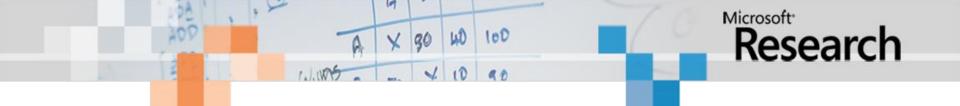
{ a \leq 0, 1 \leq s_1, s_2 \leq 0, 0 \leq c } is inconsistent

"Repairing Models"

Extracting proof from failed repair attempts is easy.

$$\begin{split} s_1 &\equiv a + d, \ s_2 &\equiv c + d \\ a &= s_1 - s_2 + c \\ a &\leq 0, \ 1 \leq s_1, \ s_2 \leq 0, \ 0 \leq c \\ M(a) &= 1 \\ M(s_1) &= 1 \\ M(s_2) &= 0 \\ M(c) &= 0 \\ \{ a \leq 0, \ 1 \leq s_1, \ s_2 \leq 0, \ 0 \leq c \ \} \ \text{is inconsistent} \end{split}$$

{ $a \le 0, 1 \le a + d, c + d \le 0, 0 \le c$ } is inconsistent



Arrays and Combinatory Array Logic

What are arrays?

Applicative stores:
 write(a,i,v)[i] = v

$$i \neq j \Rightarrow write(a, i, v)[j] = a[j]$$

• Or, special combinator:

write(
$$a, i, v$$
) = λj .ite($i = j, v, a[j]$)

What are arrays?

• Special combinator:

write(
$$a, i, v$$
) = λj .ite($i = j, v, a[j]$)

 Existential fragment is decidable by reduction to congruence closure using finite set of instances.

Models for arrays are finite maps with default values.

What else are arrays?

• Special combinators:

$$write(a, i, v) = \lambda j.ite(i = j, v, a[j])$$

$$K(v) = \lambda j.v$$

$$map_{f}(a,b) = \lambda j.f(a[j],b[j])$$

• **Result**: Existential fragment is decidable and in NP by reduction to congruence closure using finite set of instances.

What else are arrays++?

• Extra special combinators:

$$write(a, i, v) = \lambda j.ite(i = j, v, a[j])$$

 $K(v) = \lambda j.v$

 $map_f(a,b) = \lambda j.f(a[j],b[j])$

 $I = \lambda j.j$

• Easy to encode lambda calculus

What else are arrays++?

• Encoding lambda terms into CAL+:

$$\begin{split} [[\lambda x.M]] &= tr(x, [[M]]) \\ &[[x]] &= x \\ [[(MN)]] &= map_{read}([[M]], [[N]]) \\ \end{split} \\ tr(x, f(M, N)) &= map_{f}(tr(x, M), tr(x, N)) \\ \end{split}$$

• Where

$$M, N ::= x \mid \lambda x.M \mid (MN)$$

Exercise: encode lambda calculus without /

NB. Our procedure is going to assume that function passed to map is not from read.

Example translation

$$\begin{split} & [[\lambda x.((\lambda y.(yx))x)]] \\ &= tr(x,[[((\lambda y.(yx))x)]]) \\ &= tr(x,map_{read}([[\lambda y.(yx)]],[[x]])) \\ &= tr(x,map_{read}([[\lambda y.(yx)]],x)) \\ &= tr(x,map_{read}(tr(y,[[(yx)]]),x)) \\ &= tr(x,map_{read}(tr(y,map_{read}(y,x)),x)) \\ &= tr(x,map_{read}(tr(y,map_{read}(y,x)),x)) \\ &= tr(x,map_{read}(map_{map_{read}}(tr(y,y),tr(y,x))),x)) \end{split}$$

$$= tr(x, map_{read} (map_{map_{read}} (I, K(x)), x))$$

$$= map_{map_{read}} (tr(x, map_{map_{read}} (I, K(x))), tr(x, x)))$$

$$= map_{map_{read}} (map_{map_{map_{read}}} (tr(x, I), tr(x, K(x)))), I)$$

$$= map_{map_{read}} (map_{map_{map_{read}}} (K(I), tr(x, K(x)))), I)$$

$$= map_{map_{read}} (map_{map_{map_{read}}} (K(I), map_{K} (tr(x, x))), I))$$

... But there are arrays#:

• Restricted theory using *I*.

 $K(v) = \lambda j.v$

 $map_{ite}(a,b,c) = \lambda j.ite(a[j],b[j],c[j])$

 $map_{=}(a,b) = \lambda j.(a[j] = b[j])$

 $I = \lambda j.j$

- Then: $write(a, i, v) = map_{ite}(map_{=}(K(i), I), K(v), a)$
- Theory of arrays# is decidable.

Last combinator for the road...

• Can I access a *default* array value?

 $\delta(a) - default$

 $\delta(K(v)) = v$ $\delta(map_f(a,b)) = f(\delta(a), \delta(b))$

 $\delta(write(a,i,v)) = \delta(a)$

Only sound for infinite domains

Let's use CAL:

• Simple set and bag operations:

Ø	K(false)	$\varnothing_{\scriptscriptstyle Bag}$	K(0)
$\{a\}$	$write(\emptyset, a, true)$	$\{a\}$	$write(\emptyset, a, 1)$
$a \in A$	A[a]	mult(a, A)	A[a]
$A \cup B$	$map_{\vee}(A,B)$	$A \oplus B$	$map_+(A,B)$
$A \cap B$	$map_{\wedge}(A,B)$	$A\Pi B$	$map_{\min}(A,B)$
finite(A)	$(\delta(A) = false)$	$finite_{Bag}(A)$	$(\delta(A) = 0)$

• But not cardinality /A/, power-set 2^A, ...

CAL: Arrays as Combinators

 McCarthy Arrays: store/select

select(store(a, i, v), i) = v $i \neq j \Rightarrow select(store(a, i, v), j) = select(a, j)$

 Array combinators: $store(a, i, v) := \lambda j. if i = j then v else select(a, j)$ $const(v) := \lambda i. v$ $map_f(a, b) := \lambda i. f(select(a, i), select(b, i))$

 Takeaway: A common procedure for Array Combinators

A reduction-based approach

 $Sat(T_{Array} \wedge \varphi)$?

Use saturation rules to reduce arrays to the theory of un-interpreted functions

 $Sat(T_{Equality} \land Closure_{Array}(\varphi) \land \varphi)?$

Extract models for arrays as finite graphs

sat partitions: *0 -> true *1 -> false *2 {a2} -> {*4 -> *5; *7 -> *12; else -> *13} *3 {a1} -> {*7 -> *12; else -> *13} *4 {i1} -> 1 *5 {u1} -> 2 *6 {a3} -> {*4 -> *5; *7 -> *8; else -> *13} *7 {i2 j} -> 3 *8 {u2} -> 7 *9 {a4} -> {*4 -> *5; *7 -> *8; *10 -> *11; else -> *13} *10 {i3} -> 4

Deciding store

For every sub-term store(a, i, v), every index j in φ , add equation to φ :

select(store(a, i, v), j) = if i = j then v else select(a, j)

EUF model of $\phi \Rightarrow$ Array Model:

For each array a define $M_{array}(a) := \{ M(i) \rightarrow M(select(a, i)), else \rightarrow \bullet_{Ma} \}$ where select(a,i) occurs in φ .

Deciding store

For each array a in φ define $M_{array}(a) := \{ M(i) \rightarrow M(select(a, i)), else \rightarrow \bullet_{Ma} \}$

Does M satisfy axioms for *store*?

 $M(store(a, i, v)) = \lambda j$. *if* M(i) = j *then* M(v) *else* M(select(a, j))

Recall, we added

select(store(a, i, v), j) = if i = j then v else select(a, j)

Thus, M(select(store(a, i, v), j))= M(if i = j then v else select(a, j))= if M(i) = M(j) then M(v) else M(select(a, j))

Extesionality

$$\forall a, b \left(\left(\forall i \, . \, select(a, i) = select(b, i) \right) \Rightarrow a = b \right)$$

Not automatically satisfied by basic decision procedure.

Skolemized: $\forall a, b \ ((select(a, \delta(a, b)) = select(b, \delta(a, b)))) \Rightarrow a = b)$ Add instance for every pair *a*, *b*.

More Efficiently Deciding store

- $a^{-}b a$ and b are equal in current context
- $a \equiv t a$ is a name for the term t

$$\begin{split} \mathsf{idx} & \frac{a \equiv store(b, i, v)}{a[i] \simeq v} \\ \Downarrow & \frac{a \equiv store(b, i, v), \quad w \equiv a'[j], \quad a \sim a'}{i \simeq j \lor a[j] \simeq b[j]} \\ \Uparrow & \frac{a \equiv store(b, i, v), \quad w \equiv b'[j], \quad b \sim b'}{i \simeq j \lor a[j] \simeq b[j]} \\ & \texttt{ext} & \frac{a: (\sigma \Rightarrow \tau), \quad b: (\sigma \Rightarrow \tau)}{a \simeq b \lor a[k_{a,b}] \not\simeq b[k_{a,b}]} \end{split}$$

What makes it more *Efficient*?

 Axioms for *store* are only added by the model induced by EUF

Bottlenecks

$$\mathsf{ext} \frac{a:(\sigma \Rightarrow \tau), \quad b:(\sigma \Rightarrow \tau)}{a \simeq b \lor a[k_{a,b}] \not\simeq b[k_{a,b}]}$$

 Extensionality axiom is instantiated on every pair of array variables.

$$\land a \equiv store(b, i, v), \quad w \equiv b'[j], \quad b \sim b' \\ i \simeq j \lor a[j] \simeq b[j]$$

 Upwards propagation distributes index over all modifications of same array.



$$\mathsf{ext} \frac{a:(\sigma \Rightarrow \tau), \quad b:(\sigma \Rightarrow \tau)}{a \simeq b \lor a[k_{a,b}] \not\simeq b[k_{a,b}]}$$

Bottleneck: Extensionality axiom is instantiated on every pair of array variables.

$$\operatorname{ext}_{\not\simeq} \frac{p \equiv a \simeq b, \quad \Gamma(p) = \operatorname{false}}{a \simeq b \lor a[k_{a,b}] \not\simeq b[k_{a,b}]}$$
$$\operatorname{ext}_r \frac{a : (\sigma \Rightarrow \tau), \quad b : (\sigma \Rightarrow \tau), \quad \{a,b\} \subseteq \operatorname{foreign}}{a \simeq b \lor a[k_{a,b}] \not\simeq b[k_{a,b}]}$$

Optimization: Restrict to variables asserted different, or shared.



$$\uparrow \frac{a \equiv \textit{store}(b, i, v), \quad w \equiv b'[j], \quad b \sim b'}{i \simeq j \lor a[j] \simeq b[j]}$$

$$\label{eq:alpha} \Uparrow r \; \frac{a \equiv store(b,i,v), \quad w \equiv b'[j], \quad b \sim b', \quad b \in \text{non-linear}}{i \simeq j \lor a[j] \simeq b[j]}$$

- Bottleneck: Upwards propagation distributes index over all modifications of same array.
- Optimization: Only use

 ↑ for updates where
 ancestor has multiple
 children. Formulas from
 programs are well behaved.

Saturating K, map, δ

$$\begin{split} \mathsf{K} \Downarrow & \frac{a \equiv K(v), \quad w \equiv a'[j], \quad a \sim a'}{a[j] \simeq v} \\ \mathsf{map} \Downarrow & \frac{a \equiv map_f(b_1, \dots, b_n), \quad w \equiv a'[j], \quad a \sim a'}{a[j] \simeq f(b_1[j], \dots, b_n[j])} \\ & a \equiv map_f(b_1, \dots, b_n), \quad w \equiv b'_k[j], \\ & \mathsf{map} \Uparrow & \frac{b_k \sim b'_k, \text{ for some } k \in \{1, \dots, n\}}{a[j] \simeq f(b_1[j], \dots, b_n[j])} \\ & \epsilon_{\not\simeq} & \frac{v \equiv a[i], \quad i:\sigma, \quad i \text{ is not } \epsilon_{\sigma}}{\epsilon_{\sigma} \not\simeq i} \quad \epsilon \delta & \frac{a:(\sigma \Rightarrow \tau)}{a[\epsilon_{\sigma}] \simeq \delta_a} \end{split}$$

Algebraic Data types

Scalars, Tuples and Composites

Fruit = Apple | Orange | Banana

Person = { name : String, age : Int, sex : M | F }

IntOption = Some of { ofSome : Int } | None

Recursive and Mutual Recursive types

List = Nil | Cons of { head : Int, tail : List }

Ping = DropP | WinP | Pi of { pong : Pong }
Pong = WinP | DropP | Po of { ping : Pong }

ADTs: Algebraic Data-types

- Constructors are injective:
 - head(cons(x,xs)) = x
 - tail(cons(x,xs)) = xs
- Terms are well-founded:
 - $-xs \neq cons(x, xs)$
 - $-xs \neq cons(x, cons(y, xs))$
 - $-xs \neq cons(x, cons(y, cons(z, xs)))$
 - $-xs \neq cons(x, cons(y, cons(z, cons(u, xs))))$

ADTs

- Outline of a decision Procedure:
 - Force injectivity:
 - For cons(t1,t2) add lemmas:
 - head(cons(t1,t2)) = t1
 - tail(cons(t1,t2)) = t2
 - Build pre-model for constants of data-type sort.
 - x = Nil y = Nil z = Nil
 - Perform occurs check in each equivalence class.
 - Q: can there be two constructors in an equivalence class?